



04 DEC.2019

ASPARI SYMPOSIUM

Program

- 08:30-09:00** Inloop met koffie en thee, *Seirgei Miller*, Opening en Welkom (UT)
- 09:00-09:15** *Niels Hop*, WITOS Paving - ervaringen met implimentatie (UT/TWW)
- 09:15-09:30** *Sam Rutten*, Aziëhavenweg - PQi in 2008 uitgevoerd en nu? (UT/BAM)
- 09:30-09:45** *Chris vd Pol*, Asfalt recyclen in één werkgang (UT/Dura Vermeer)
- 09:45-10:00** *Wido de Witte*, Evalueren van temperatuur drempels voor verdichting (UT/Boskalis)
- 10:00-10:15** *Peter Baars*, Valideren van asfalt afkoelingsvoorspelling (UT/Roelofs)
- 10:15-10:45** Koffie en Thee
- 10:45-11:00** *Farid Vahdatikhaki & Sajad Mowlaei*, Developing an asphalt construction simulator (UT)
- 11:00-11:15** *Denis Makarov*, Automation of Asphalt Construction Process (UT)
- 11:15-11:30** *Michael Primavera*, A comparative Life Cycle Assessment of Traditional & Cement Treated Recycled Base Layers (UT)
- 11:30-11:45** *Monik Pena Acosta*, Reflectivity, roads and urban climates (UT)
- 11:45-12:45** Lunch
- 12:45-13:10** *Babs Ernst*, Asfalt onderwijsmaterialen voor de HBO sector - stand van zaken (UT)
- 13:10-13:35** *Denis Makarov & Afshin Jamshidi*, Modernizing the PQi method (UT)
- 13:35-14:00** *Janine Profijt*, Het promoten van MBO onderwijs civiele techniek (UT)
- 14:00-14:30** *Seirgei Miller*, Overzicht ASPARI in Nederland en het buitenland (UT)
- 14:30-15:00** Koffie en Thee met hapjes

in Program

ASPARI BSc projects

VR & simulators in
asphalt construction

Automation!?

New educational
methods

ASPARI

Ceintuurbaan 2
3847 LG Harderwijk,
Netherlands

www.aspari.nl

04 dec. 09:00 – 15:00

WITOS Paving Ervaringen met implementatie



TWW

TWENTSE WEG- EN WATERBOUW BV



ASPARi

Paving the way forward

Inhoud

- Inleiding bedrijf & Witos
- Hoe is het onderzoek opgezet
- Ervaringen met Witos
- Hoe gaan we verder?

Twentse Weg- en Waterbouw

- Middelgrote wegenbouwer
- Onderdeel van Reinteninfra
- Vier eigen asfaltploegen
- Eigen asfaltcentrale in Hengelo

Wat is Witos Paving?



WITOS Paving Control
The planning and control module



WITOS Paving Materials
The mixing plant module



WITOS Paving Transport
The transport module



WITOS Paving JobSite
The job site module



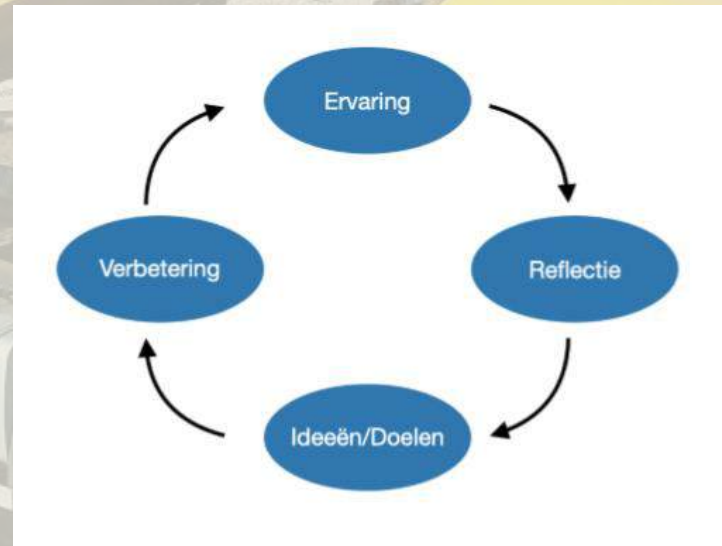
WITOS Paving Analysis
The analysis and documentation module



TWW
TWENTSE WEG- EN WATERBOUW BV

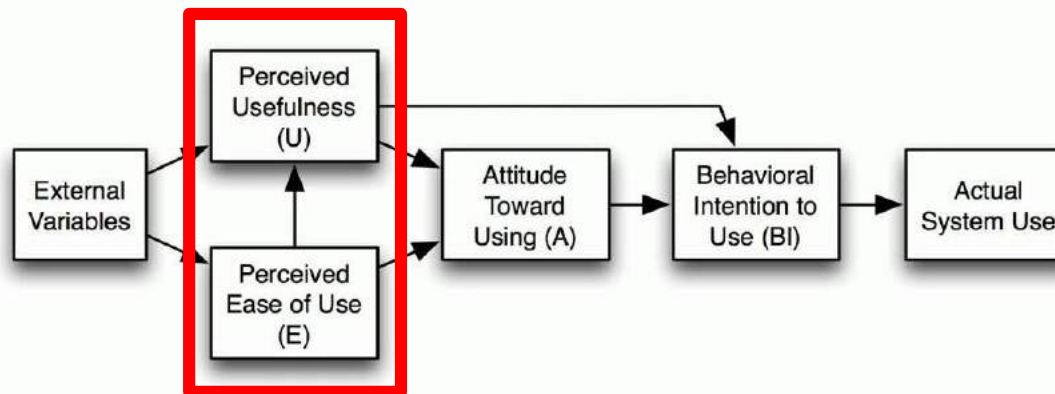
Hoe krijg je nieuwe technologie binnen een asfaltploeg geaccepteerd?

- Reflectieve leermethode
- Gedragsverandering van de gebruiker staat centraal



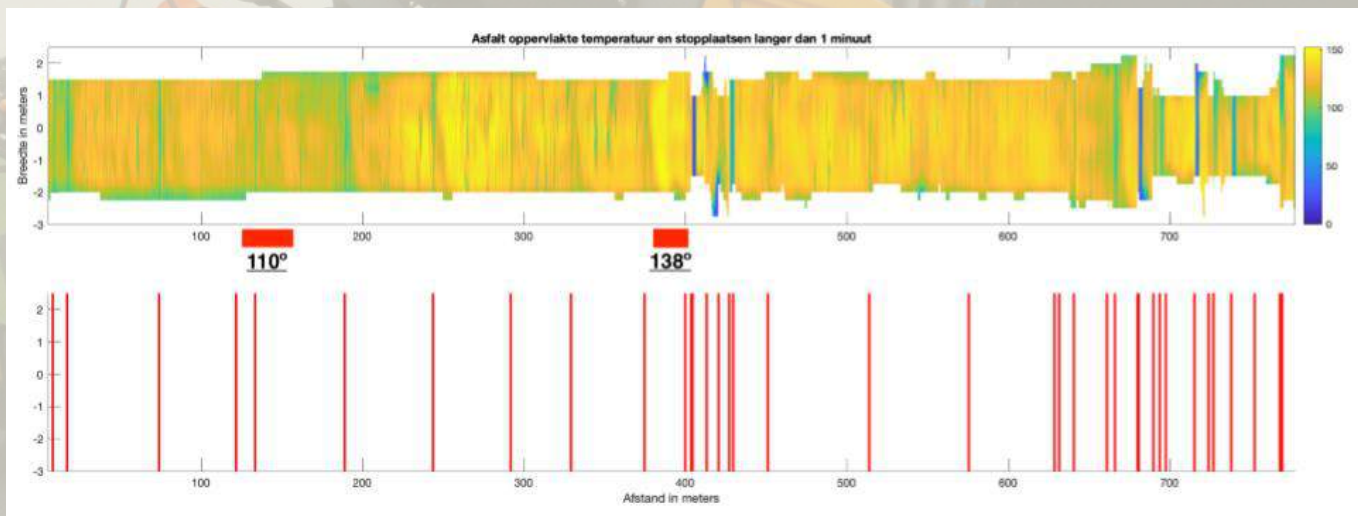
Hoe krijg je nieuwe technologie binnen een asfaltploeg geaccepteerd?

- Wat beïnvloed de acceptatie?



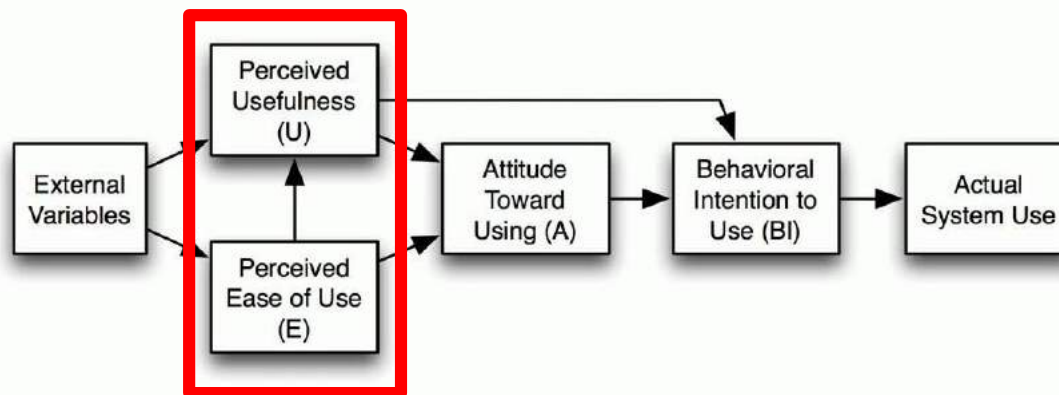
Het nut van Witos

- Het nut van de data wordt gezien door de asfaltploeg
- Door sensoren wordt het proces expliciet gemaakt



Invloed van gebruiksgemak

- Gebruiksgemak heeft grote invloed op het waargenomen nut



Gebruiksgemak van Witos

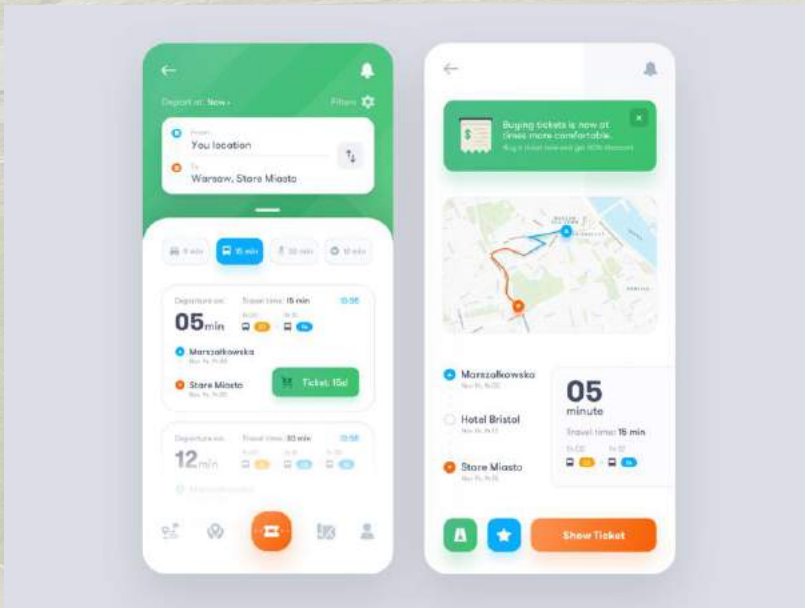
The screenshot displays the Witos software interface, which is used for project management and data collection. The main window is titled "Create Project: Project Definition" and features a menu bar with options like Project, Edit, Goto, WBS element, Details, Extras, System, and Help. Below the menu bar, there are several tabs: Basic data, Control, Administration, and LongText. The "Basic data" tab is active, showing fields for Project Def., Status (System Status: CRTD, User status), and Responsibilities (Person Respons., Applicant no.).

On the left side, there is a "wGetGUI v1.20" window with various settings for file downloading, including Hosts, Retrieval Options, and Behaviour of wget. Below this is a "My WinTitleBar" window with a toolbar and a table of data.

On the right side, there is a "Display View 'Item': Details" window showing a dialog structure and various fields for item details, including Target SalesDocTyp, From SalesDoc Type, ItemCat Proposal, Item Category, and Copying requirements.

ID	No.	Date	Curr.	Plane Type	Capacity	Occupied	Booking total
AO	2	22.03.1999	ATS	146-300	128	11	106.335,28
AO	2	11.07.1998	ATS	146-300	128	56	158.085,13
AO	1	20.08.2001	ATS	146-200	112	1	9.049,60
AO	1	09.12.2000	ATS	146-200	112	77	514.629,44
AO	1	21.10.1996	ATS	146-200	112	9	38.707,20
AA	17	21.10.1996	ATS	146-200	112	9	38.707,20
AA	17	09.12.2000	ATS	146-200	112	77	514.629,44
AA	17	20.08.2001	ATS	146-200	112	1	9.049,60
AA	26	11.07.1998	ATS	146-300	128	56	158.085,13
AA	26	22.03.1999	ATS	146-300	128	11	106.335,28

Gebruiksgemak van software in de huidige maatschappij



Stelling

De focus van asfaltonderzoek moet verschuiven.
De focus ligt nu vooral op de technologie die gebruikt kan worden, maar de focus moet veel meer liggen op de menselijke interactie met de technologie.

Effect of Asphalt Compaction and Temperature During Paving on Asphalt Lifespan

By Sam Rutten



Research Question:

What relationship is there between asphalt processing, particularly compaction and temperature homogeneity during paving, and the asphalt's ultimate lifespan?

Literature study

Expert Interviews

Empirical study

- 2 roads: A35 and Aziëhavenweg

Methods

Literature Study Findings

- Temperature differentials of 20 °C within the asphalt mat have a high likelihood of causing segregation
- 1% more voids could result in up to 10% decreased pavement life
- Raveling is largely influenced by compaction
- Load associated cracking is highly influenced by compaction
- Non-load associated cracking is influenced by temperature (cooling of asphalt)

Historical data

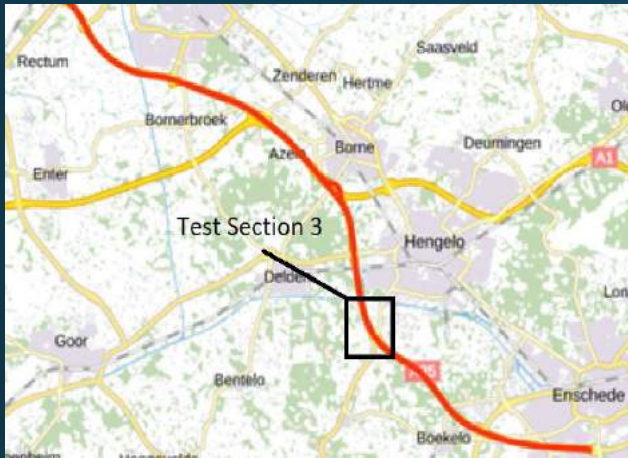
Distress data

Overlay

Conclusions

Empirical
Study

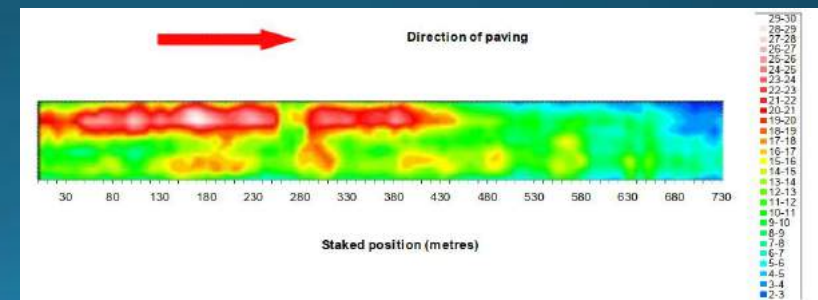
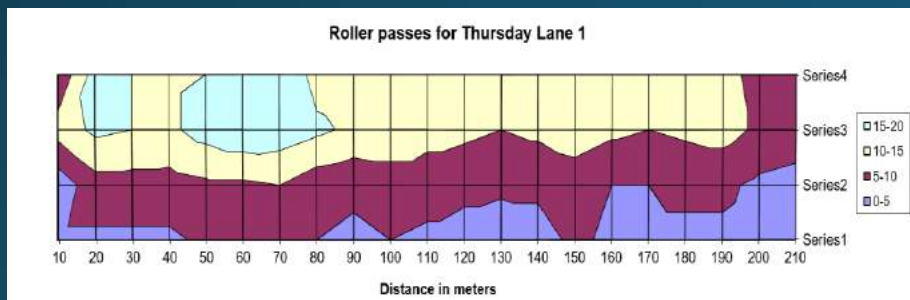
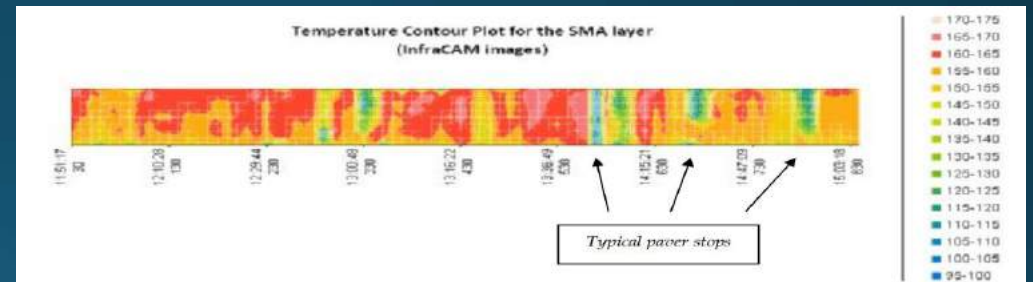
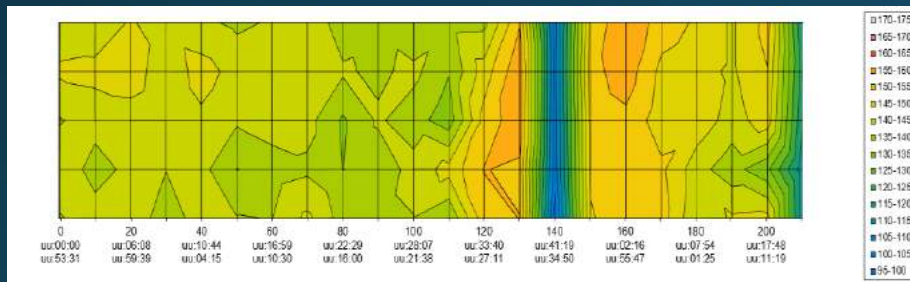
A35 Test Section 3 and Aziëhavenweg



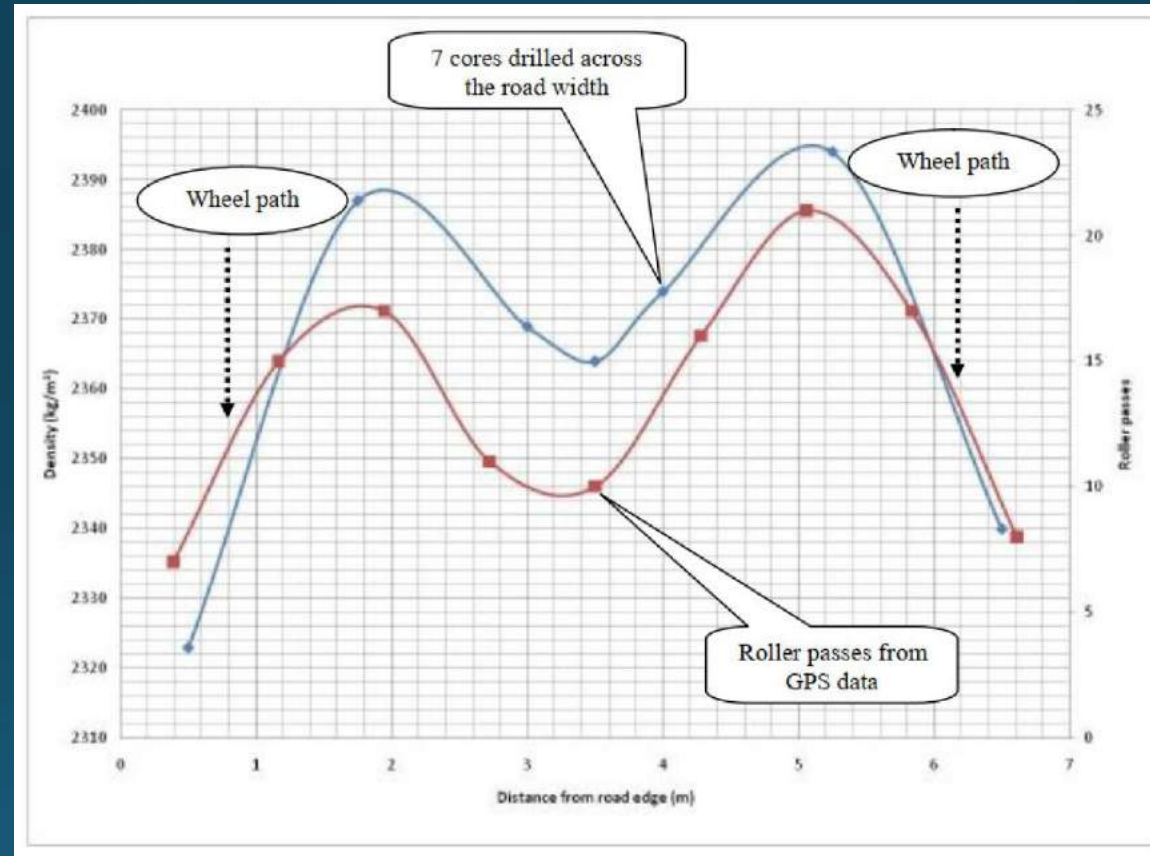
Source: Rijkswaterstaat, 2019



Source: Google Maps, 2019



Aziehavenweg 2008



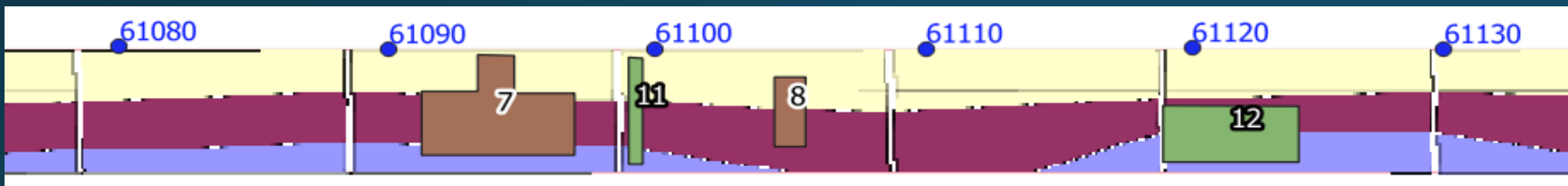
Aziëhavenweg 2019: Rutting

- Significantly more rutting on the outside of the road
- Difference in rutting between central 3 meters and outside 2 meters

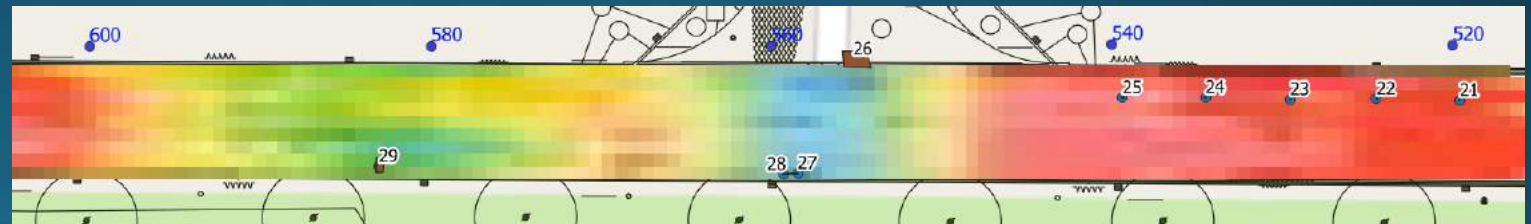


Final Conclusions

- Literature study and expert interviews suggests clear connection between temperature homogeneity and compaction and distress
- Empirical study suggest little to no connection between temperature homogeneity and compaction and distress such as cracking and raveling
 - Does suggest a connection between compaction percentage and rutting



Compaction map A35 overlaid with distress areas



Temperature Homogeneity map Aziehavenweg overlaid with distress areas



ASFALT RECYCLEN IN ÉÉN WERKGANG

EEN BIJDRAGE AAN DE ONTWIKKELING VAN EEN ASFALT RECYCLING TREIN IN NEDERLAND



ASPARI
Paving the way forward

**UNIVERSITY
OF TWENTE.**



DURA VERMEER

Chris van de Pol
Bsc Civiele Techniek
Bachelor thesis

IN SITU RECYCLEN FULL DEPTH RECYCLING



COLD IN PLACE RECYCLING



IN SITU RECYCLEN

HOT IN PLACE RECYCLING



DOELSTELLING ONDERZOEK

ZOAB 100% IN SITU RECYCLEN



Heating of porous asphalt for in-situ recycling

A contribution to the development of an Asphalt Recycling Train in the Netherlands



Chris van de Pol
Civil Engineering
University of Twente

Bachelor thesis report
11-11-2019



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PROCES STAPPEN

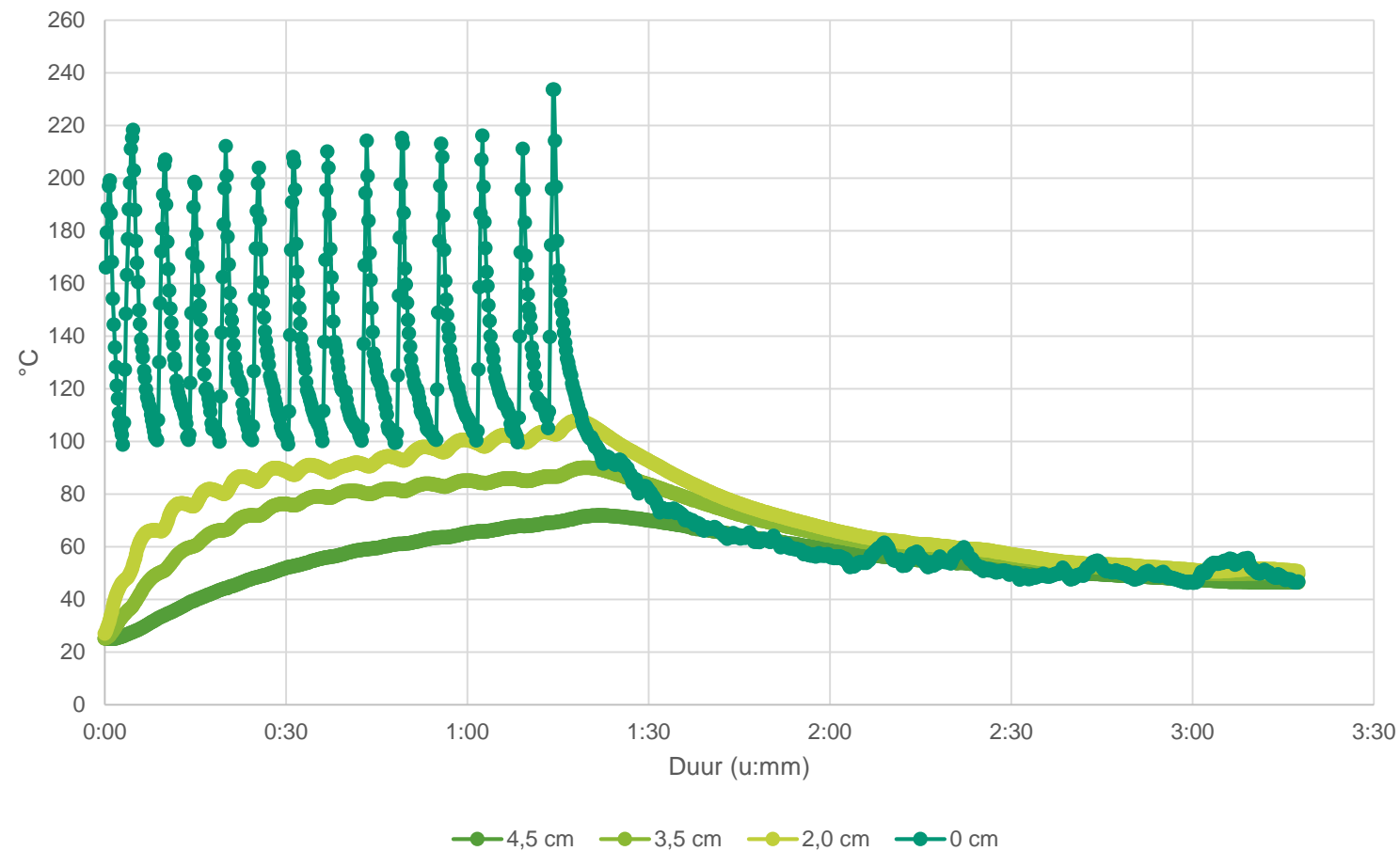
1. Voorverwarmen
2. Loswoelen
3. Herstellen
4. Naverwarmen
5. Homogeniseren
6. Verwerken
7. Verdichten



VOORVERWARMEN VAN ZOAB

INFRAROOD STRALING

Voorverwarming middels infrarood



VOORVERWARMEN VAN ZOAB

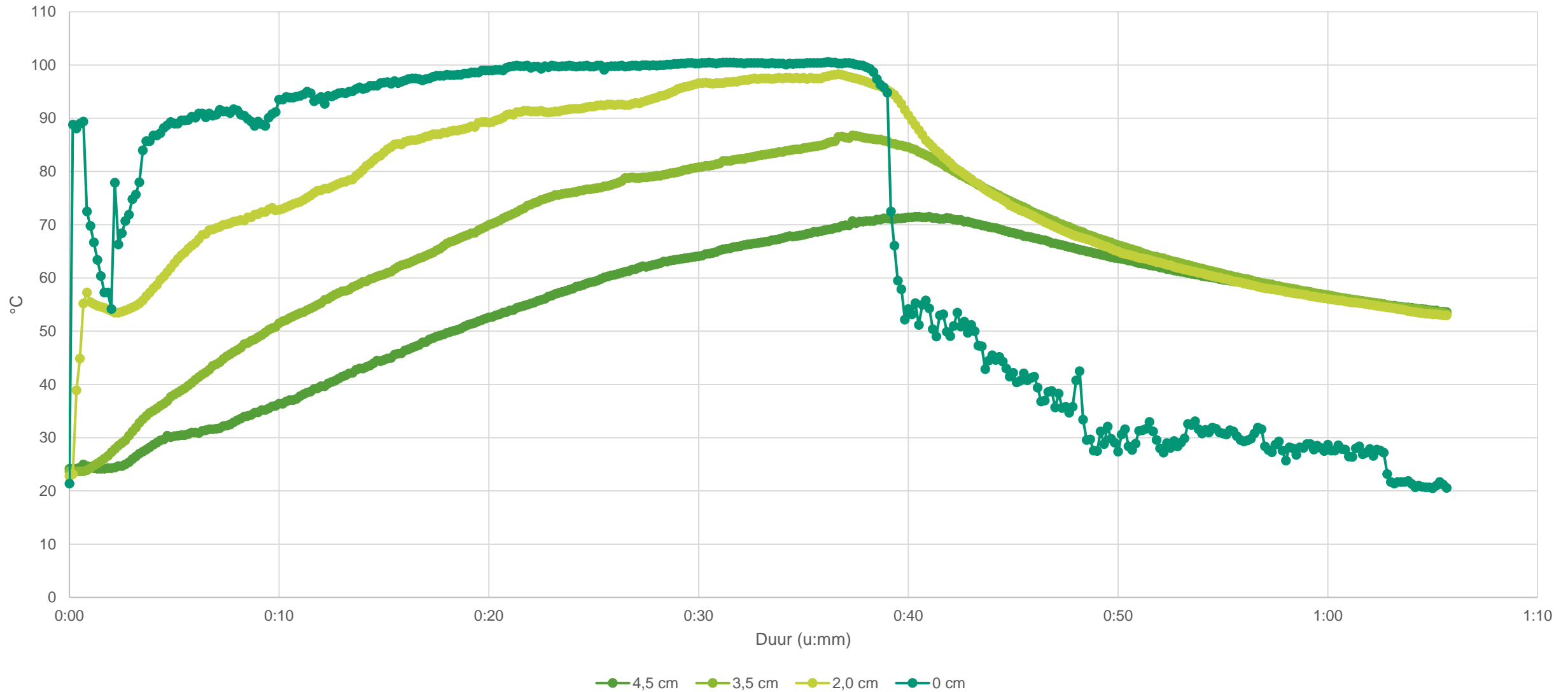
STOOM



VOORVERWARMEN VAN ZOAB

STOOM

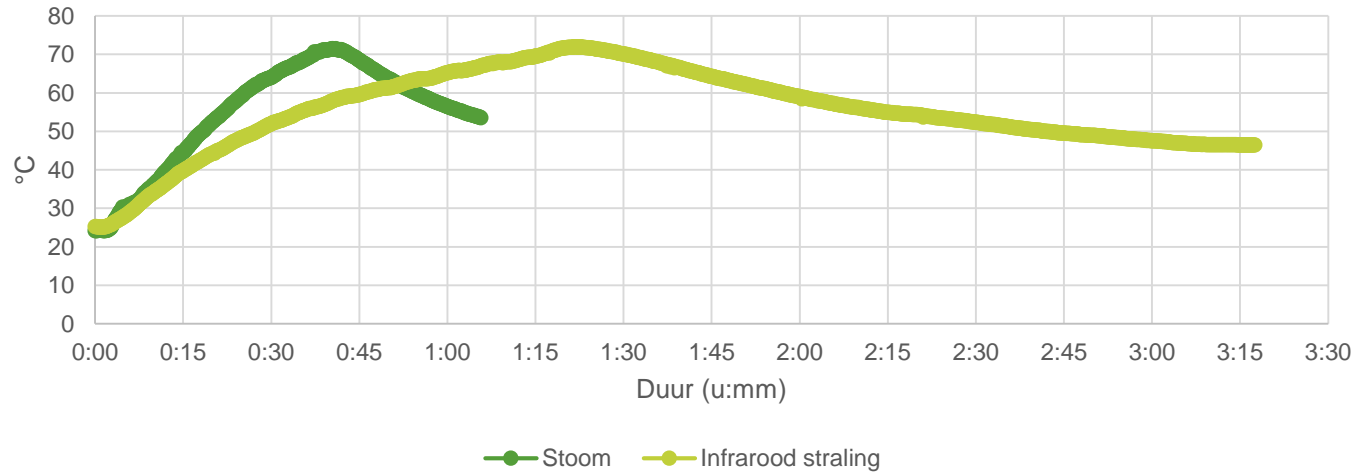
Voorverwarming middels stoom



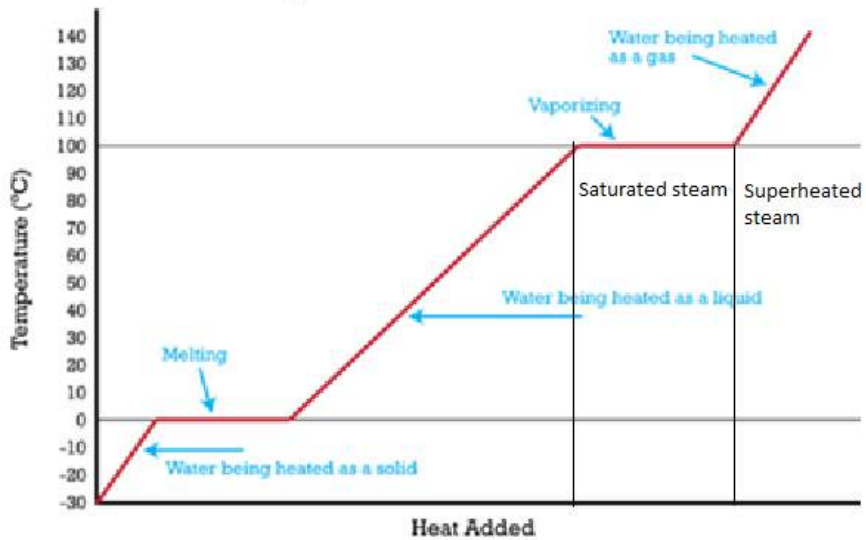
VOORVERWARMEN VAN ZOAB

STOOM – INFRAROOD – HETE LUCHT

Stoom versus infrarood



Heating Curve for Water at 1.00 atm Pressure



NAVOLGING A27 EEMNES



A67 HAPERT



ASFALT RECYCLING TREIN IN NEDERLAND?



DISCUSSIE & VRAGEN

100% RECYCLEN == 100% AFHANKELIJK VAN.....

100% in-plant recycling

100% in-situ recycling

Vooronderzoek?

Dataopslag door: Rijk, Provincies, Gemeenten, Aannemer?

- Type asfalt (mengselrecept, bitumen)
- Datum van aanleg
- Reparatievakken, vorstschade
- ASPARi data?
- CAD, GIS, BIM?
- Onderlagen?



Temperatuurdrempels voor verdichtingsproces

Aspari Mini-symposium

4 december 2019 te
Harderwijk

Universiteit
Twente/Boskalis

Wido de Witte

Probleem en onderzoeksrichting

- Temperatuurgrens voor verdichtingsproces
- Geen model voor grensbepaling
- Nieuwe asfaltmengsels
- Impliciete kennis
- Verwerkbaarheid
- Dichtheidsprogressie
- Analyse en evaluatie

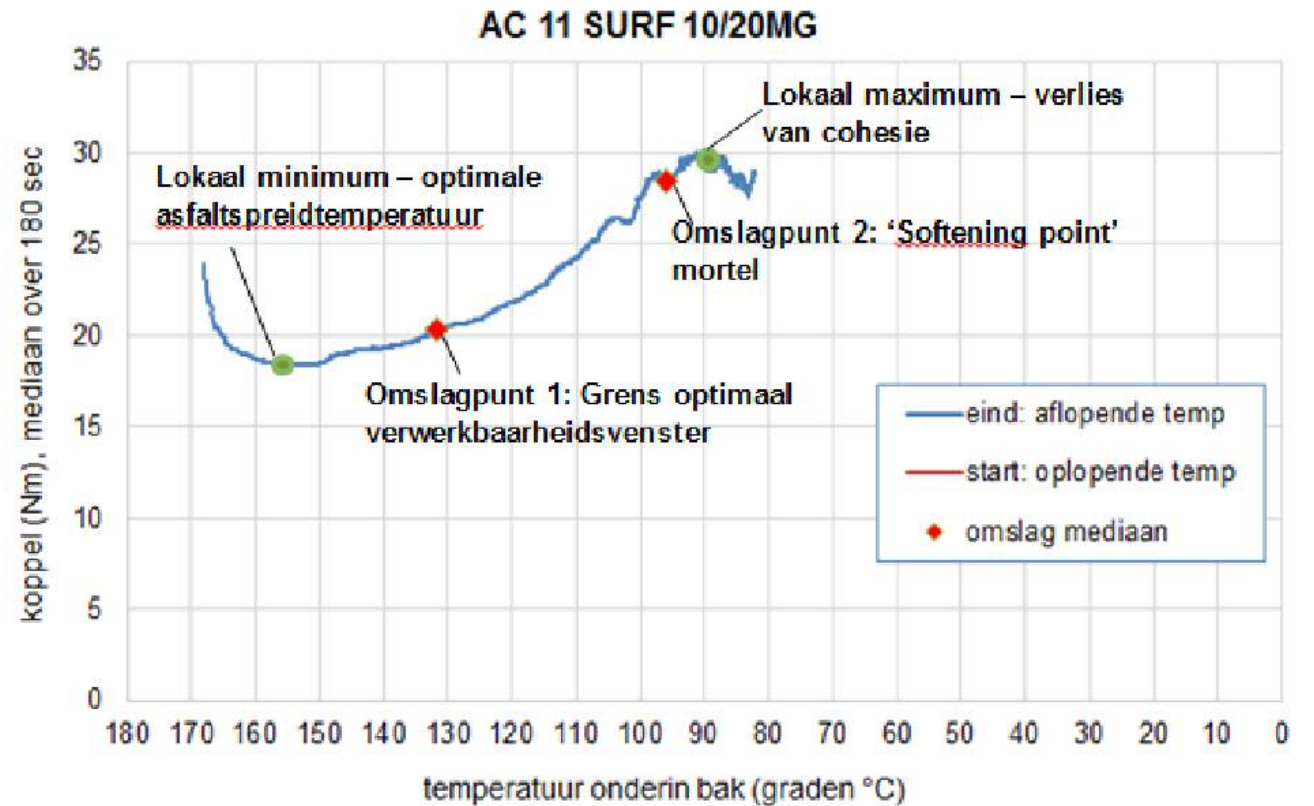
Verwerkbaarheidsproef

- Verwerkbaarheid
 - Koppel
 - Temperatuur
- Drempelwaarden
 - Minimum
 - Optimum
 - Softening point
- Protocol
 - 20 kg
 - 15 rpm



Verwerkbaarheidsproef

- Verwerkbaarheid
 - Koppel
 - Temperatuur
- Drempelwaarden
 - Minimum
 - Optimum
 - Softening point
- Protocol
 - 20 kg
 - 15 rpm



Doel en scope

- Validatie en evaluatie
- Verwerkbaarheidsproef
 - Temperatuurvenster
- Verdichtingsproces veldproject
 - Dichtheid progressie
 - Temperatuur
- Data vergelijken
- Evaluatie van de verwerkbaarheidsproef
- ZOAB-mengsel
- Asfaltbeton mengsel
- Metingen wintermaanden
- Wel en geen gemodificeerde bitumen

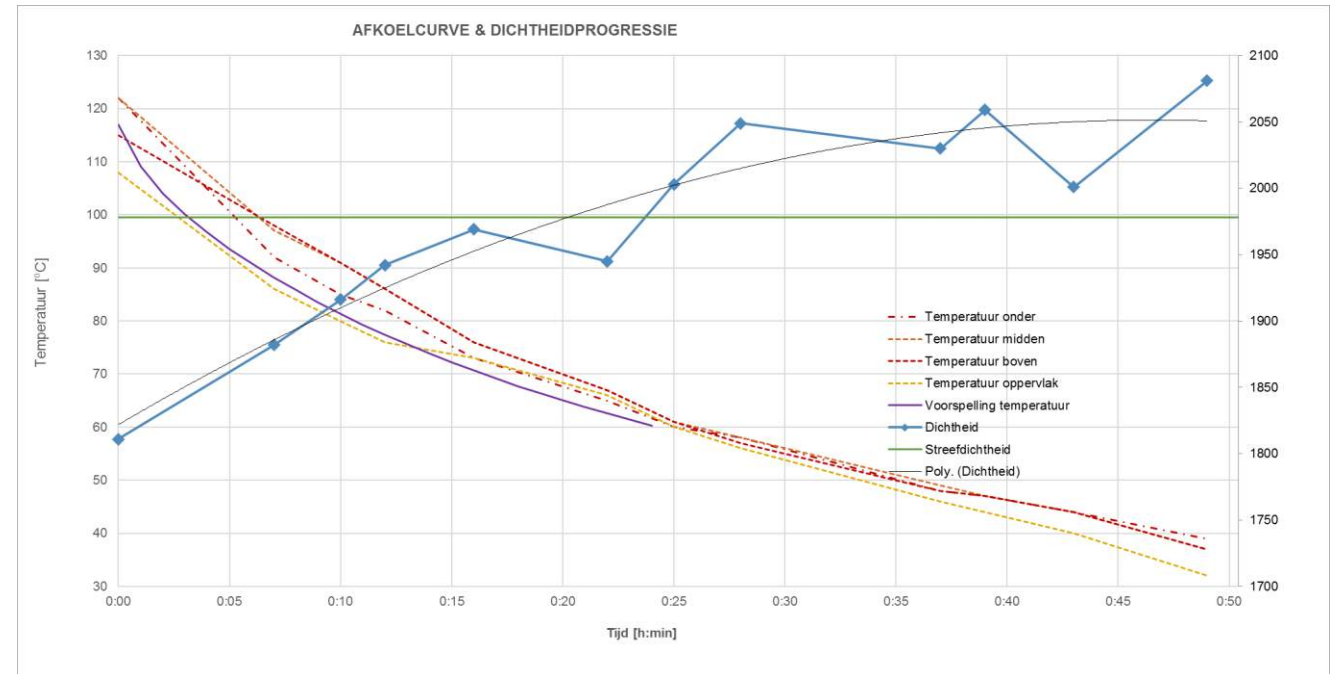
Veldmeting

- Verloop dichtheid
 - Nucleaire dichtheidsmeter
- Temperatuurverloop
 - In en op asfalt
- Observatie walsen
 - Type wals
 - Interval



Veldmeting

- Verloop dichtheid
 - Nucleaire dichtheidsmeter
- Temperatuurverloop
 - In en op asfalt
- Observatie walsen
 - Type wals
 - Interval



Analyse

- Verwerkbaarheidsproef
- Veldmeting
- Verhouding koppel
- Streefdichtheid
- Dichtheidprogressie

- Voorspelde afkoeling
- Weer

Uitdagingen

- Verwerkbaarheidsproef
 - Definiëren verwerkbaarheid
 - Snelheid mengarm
 - Temperatuurverdeling
- Veldmeting
 - Nauwkeurigheid meetapparatuur
 - Geen invloed omstandigheden
- Vergelijking
 - Verandering dichtheid t.o.v. temperatuur
 - Streefdichtheid behaald
 - Walspassage
 - Variabiliteit temperatuur hoogte

Einde presentatie

Wido de Witte
Universiteit
Twente/Boskalis



VALIDEREN VAN VOORSPELLINGSMODELLEN VAN ASFALTKOELING

BACHELOR THESIS

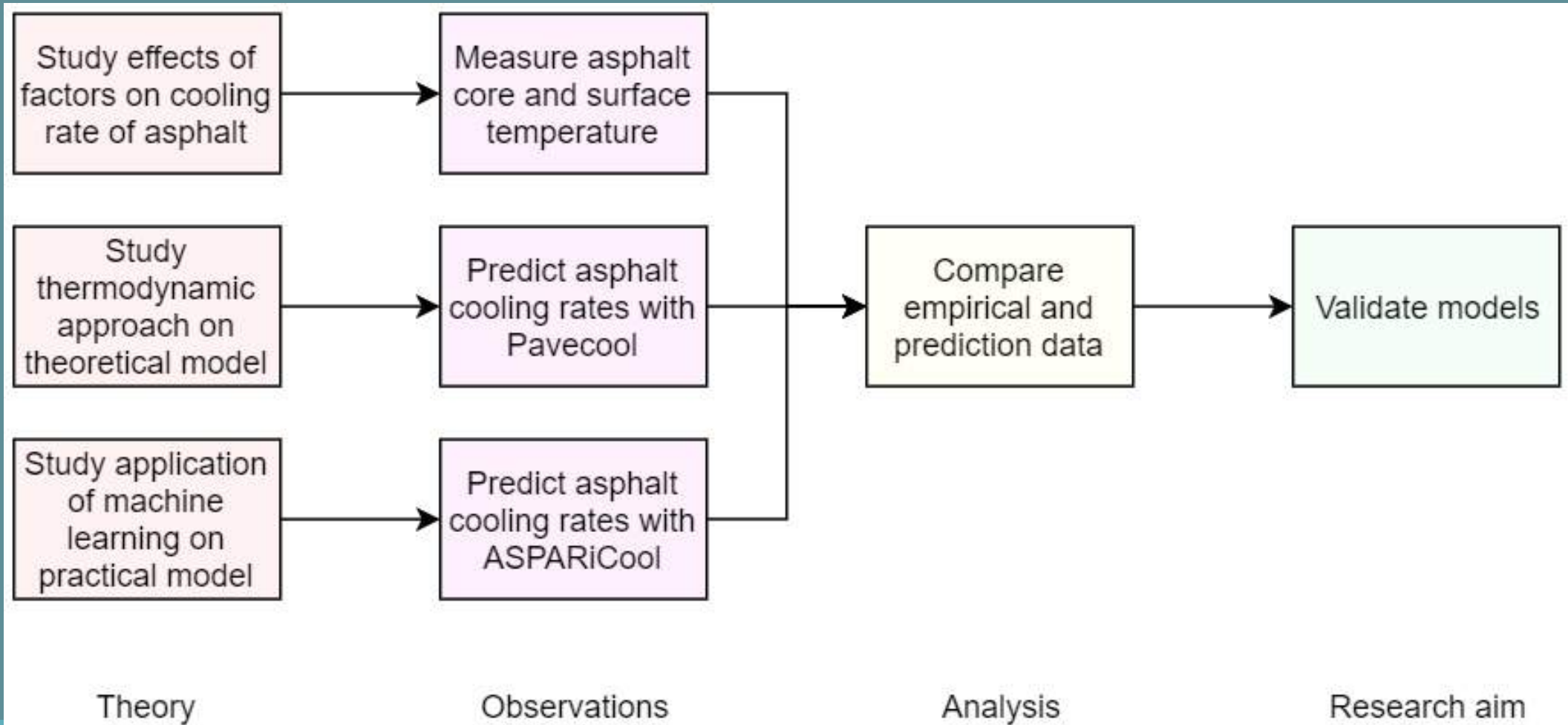
PETER BAARS

ASPARI & ROELOFS – UNIVERSITY OF TWENTE

Beschrijving project

- Koeling asfalt belangrijk voor verdichting
- Kwaliteit asfalt
- Afkoelingscurve
- Voorspellingsmodellen (o.a. Pavecool, ASPARiCool)
- Gebrek aan empirische data
- (Nederlandse) variërende weersomstandigheden

Onderzoeksmodel









Meetverslag 3

Datum: 15 november 2019
Locatie: Runderweg 6, Lelystad

Situatieschets:

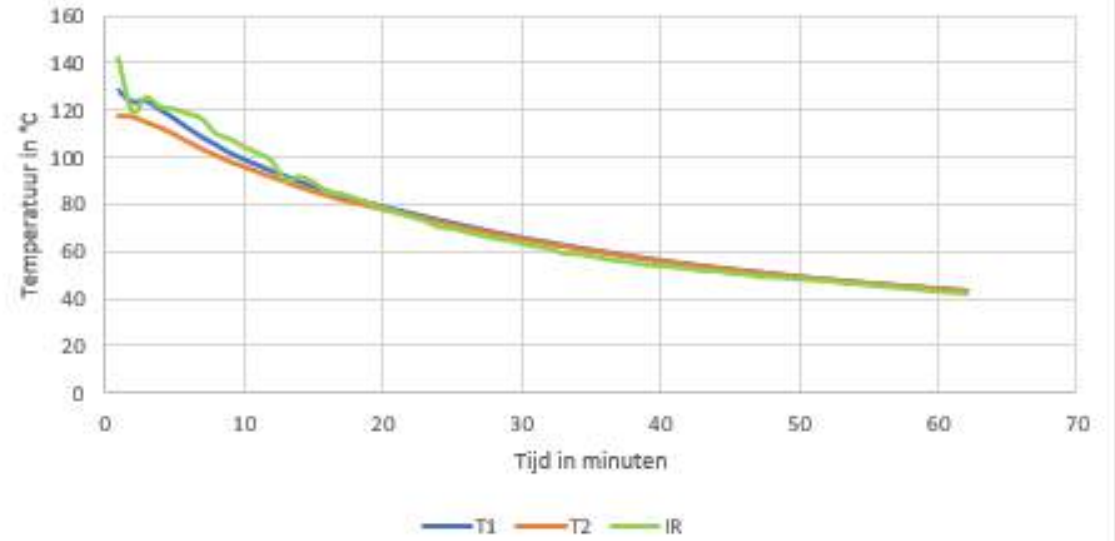


Situatiebeschrijving:

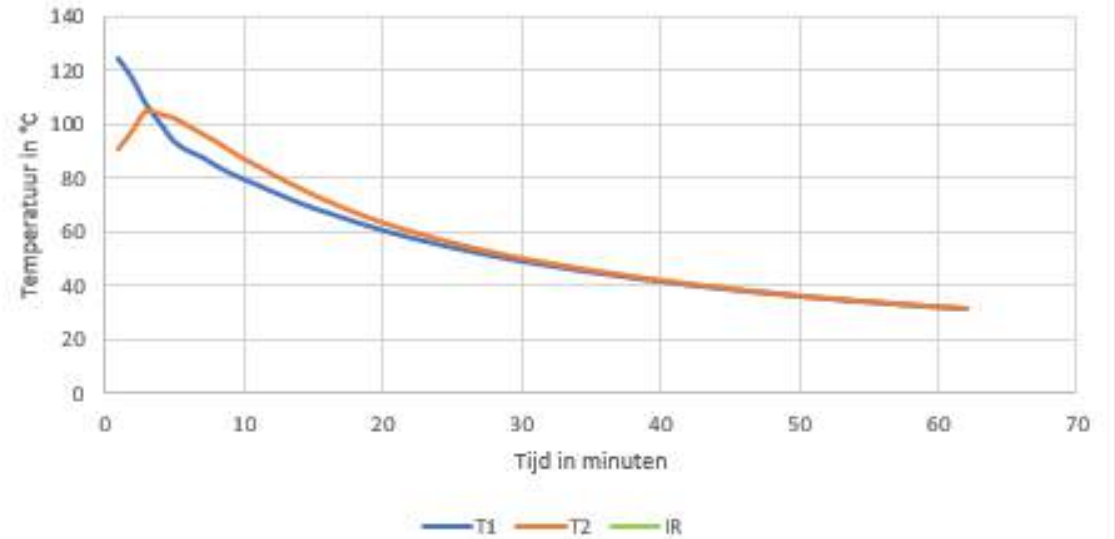
Type weg:	Privé asfaltweg
Geschatte lengte traject:	400 m
Geschatte breedte traject:	6 m
Mengsel:	AC 16 Surf DL-C
Laag:	Deklaag
Laagdikte:	4 cm
Oppervlakte asfalt:	2750 m ²
Hoeveelheid asfalt:	275 ton
Bijzonderheden:	Weerstation is verplaatst van B naar C vlak na begin meting punt C

Afkoelingscurves per meetpunt

Afkoelingscurves meetpunt A



Afkoelingscurves meetpunt B



Meetverslag 5

Datum: 26 november 2019
Locatie: Kroezenhoek-West, Den Ham
(Nieuw industrieterrein aan de Vriezendijk)

Situatieschets:

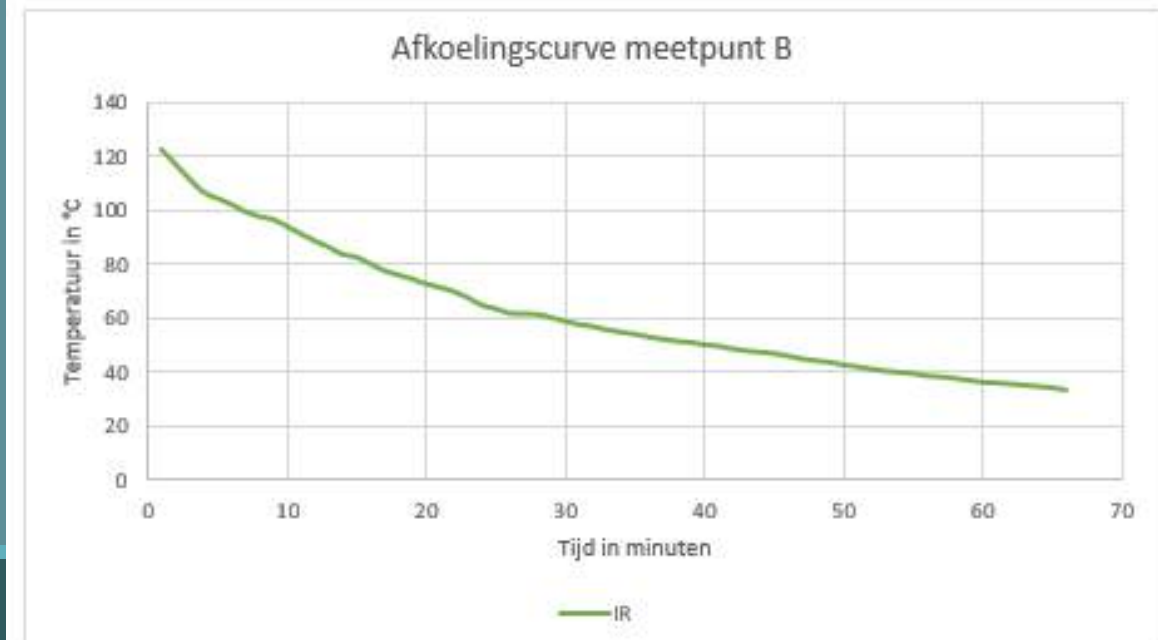
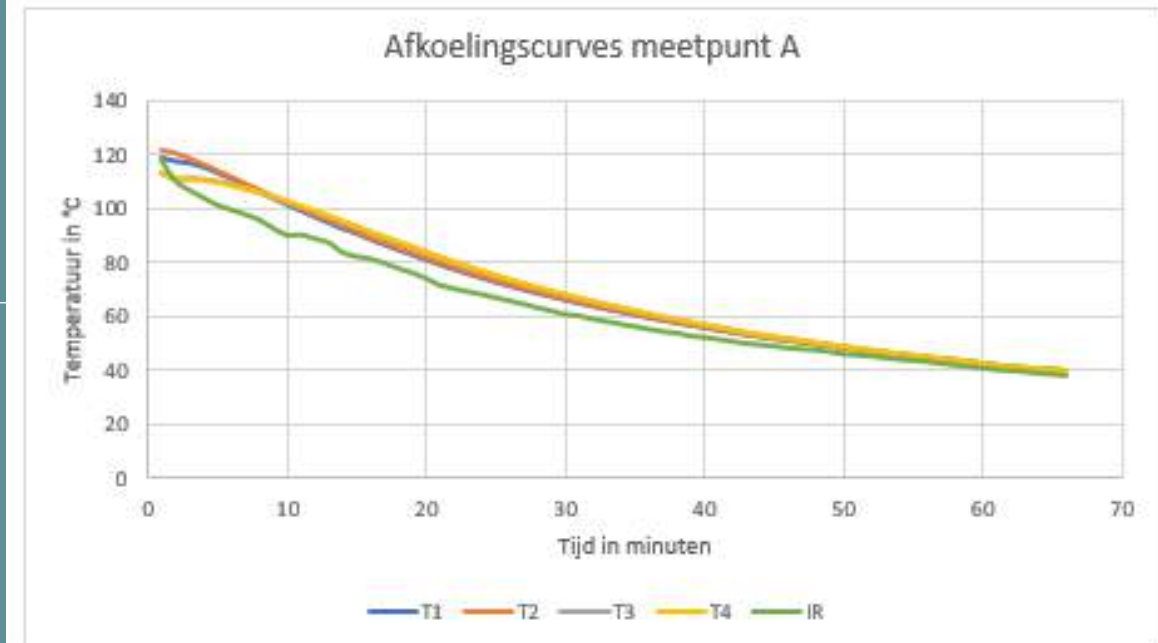
Situatiebeschrijving:

Type weg:	Erftoegangsweg industrieterrein
Geschatte lengte traject:	
Geschatte breedte traject:	
Mengsel:	AC 22 Base OL-B
Laag:	Onderlaag
Laagdikte:	6 cm
Oppervlakte asfalt:	3175 m ²
Hoeveelheid asfalt:	477 ton
Bijzonderheden:	

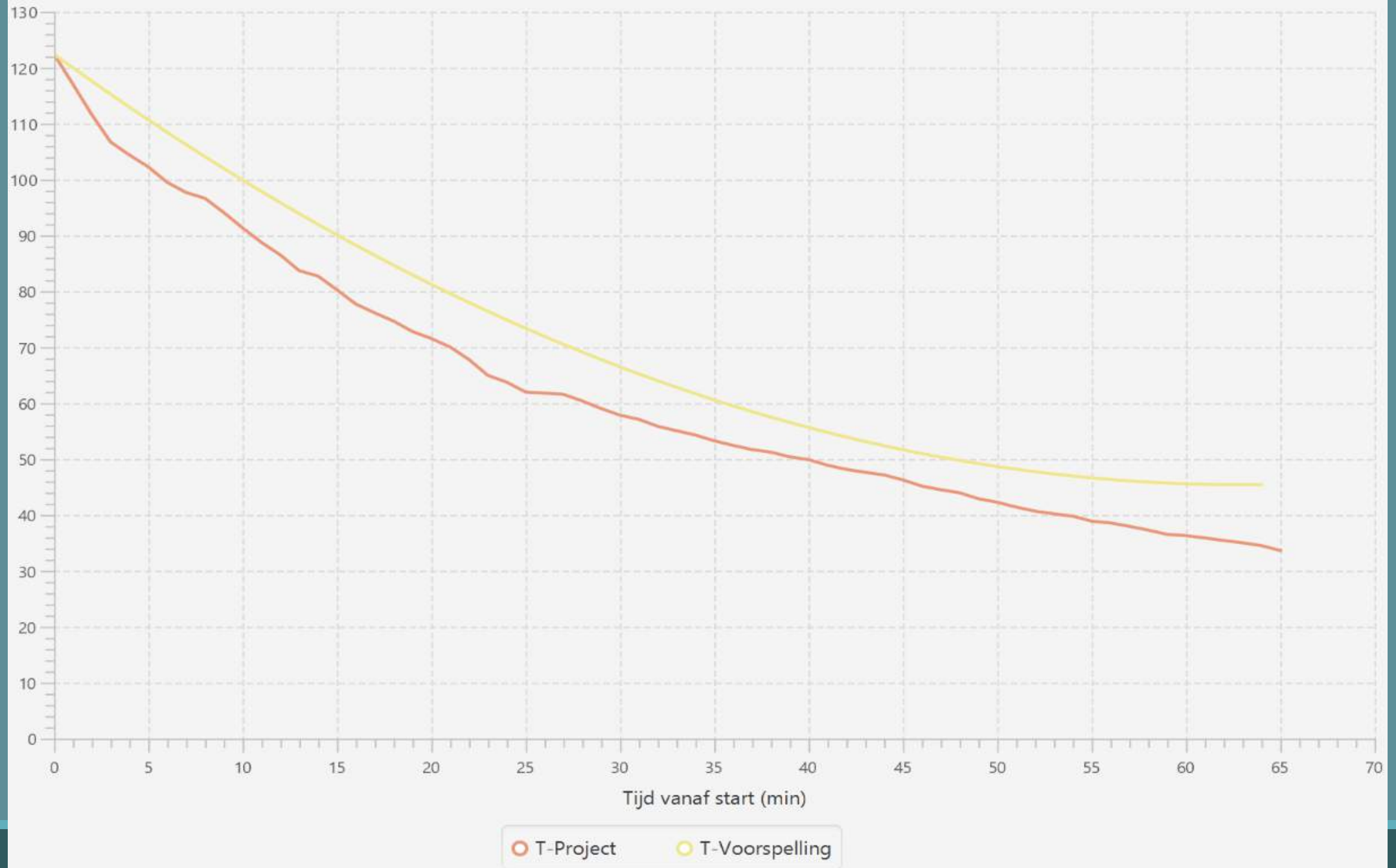
Materialen:

- 1 infraroodcamera (op meetpunten A, B en C)
- 1 infraroodscanner (handmatig data loggen, meetpunt D)
- 3 thermokoppelhouders (met ieder 4 thermokoppels)*
 - o *Niet alle thermokoppels konden worden gebruikt, doordat niet alle stekertjes in de datalogger pasten

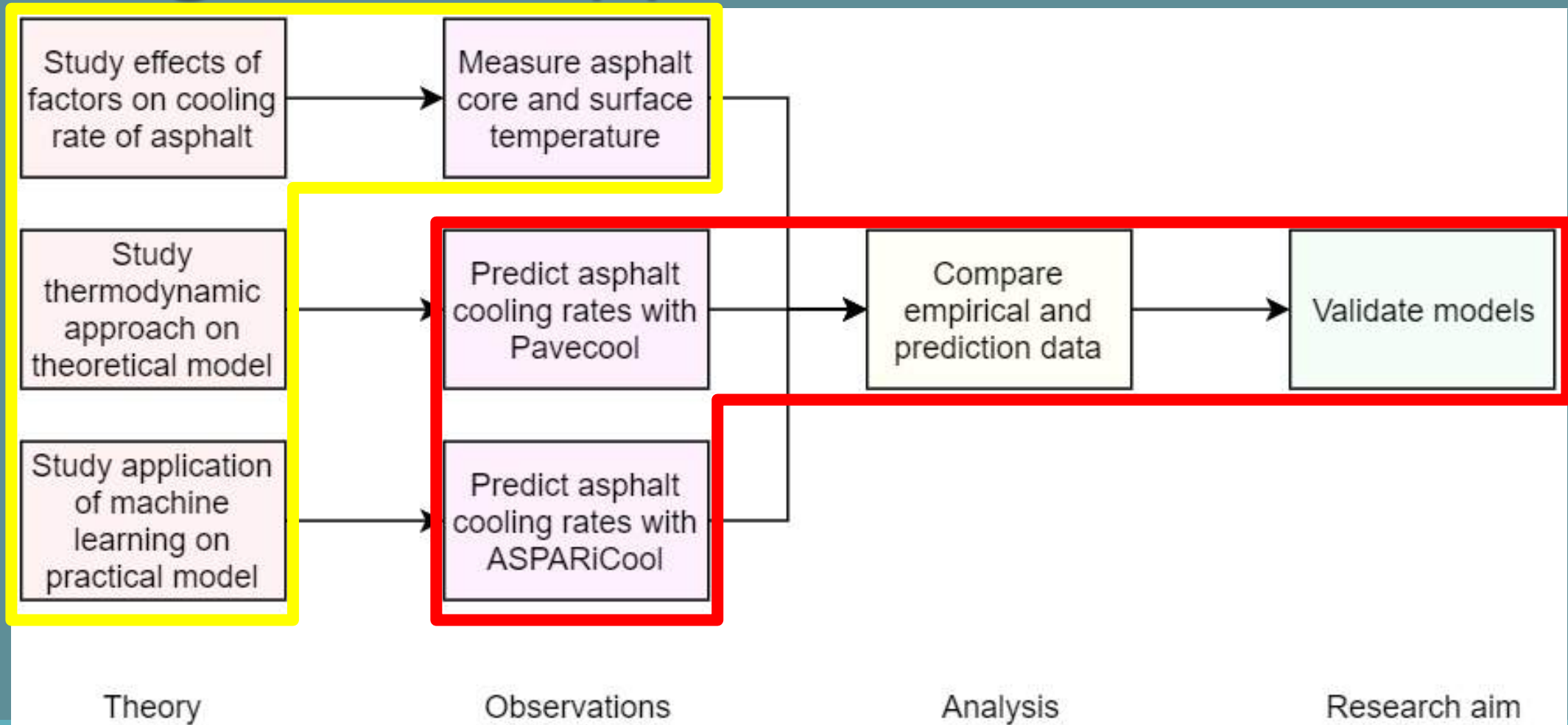
Afkoelingscurves per meetpunt



Vergelijking voorspelling met ASPARICOOL PUNT B 26112019.xlsx



Volgende stappen



Activity	Week:	1	2	3	4	5	6	7	8	9	10	11	12
Finishing proposal													
Literature research			*				*						
Field measurements													
Processing and structuring data			*	*			*						
Predictions								*					
Analyse and compare data													
Compare output with literature													
Conclusions/recommendations													
Write report													
Examination													
Eventual delay project													

**Optional*



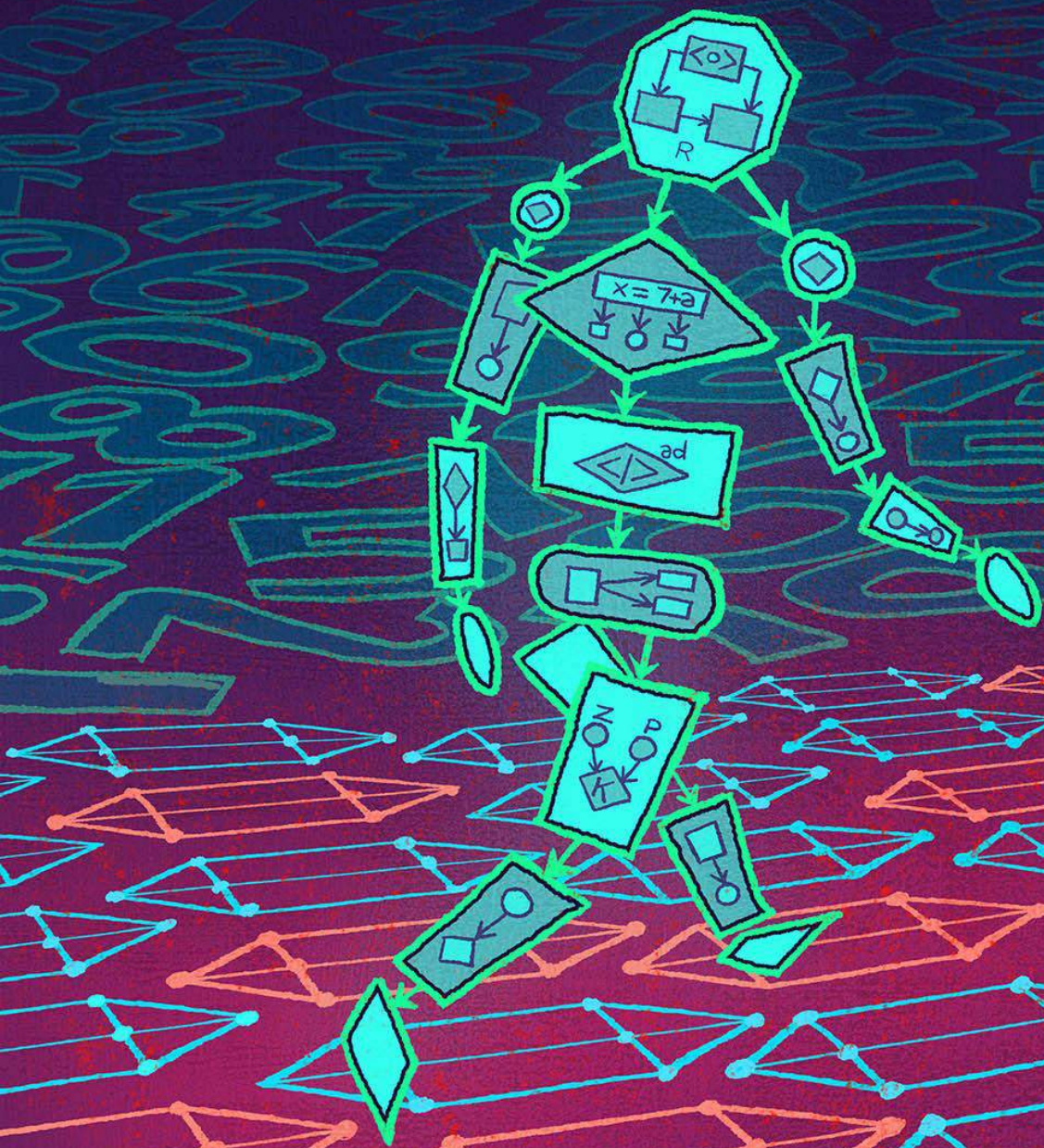
BEDANKT VOOR UW AANDACHT

ZIJN ER NOG VRAGEN?

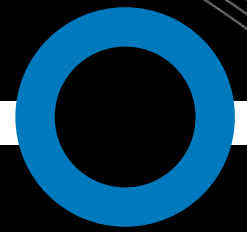
VIRTUAL REALITY-BASED TRAINING SIMULATOR FOR PAVING OPERATION

FARID VAHDATI & SAJJAD MOWLA

DEC. 2019



IN THIS PRESENTATION:



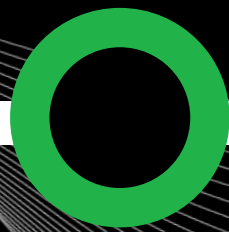
1.

Introduction



2.

Training Simulator



3.

Things to Capture



4.

Things to Learn



5

Take-home
message



6.

Discussions

ASPARi showed that there is more to paving operation than we thought before! Together, we generated new insights!



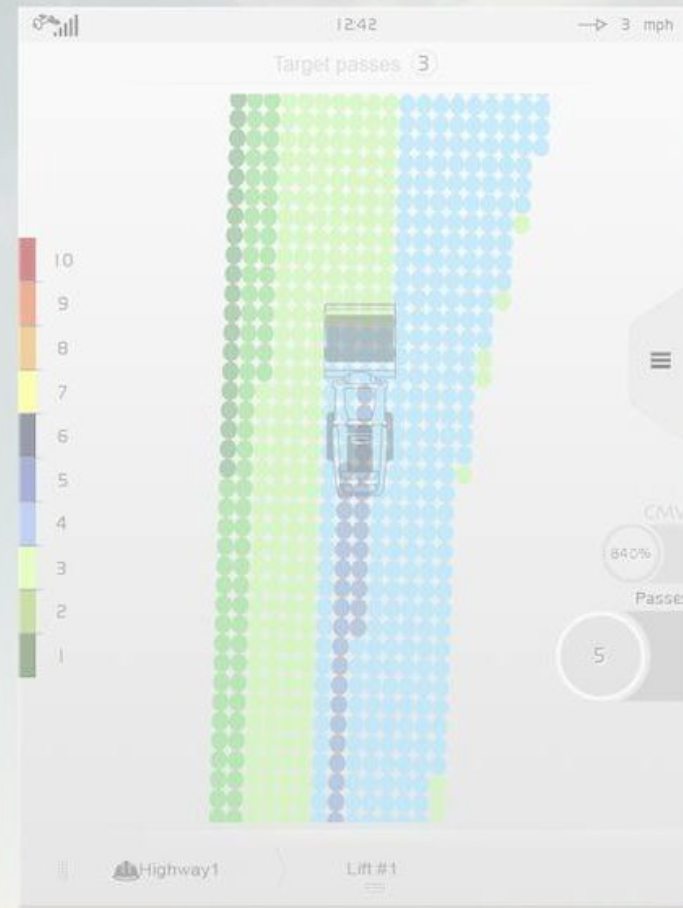
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We need to transfer these insights to the next generation!

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It is also important to support operators to better carry these insights into their work.
But, what, when, and how?



Development of support systems and training with actual equipment is **time-consuming, costly, and unrealistic** (i.e., controlled environment)

A woman with blonde hair, wearing a high-visibility yellow and blue safety jacket and a black VR headset, is holding two VR controllers. She is in a factory or industrial setting, with a computer monitor displaying a 3D model of a mechanical part in the background. The scene is brightly lit with overhead lights.

Virtual Reality (VR) provides an easy, cheap, and safe platform for training and testing

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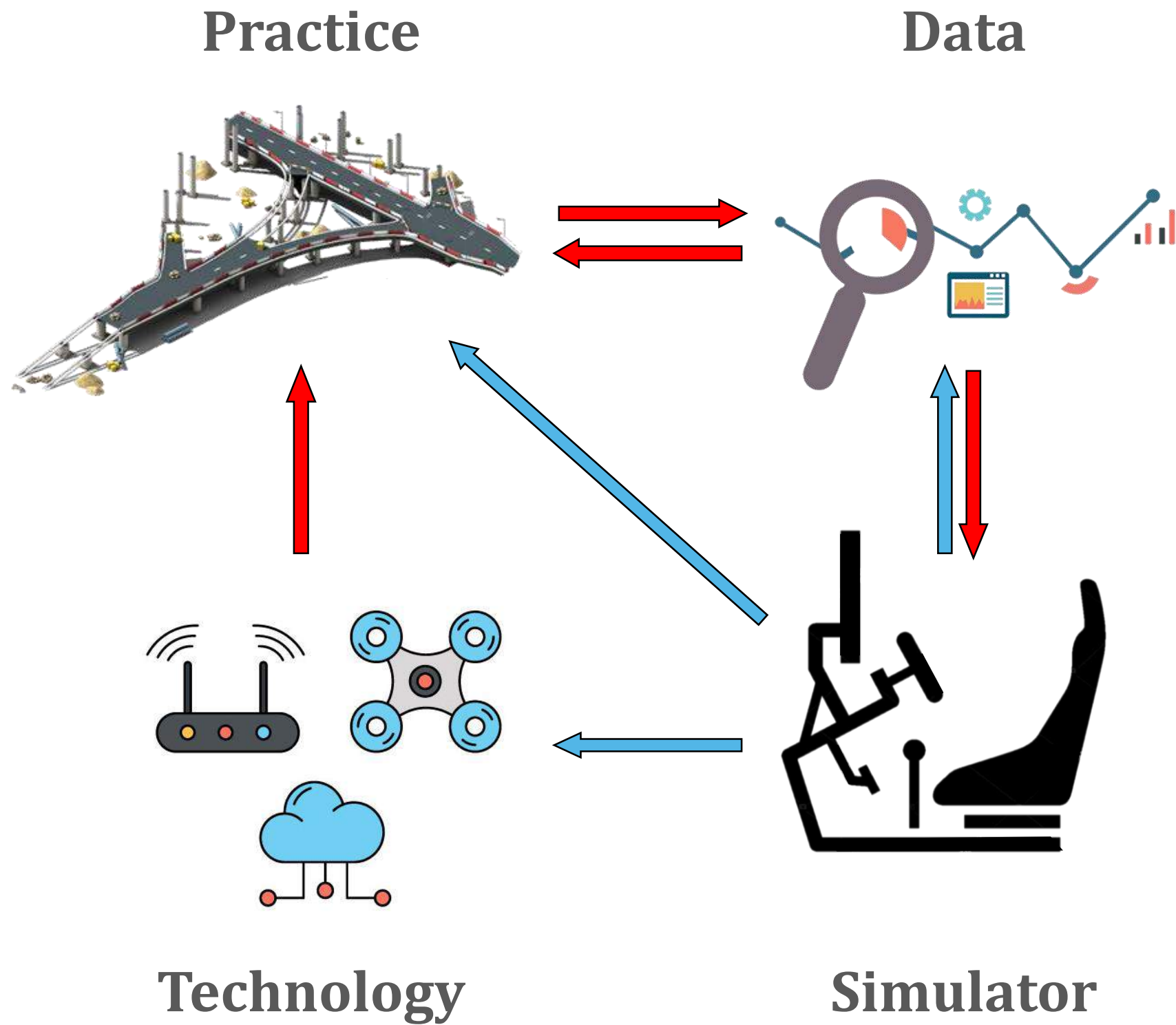


There are many VR simulators for different types of construction equipment. But, there are virtually no simulators for paving equipment

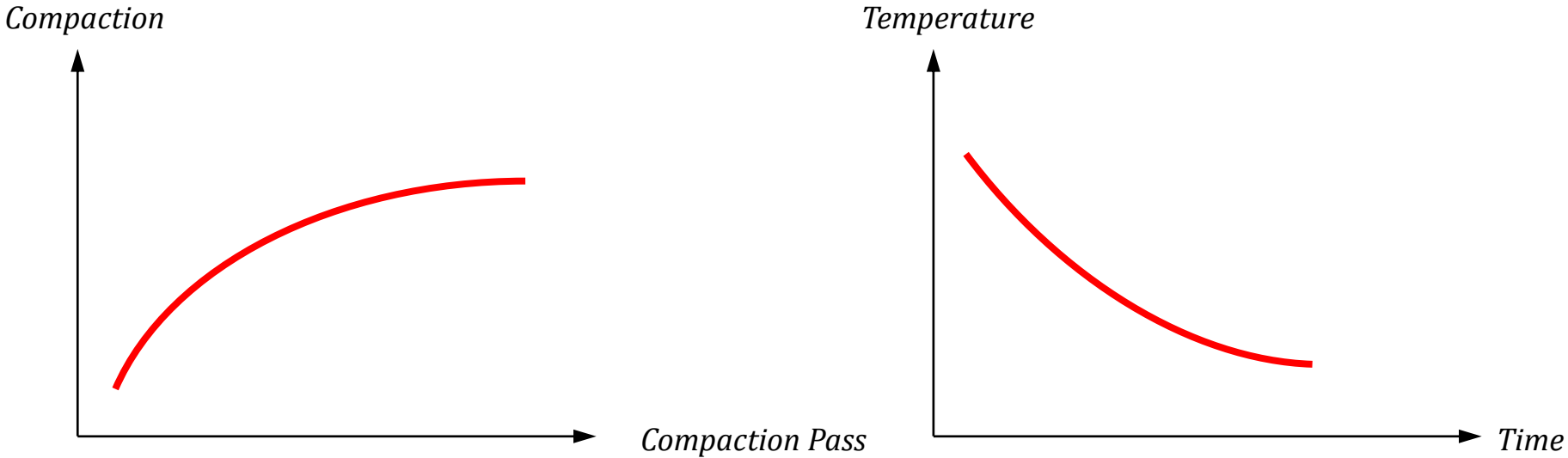
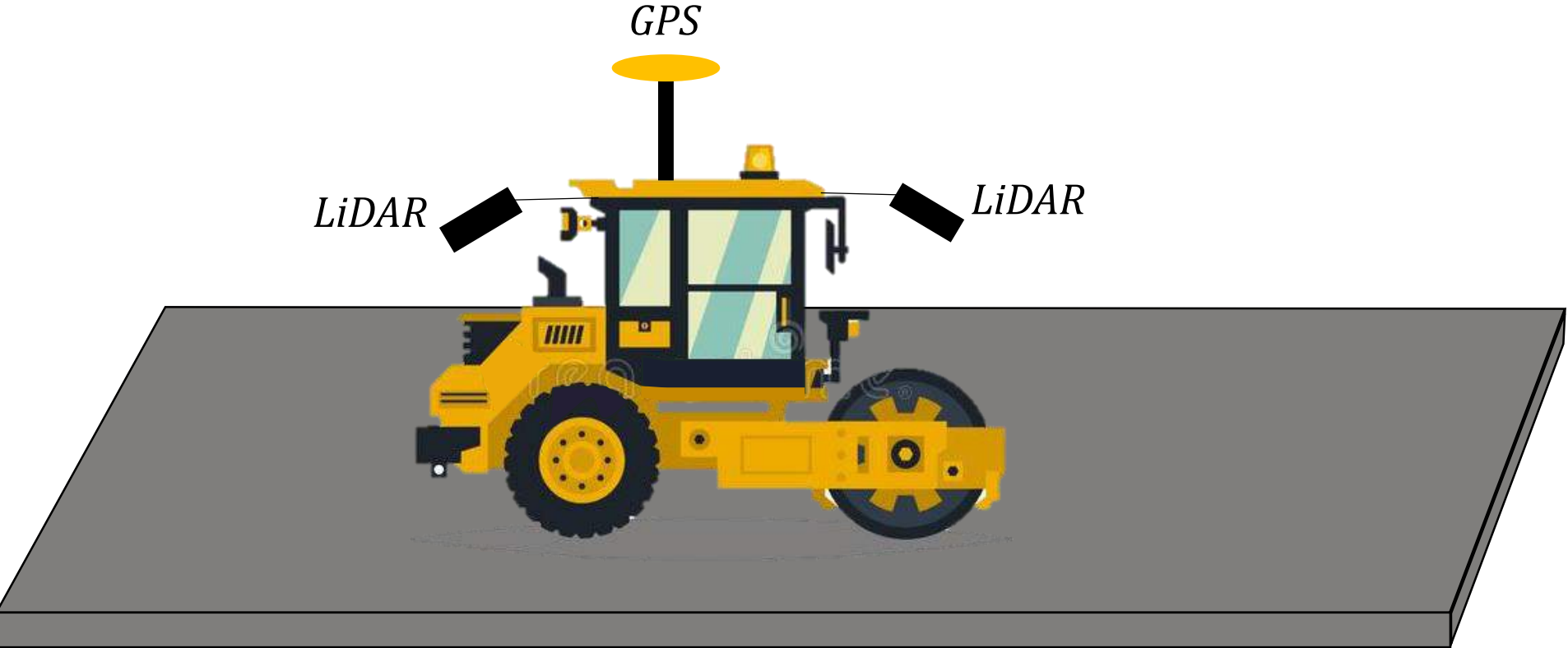
ASPARi intends to build on its rich data- and experience-base to take the initiative for building a VR-based training simulator for paving operations

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Our approach is to use simulators as a mediator to close the loop between practice, technology, and data.



ASPARi data can be leading in developing a physics- and context-realistic simulator



Feedback from operators, teachers, and students is essential.



VR simulator is not only a way to train new operators, but also, but also to learn more from data and to assess technological solutions before implementation.

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HOW CAN WE **IMPROVE** **TRAINING** EVEN FURTHER?



Is automation all about technology?

..or do we need just a little bit of that human touch

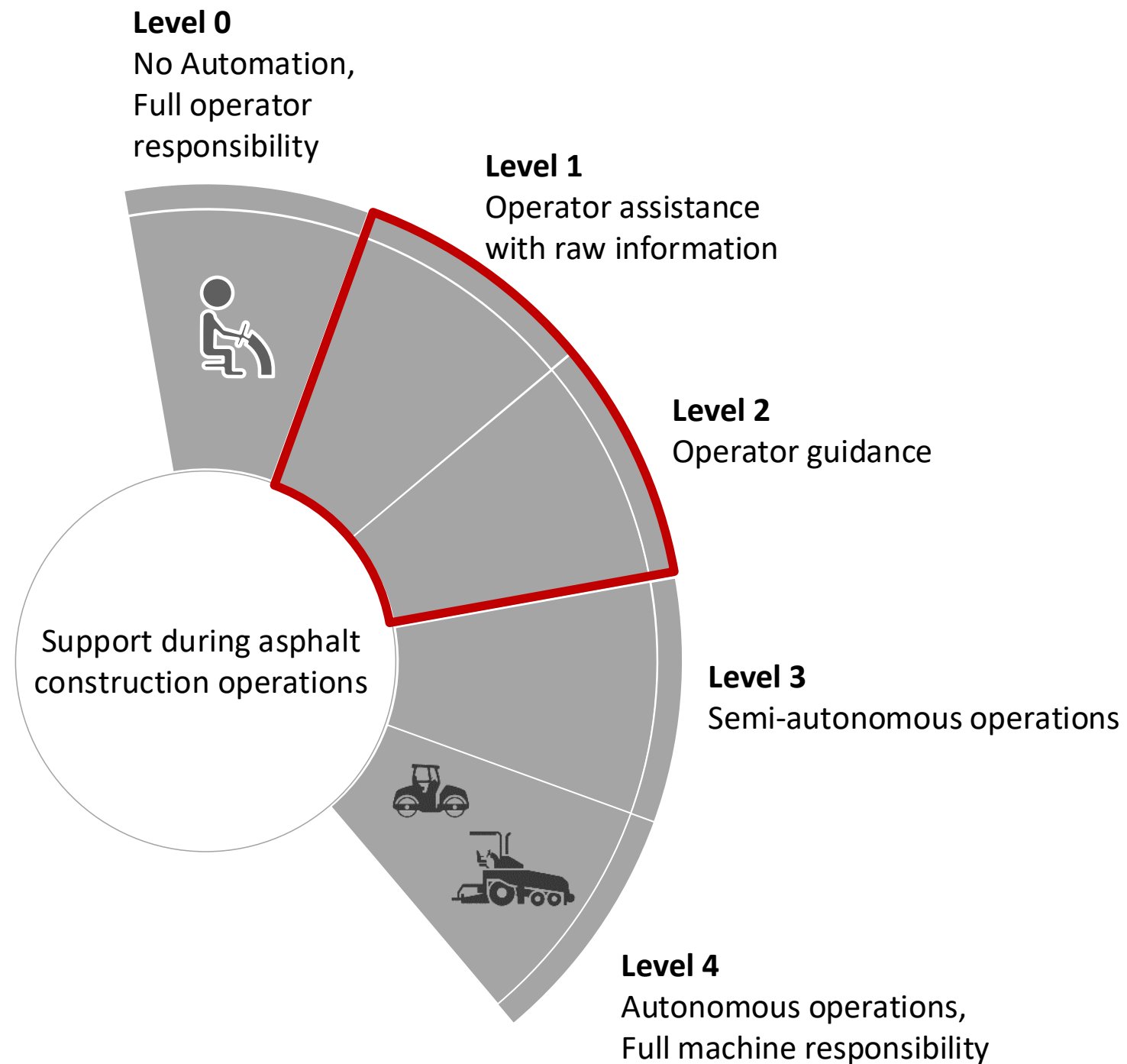
ASPARi symposium 2019

Denis Makarov

Agenda

- ..2018 symposium
- Current state of autonomy in asphalt construction
- ASPARi approach

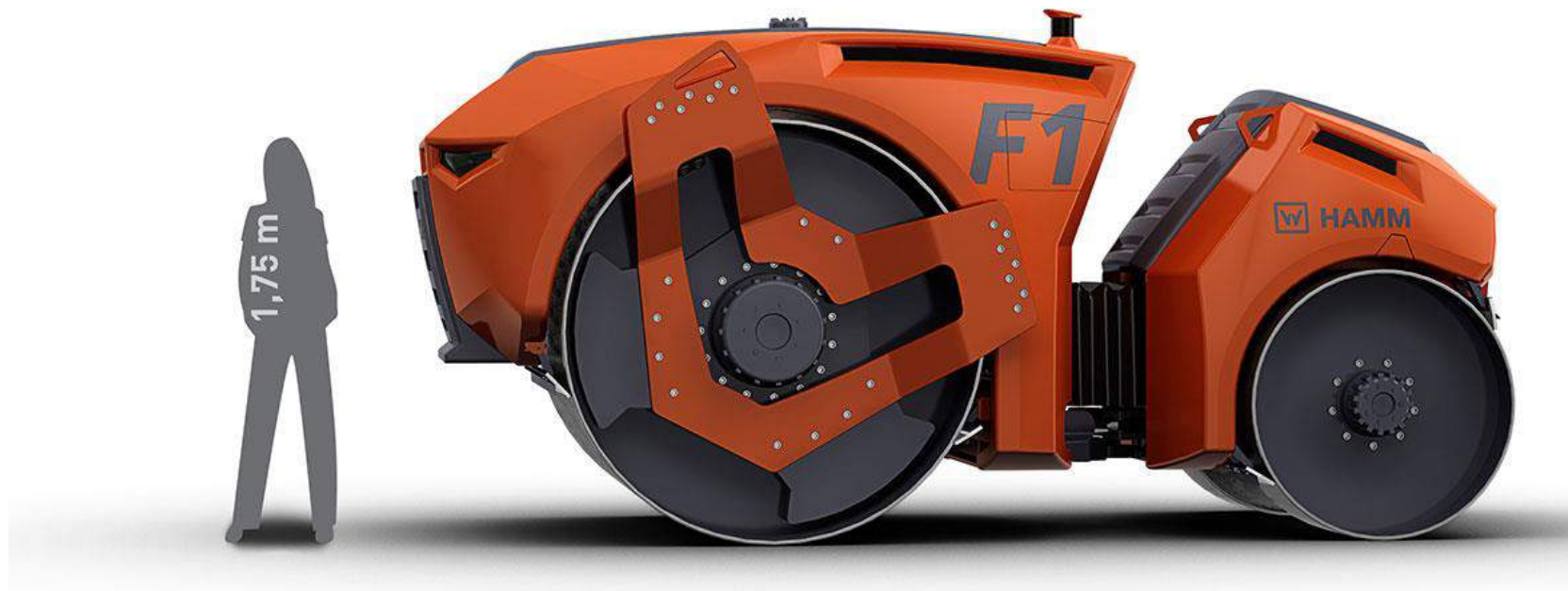
ASPARi symposium 2018..



- Provide operators with actionable guidance over their operations instead of 'raw' process related data

Industry initiatives

..
Dr. Axel Römer, Head of R&D at HAMM, has already examined with his team what a self-driving roller might look like: “We have considered technical, constructive and economic aspects and evaluated them in various studies. The result: A driverless roller will not have an operator’s platform anymore but will need significantly more sensors to monitor not only the compaction parameters but also the area surrounding the roller. We have connected these requirements and see many new and constructive possibilities. For example, we could construct autonomous rollers with significantly larger drum diameters, bigger water tanks and more space for the batteries of electrically powered rollers. This offers advantages in terms of quality, environmental friendliness and efficiency.” In collaboration with industrial designers, HAMM has elaborated and drawn up a corresponding concept plus design study. The result is impressive – in particular the drum of the 9-tonne machine with its diameter of just under two meters. At the same time, the overall height of the machine is significantly lower than that of current machines with cab or roof.



<https://www.hamm.eu/en/news-media/news-jobreports/2019/01-construction40.php>



<https://www.bomag.com/ww-en/press/news-videos/future-study-fully-autonomous-tandem-roller/>

..
The fully autonomous tandem roller ROBOMAG can be used completely independently in a defined work area. For loading or manual operation, the ROBOMAG tandem roller can be operated simply by remote control. The system obtains information on position, situation and movement using a combination of different technologies for spatial orientation, environmental perception and environmental safety. A comprehensive safety concept with sensory environment recognition is used to prevent collisions. In addition to the fully automatic mode, the ROBOMAG also has the option to follow manually entered movement patterns so the roller can perform its task autonomously even with special compaction jobs. It goes without saying that the roller has a mechanical emergency stop mechanism in every mode.

Industry initiatives

Dr. Axel Römer, Head of R&D at HAMM, has already examined with his team what a self-driving roller might look like: “We have considered technical, constructive and economic aspects and evaluated them in various studies. The result: A driverless roller will not have an operator’s platform anymore but will need significantly more sensors to monitor not only the compaction parameters but also the area surrounding the roller. We have considered the requirements and constructive possibilities. For example, the use of significantly larger drum diameters, the use of batteries of electrically powered rollers for improved environmental friendliness and the use of autonomous navigation. HAMM has elaborated and drawn up a concept. The result is impressive – in particular, the width of the roller is just under two meters. At the same time, the height is significantly lower than that of conventional rollers.”

Are we really ready for fully autonomous machines?

- Accuracy of sensory data
- Process quality
- Asphalt quality
- Safety of the process



[/news-videos/future-study-fully-autonomous-tandem-roller/](#)

The roller ROBOMAG can be used completely autonomously. For loading or manual operation, the roller can be operated simply by remote control. The system enables autonomous navigation and movement using a combination of GPS, laser orientation, environmental perception and a fail-safe safety concept with sensory environment recognition is used to prevent collisions. In addition to the fully automatic mode, the ROBOMAG also has the option to follow manually entered movement patterns so the roller can perform its task autonomously even with special compaction jobs. It goes without saying that the roller has a mechanical emergency stop mechanism in every mode.

<https://www.hamm.eu/en/news-media/news-jobreports/2019/01-construction40.php>

Classification matters

- Provides a **common terminology**, which eases the **sharing of knowledge**;
- Provides a better understanding of the **interrelationships** between the levels;
- Helps to identify **gaps in a knowledge**;
- Supports **decision making processes**.

Examples of existing metrics

Aviation



HIGH

10. The computer decides everything, act autonomously, ignoring the human.
9. informs the human only if it, the computer decides, to
8. informs the human only if asked, or
7. executes automatically, then necessarily informs the human, and
6. allows the human a restricted time to veto before automatic execution, or
5. executed the suggestion if the human approves, or
4. suggests one alternative
3. narrows the selection down to a few, or
2. the computer offers a complete set of decision/action alternatives, or
1. the computer offers no assistance: human must take all decisions and actions.

LOW

Levels of automation of decision and action selection, adapted from: National Research Council. The future of air traffic control: Human operators and automation. National Academies Press; 1998 Feb 9

Autonomous cars



Level 0

No automation

Zero autonomy, the driver performs all driving tasks.

Level 1

Driver Assistance

Vehicle is controlled by the driver, but some driving assist features may be included in a vehicle design.

Level 2

Partial Automation

Vehicle has combined automated functions, like acceleration and steering, but the driver must remain engaged with the driving task and monitor the environment at all times.

Level 3

Conditional Automation

Driver is a necessity, but is not required to monitor the environment. The driver must be ready to take control of the vehicle at all time with notice.

Level 4

High Automation

The vehicle is capable of performing all driving functions under certain conditions. The driver may have the option to control the vehicle.

Level 5

Full Automation

The vehicle is capable of performing all driving functions under all conditions. The driver may have the option to control the vehicle.

Society of Automotive Engineers levels of autonomy, adapted from: Automation Levels for cars, SAE, <https://automotiveelectronics.com/sae-levels-cars/>

Agriculture



Guidance

All manned vehicles

Coordination & Optimization

All manned vehicles

Operator Assisted Autonomy

Manned back-up

Supervised Autonomy

In-field supervision of unmanned vehicles

Full Autonomy

No local supervision (Remote supervision or artificial intelligence)

CASE IH automation, adapted from: Categories of Autonomy and Announces Pilot Program, vCase IH, <https://www.caseih.com/emea/en-za/News/Pages/2018-02-14-Case-IH-Defines-Categories-of-Autonomy-and-Announces-Pilot-Program.aspx>

ASPARi approach

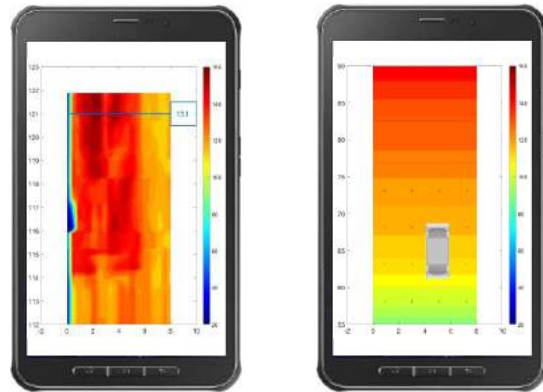
Level 0

No automation



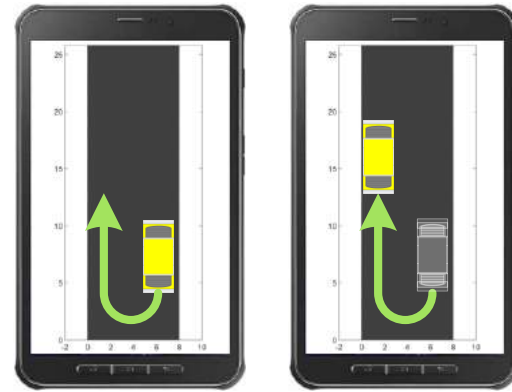
Level 1

Operator assistance with raw process related information (no guidance, engaged control)



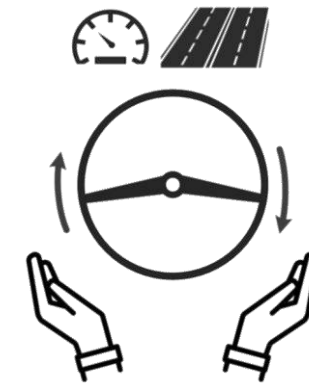
Level 2

Operator guidance during paving and compaction operations



Level 3

Semi-autonomous construction operations, disengaged control of machine operators



Level 4

Autonomous construction operations, disengaged monitoring of machine operators



ASPARi approach

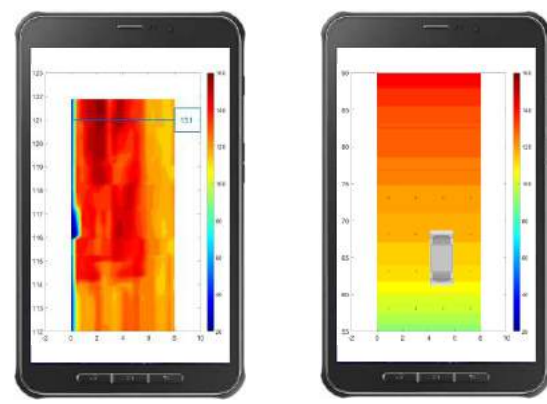
Level 0
No automation



Transition

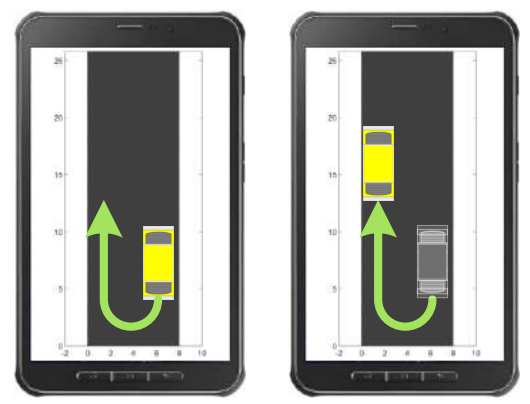
Level 1

Operator assistance with raw process related information (no guidance, engaged control)



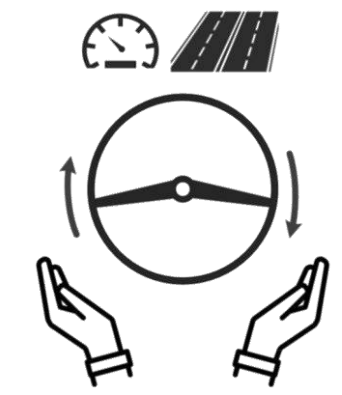
Level 2

Operator guidance during paving and compaction operations



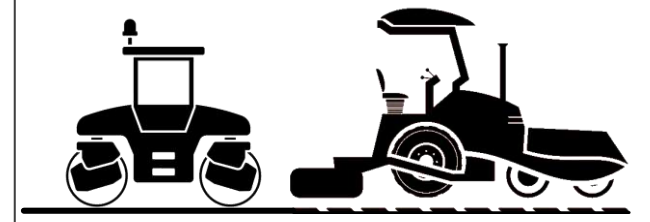
Level 3

Semi-autonomous construction operations, disengaged control of machine operators



Level 4

Autonomous construction operations, disengaged monitoring of machine operators

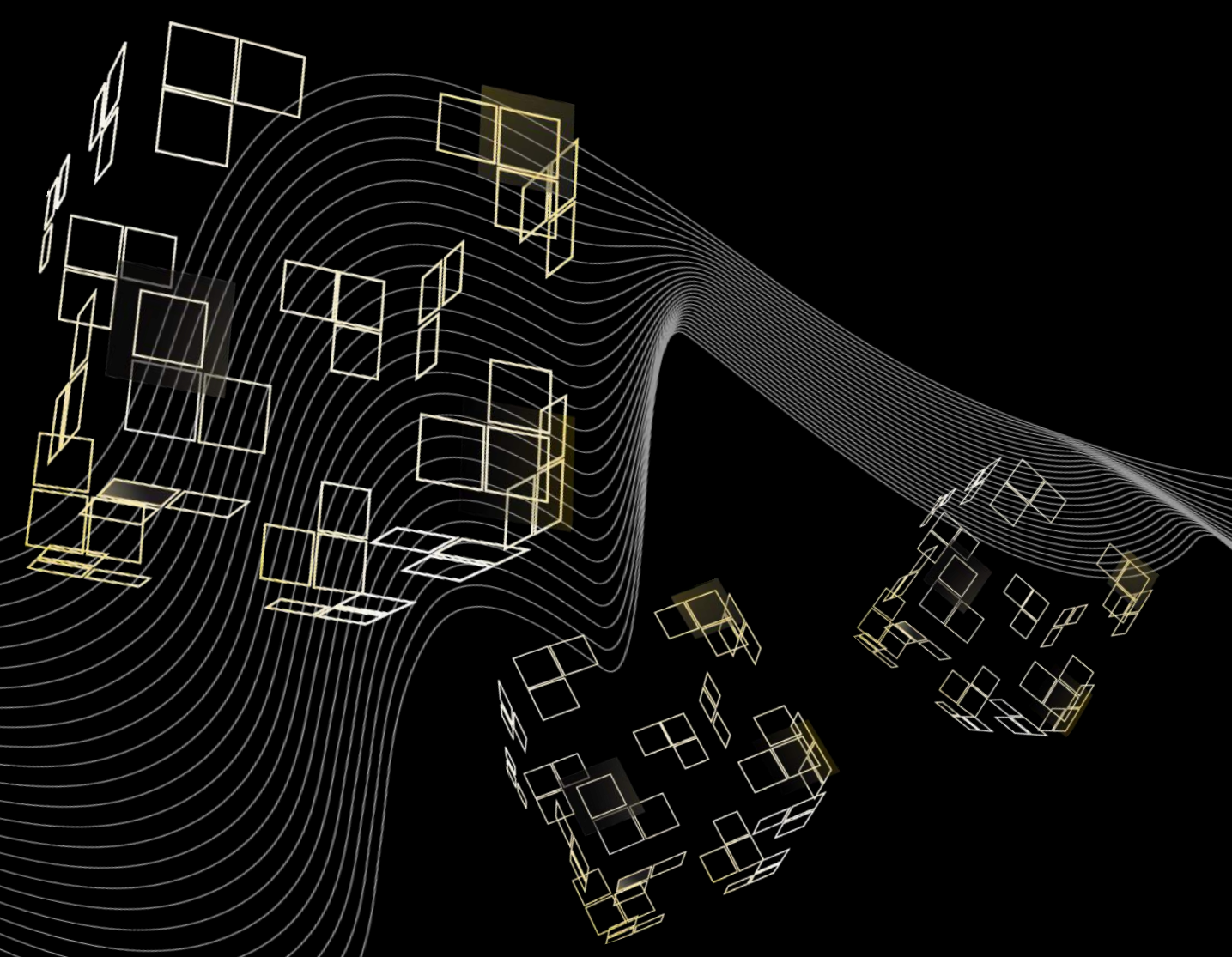


Human role



- User experience
- User interface
- Information overload
- Reliability
- Building trust
- Functionality
- ..and changing role of operators

Thank you for your
attention!





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A comparative Life Cycle Assessment of Traditional and Cement Treated Recycled Road Pavement Base

Student

Michele Primavera

Supervisors

Dr. Joao Santos - Dr. Sara Bressi

CONTENT

PROBLEM STATEMENT

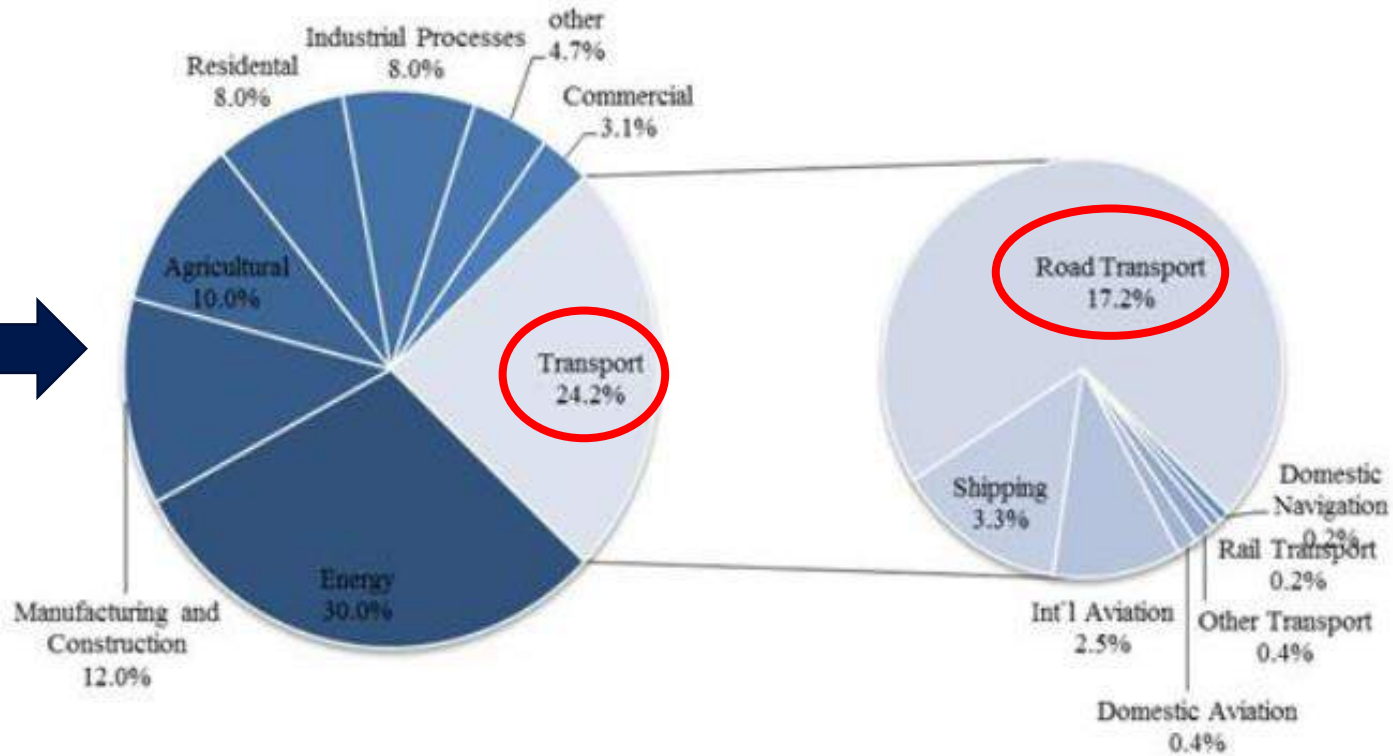
INTRODUCTION

CASE STUDY

RESULTS

FUTURE WORK

The transportation sector generates enormous amount of airborne emission



EU27 greenhouse gas emissions by sector and mode of transport, 2007 (EU, 2014)

Benefits of Being More Sustainable

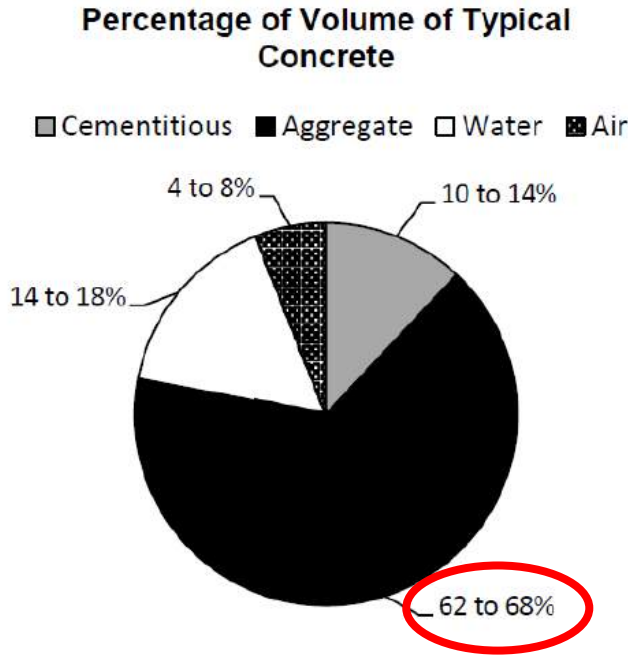
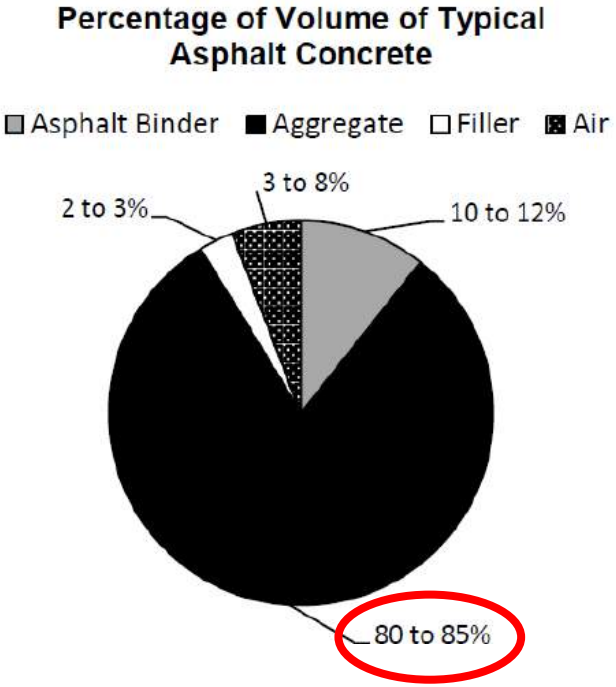


- Reduced pavement life-cycle costs

- Reduced energy
- Reduced noise
- Improved air quality



- Improved safety
- Improved ride
- Conservation of resources



Source: Tayabji, Smith, and Van Dam 2010

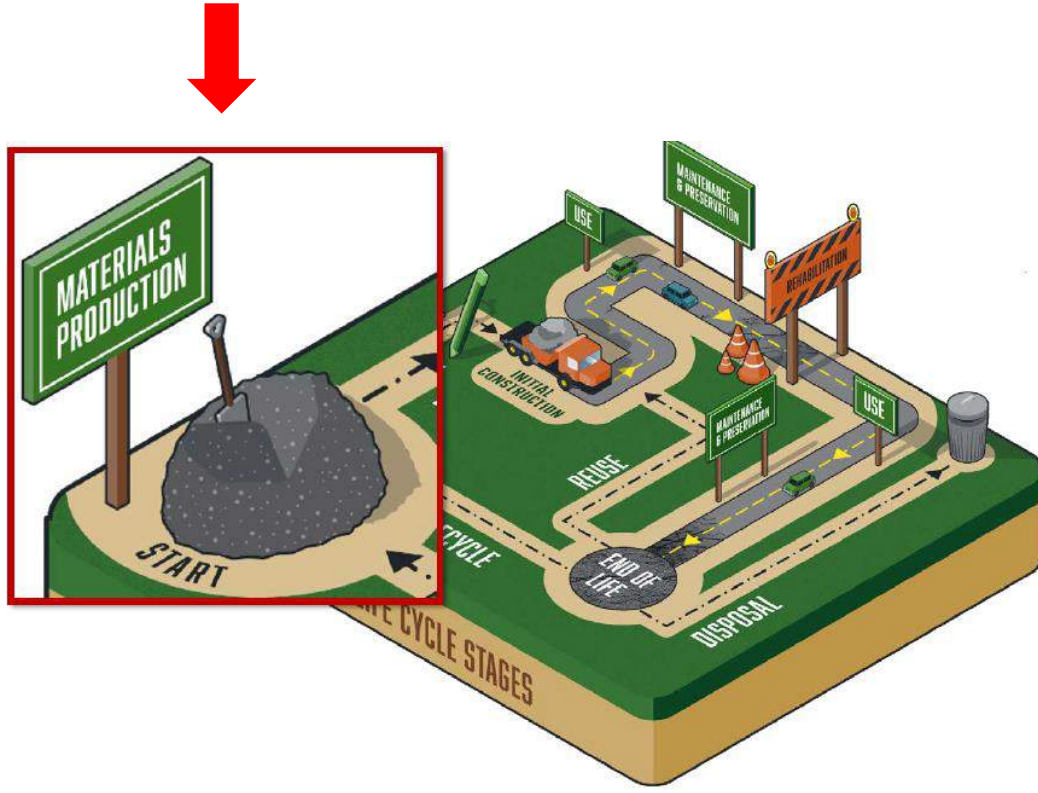


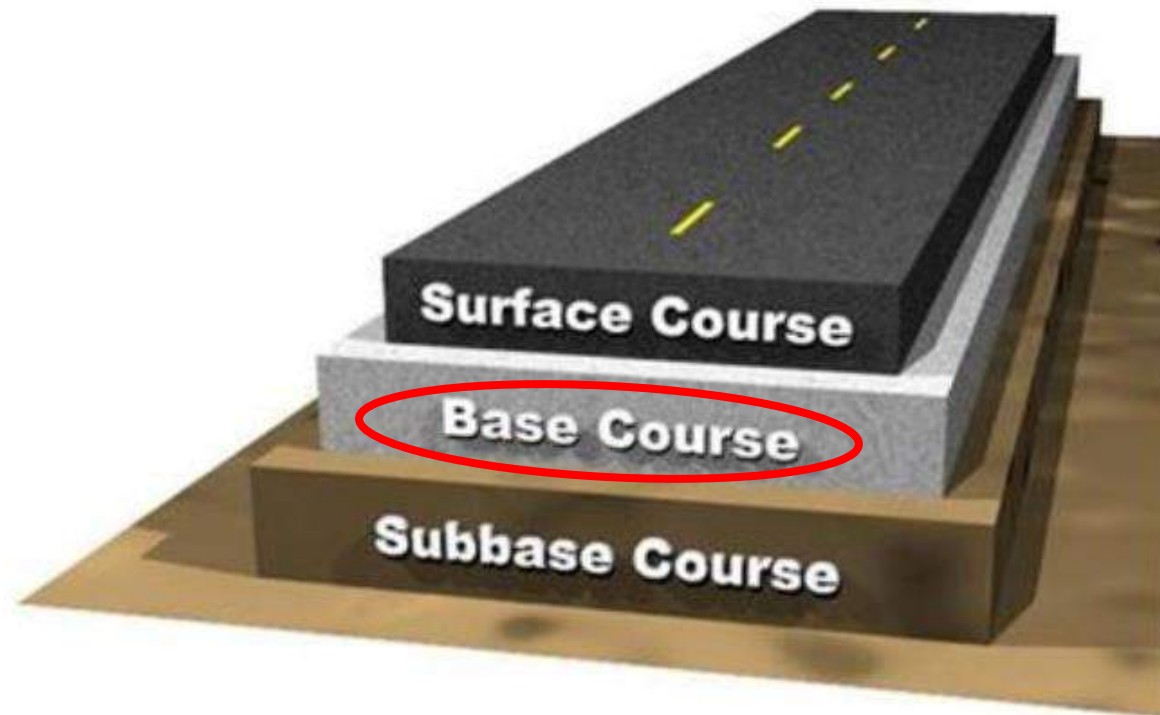
Image Source: FHWA/APTech

Is it always environmentally beneficial to use recycled materials to replace the virgin aggregates?



In this study the layer in pavement road structure that we'll consider is:

CEMENT TREATED BASE COURSE



Cement Treated Base course consists of a uniform mixture of :

Cement Treated Base



VIRGIN AGGREGATE



Or

RAP

(Reclaimed Asphalt Pavement)



CEMENT



WATER



IN PLANT PRODUCTION

CTB PRODUCTION



Mixing in central plant



Transport



Placing



Slope finishing



Compaction



Bitumen emulsion spreading

IN PLACE PRODUCTION

CTB PRODUCTION



Transport



Placing



Cement spreading



Water spreading



Mixing



Slope finishing



Compaction



Bitumen emulsion spreading

The objective of the work is the comparison, in terms of environmental impact, between:

- *In Plant and In Place Production*
- *CTB (with 100% of Virgin Aggregate) and CTRB (with 100% of RAP)*



The methodology used to assess the environmental impacts is:

Life Cycle Assessment

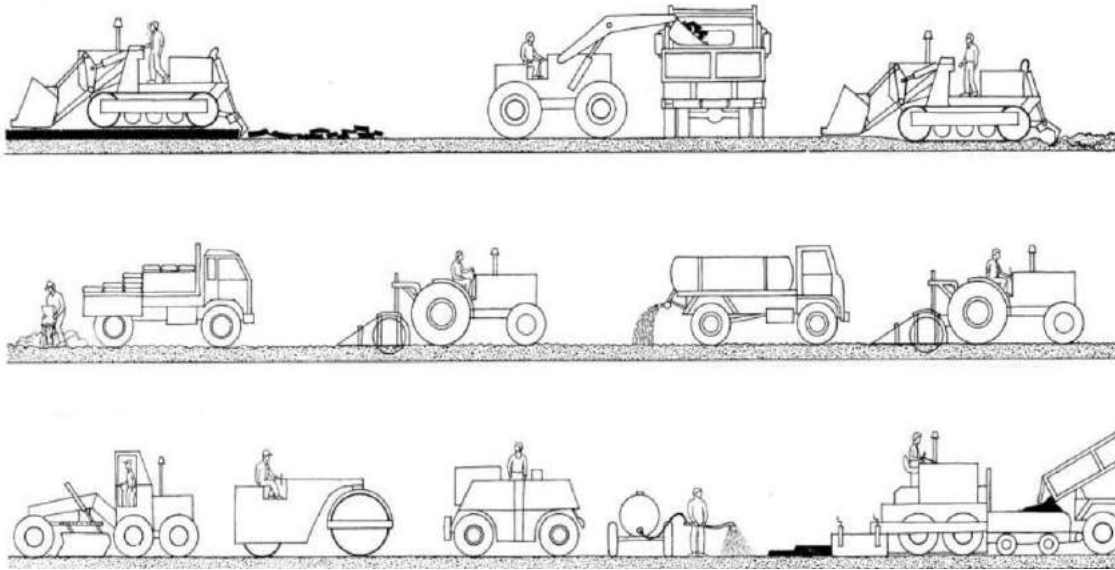


Software program

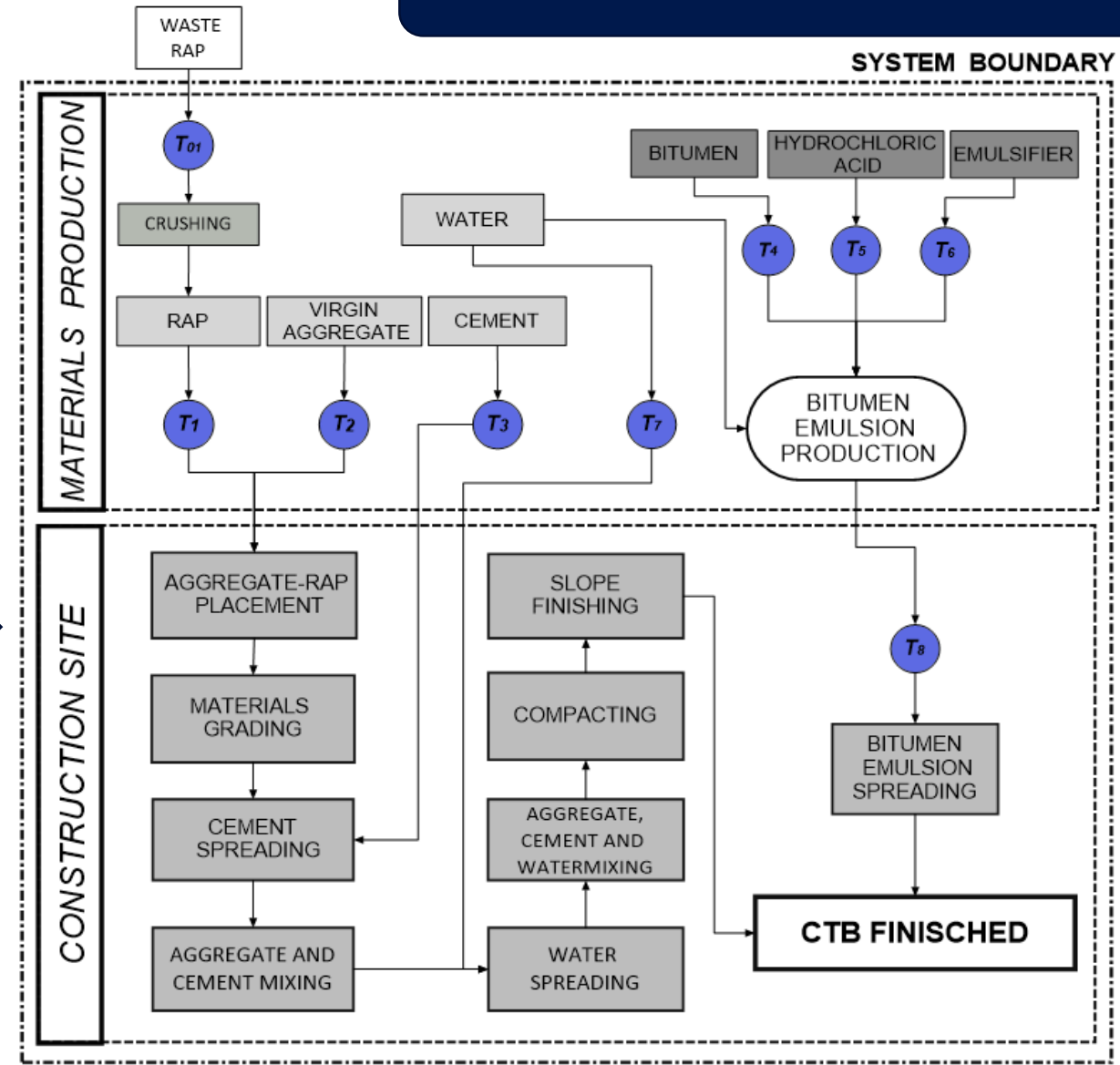


https://edificacionsostenible.saint-gobain.es/certification/breeames-2015/aislamiento-para-suelos/mat-1-impactos-de-ciclo-de-vida?language_content_entity=es#

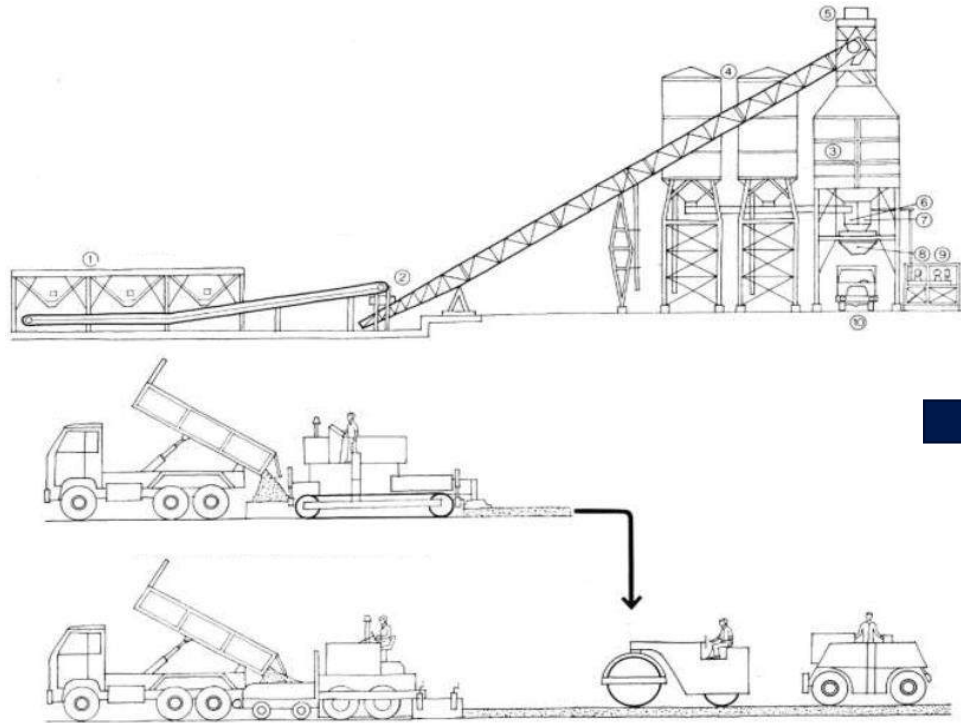
IN PLACE PRODUCTION



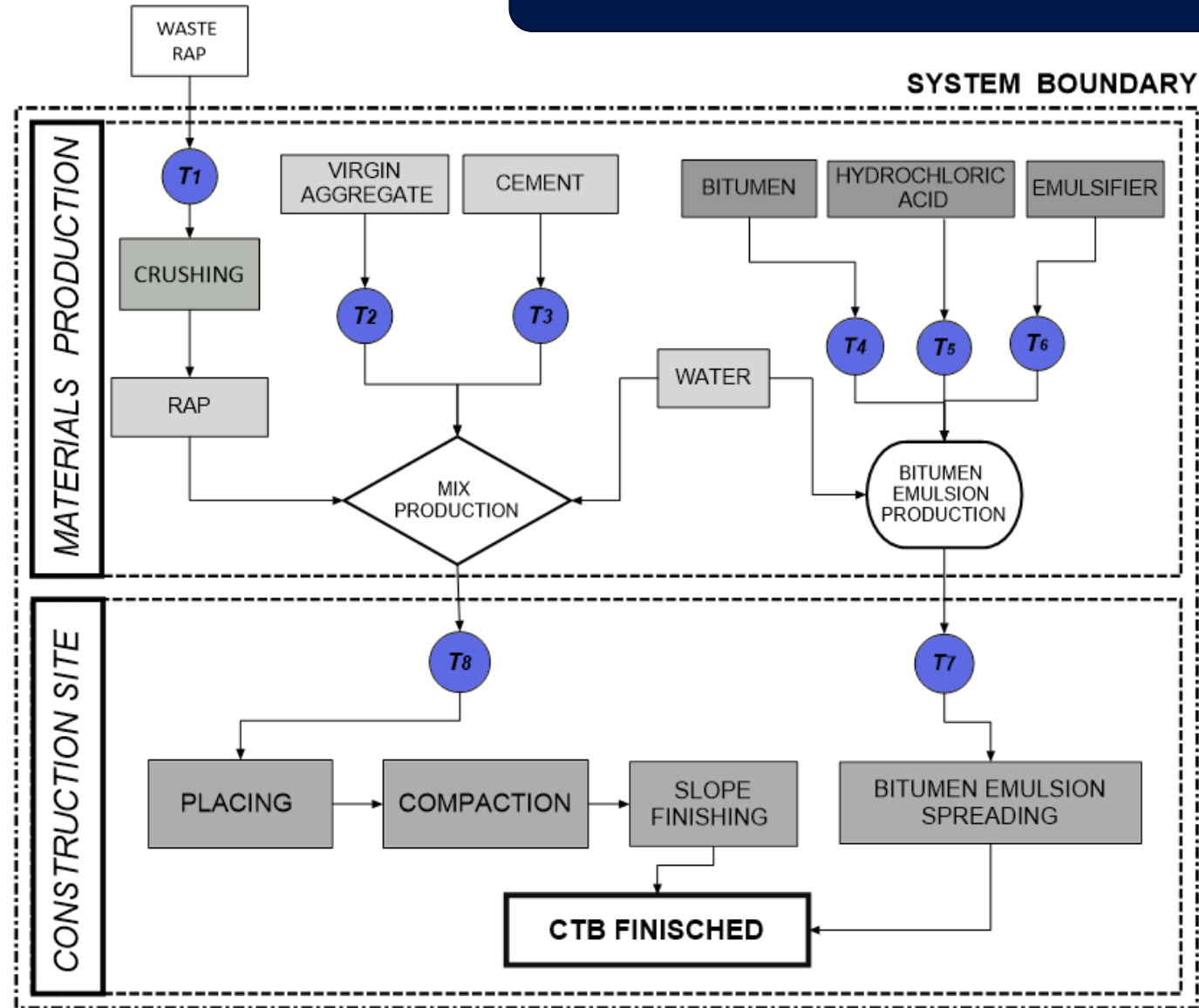
SYSTEM BOUNDARIES



IN PLANT PRODUCTION



SYSTEM BOUNDARIES



Based on a laboratory test, a pavement design was conducted to determinate the thickness of the layer for each mixture.

INPUT DATA

Table 3. Flexible Pavement Design Conditions

Category	Condition
Pavement type	Major city streets and thoroughfares and country highways
Total equivalent 18-kip single axle loads ($ESAL_{18-kip}$)	2,028,404
Analysis period	30 years
Design period	20 years
Initial pavement serviceability index (P_0)	4.2
Terminal pavement serviceability index (P_t)	2.5
Reliability (R)	90%
Overall standard deviation (S_0)	0.35



PAVEMENT DESIGN ANALYSIS

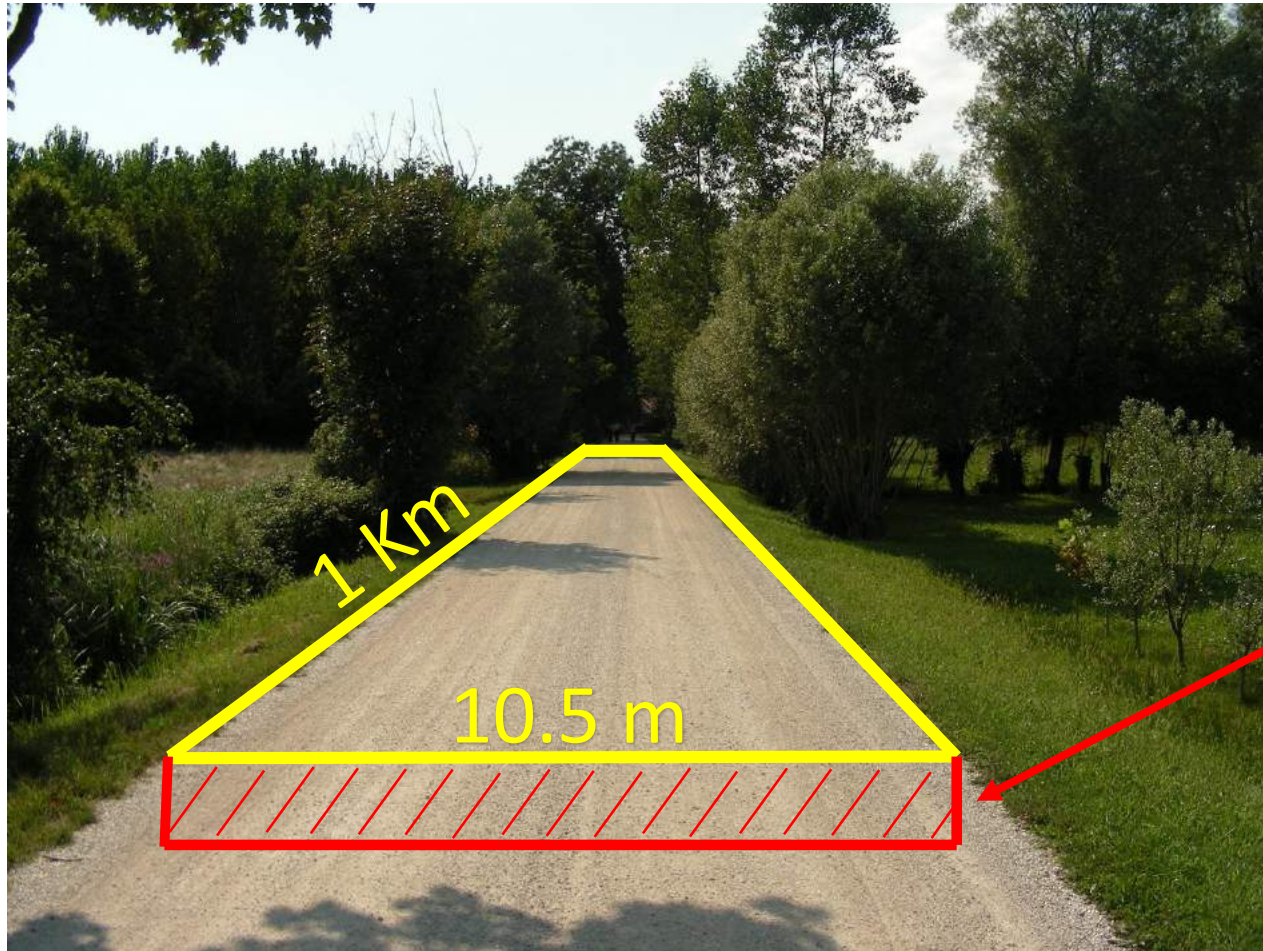
Table 6. Results of Pavement Design Analysis

Base material		Thickness (mm)		
		Surface	Base	Subbase
<u>100% virgin aggregate</u>	+0% cement	127	127	114
	+3% cement	76	241	114
	+5% cement	76	191	114
	+7% cement	76	165	114
<u>100% RAP^a</u>	+0% cement	178	0	89
	+3% cement	76	343	114
	+5% cement	76	318	114
	+7% cement	76	292	114
90% RAP ^a	+0% cement	165	13	114
	+3% cement	76	318	114
	+5% cement	76	292	114
	+7% cement	76	292	114
80% RAP ^a	+0% cement	165	51	114
	+3% cement	76	292	114
	+5% cement	76	292	114
	+7% cement	76	280	114
70% RAP ^a	+0% cement	152	76	114
	+3% cement	76	292	114
	+5% cement	76	280	114

+ 102 mm

^aReclaimed asphalt pavement.

Ramzi Taha, A.M.ASCE, Ali Al-Harthy, Khalid Al-Shamsi and Muamer Al-Zubeidi (2002).



LENGTH = 1KM

WIDTH = 10.5m

THICKNESS= variable

100% VIRGIN AGGREGATE - 5%CEMENT

IMPACT	IN PLACE	IN PLANT	Unit
Ac	392.39523	575.6014	kg SO2 eq.
PO	16.48638	24.91602	kg ethylene eq.
CC	1.79E+05	2.23E+05	kg CO2 eq.
OLD	0.01385	0.01879	kg CFC-11 eq.
DAR-FF	1.26E+06	1.80E+06	MJ
Eu	96.19581	146.01721	kg PO4--- eq.
MAE	3.67E+07	7.78E+07	kg 1,4-dichlorobenzene eq.
TE	846.9613	952.38532	kg 1,4-dichlorobenzene eq.
FAE	1.27E+04	2.28E+04	kg 1,4-dichlorobenzene eq.
DAR-E	0.054	0.12069	kg antimony eq.
HT	2.29E+04	3.98E+04	kg 1,4-dichlorobenzene eq.

Central Plant Production			
IMPACT	100% VIRG AGGR	100% RAP	Unit
Ac	575.6014	738.94112	kg SO2 eq.
PO	24.91602	31.4999	kg ethylene eq.
CC	2.23E+05	3.05E+05	kg CO2 eq.
OLD	0.01879	0.01956	kg CFC-11 eq.
DAR-FF	1.80E+06	2.08E+06	MJ
Eu	146.01721	194.01068	kg PO4--- eq.
MAE	7.78E+07	1.07E+08	kg 1,4-dichlorobenzene eq.
TE	952.38532	1041.78616	kg 1,4-dichlorobenzene eq.
FAE	2.28E+04	3.06E+04	kg 1,4-dichlorobenzene eq.
DAR-E	0.12069	0.14253	kg antimony eq.
HT	3.98E+04	4.63E+04	kg 1,4-dichlorobenzene eq.

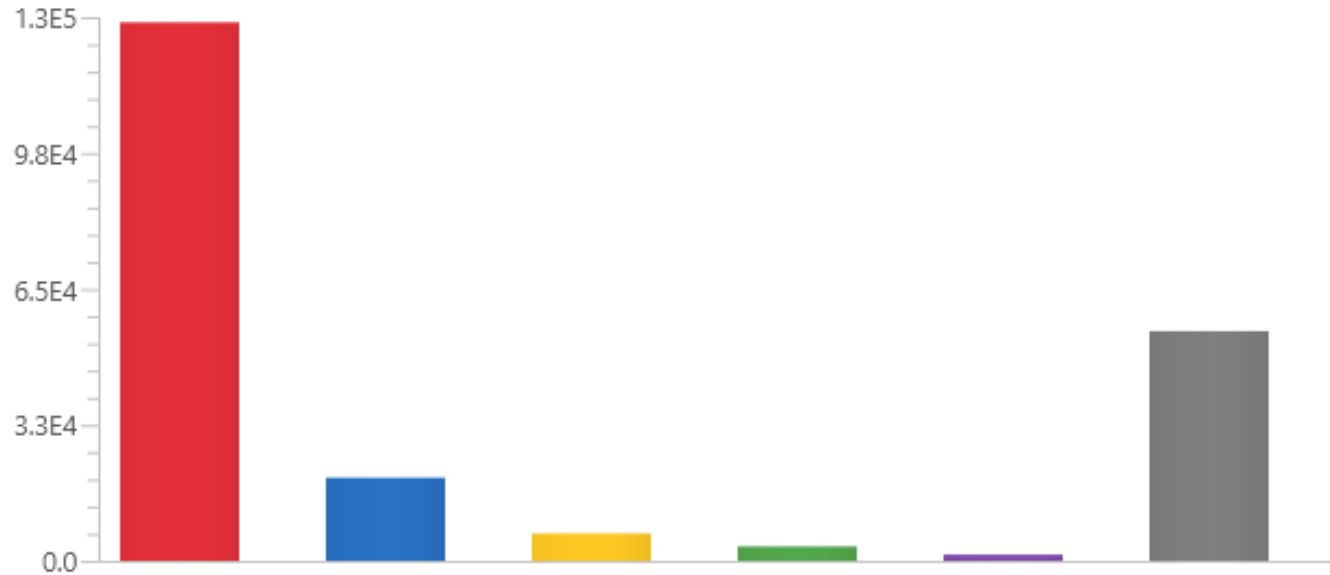


Toxicity

CTRB (100% RAP) - CTB (100% VIRGIN AGGREGATE)

LCA

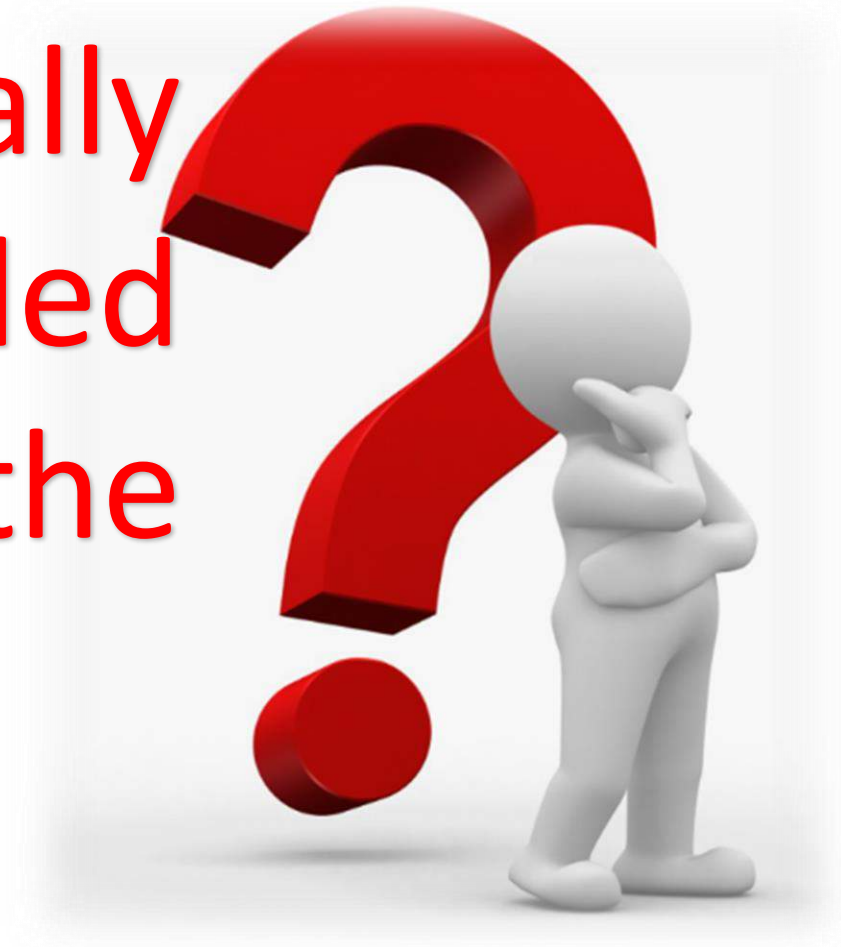
Impact category: Climate change - GWP100



- 1.288E5 kg CO2 eq. → CLINKER PRODUCTION
- 1.988E4 kg CO2 eq.
- 6.559E3 kg CO2 eq.
- 3.444E3 kg CO2 eq.
- 1.487E3 kg CO2 eq.
- 5.494E4 kg CO2 eq.

TOTAL AMOUNT OF CEMENT	
TRADITIONAL BASE	RECYCLED BASE
214 ton	306 ton

Is it always environmentally beneficial to use recycled materials to replace the virgin aggregates?



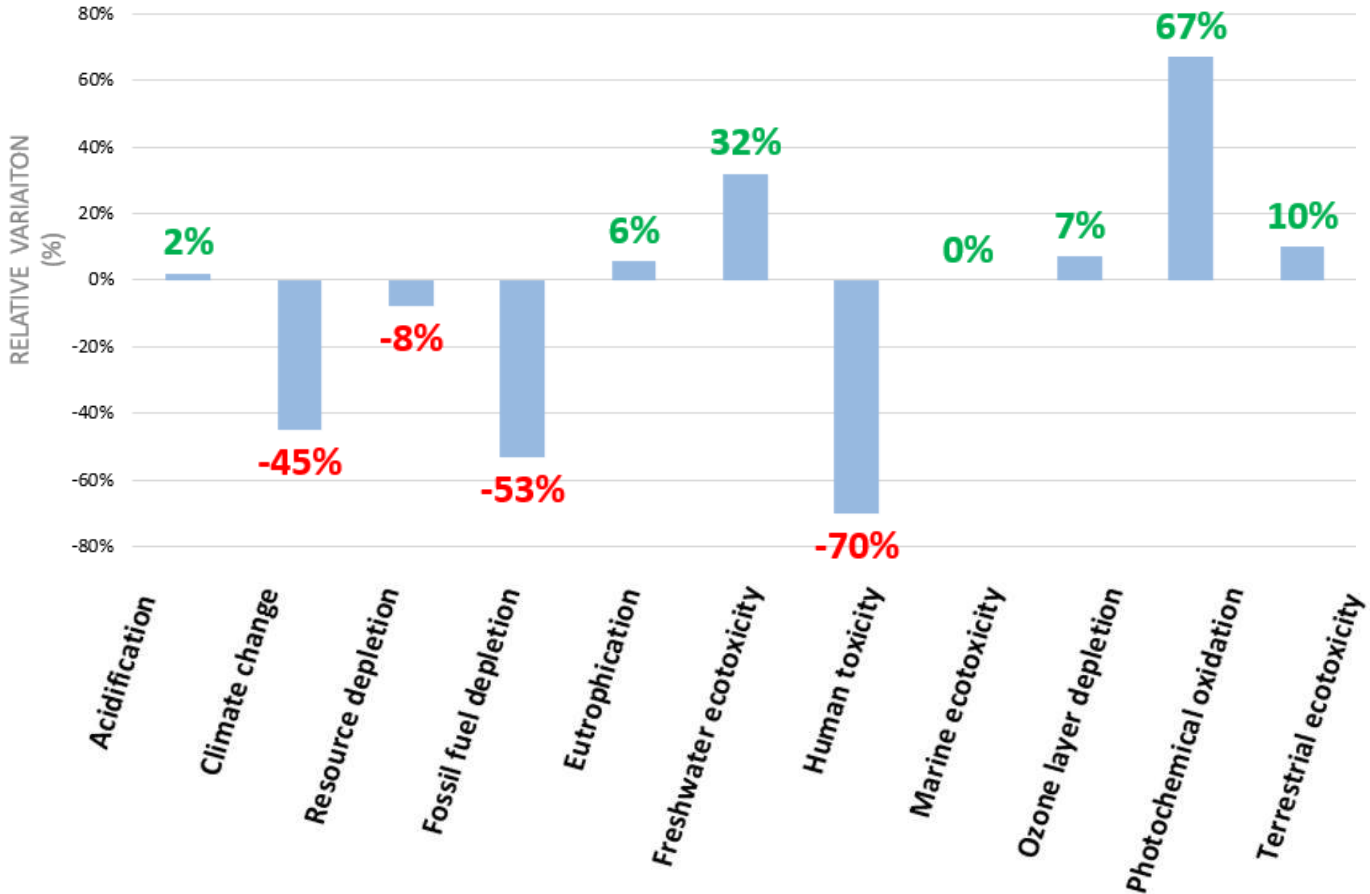
ANSWER

ENVIRONMENTAL IMPACT

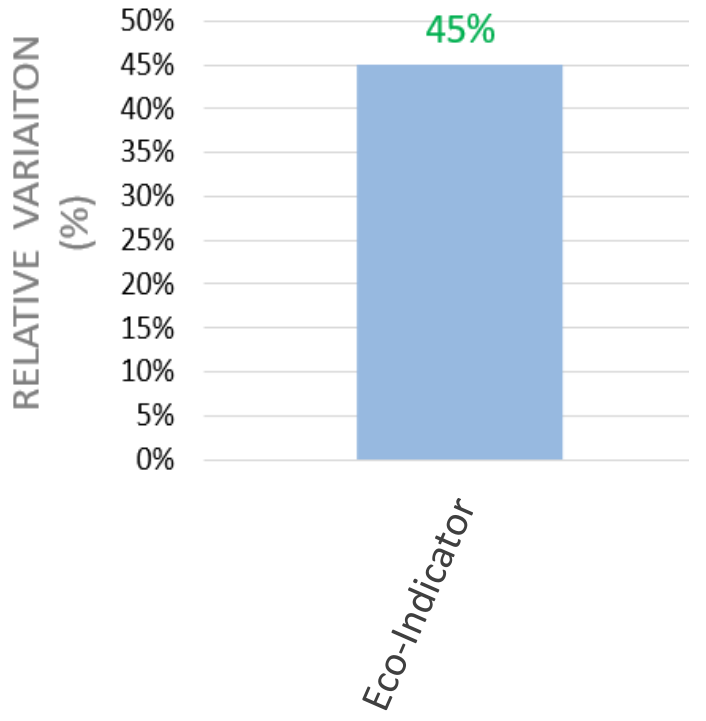
NO!!!

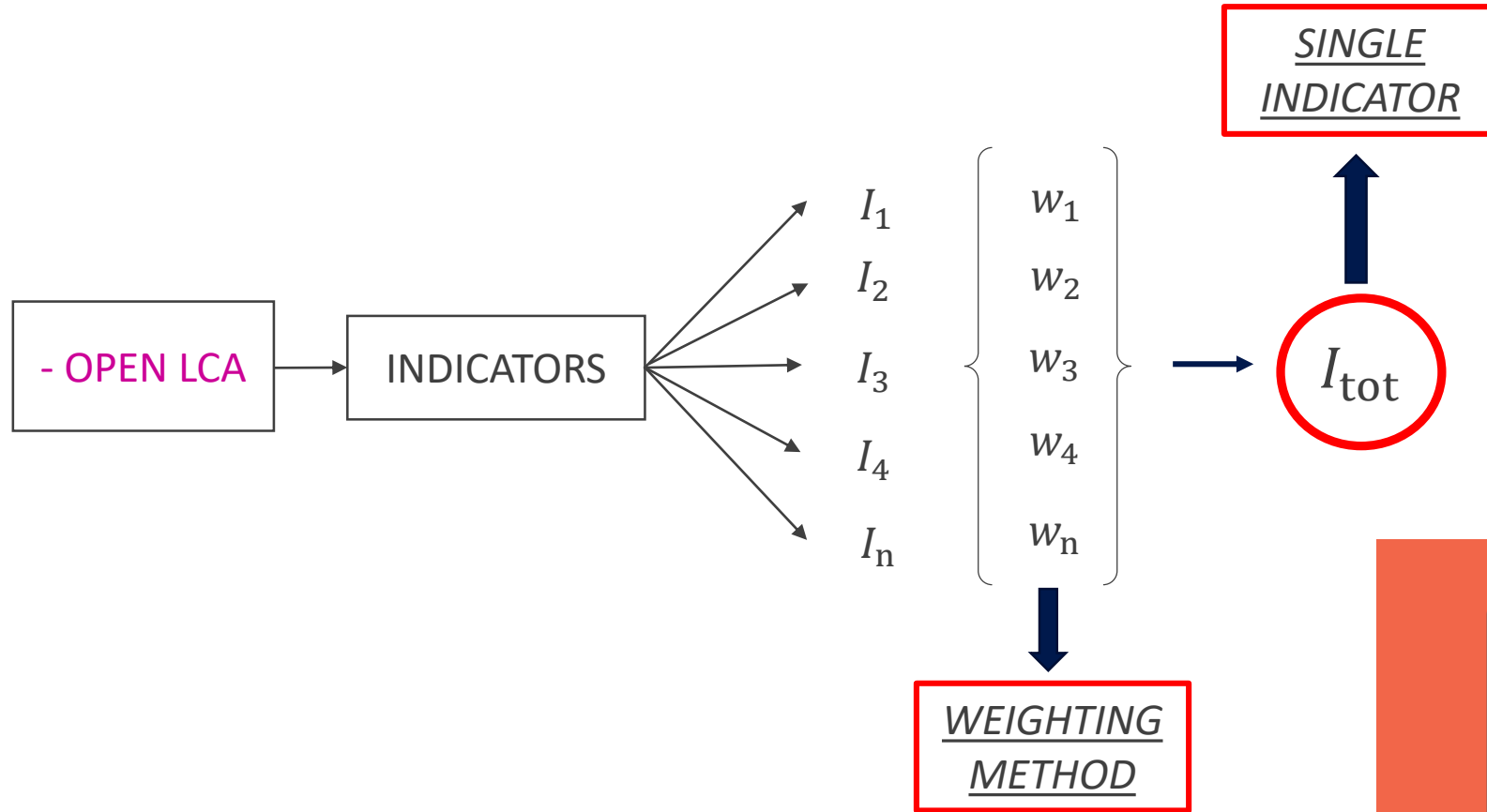


Which alternative to choose?



SINGLE INDICATOR

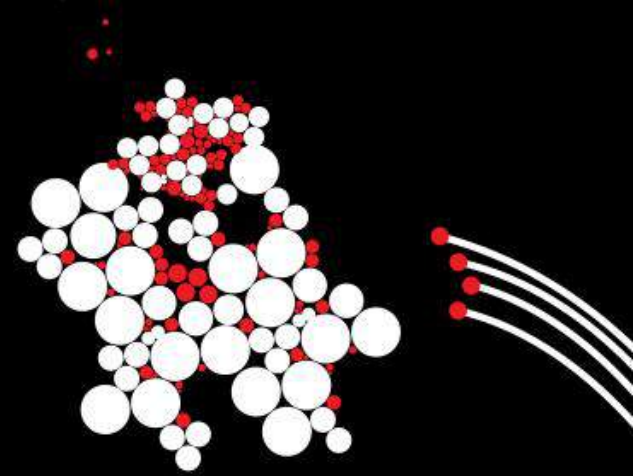




THE END !!!



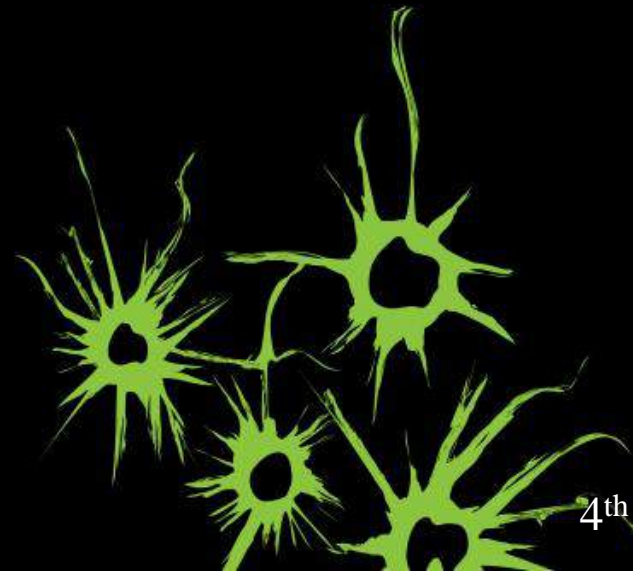
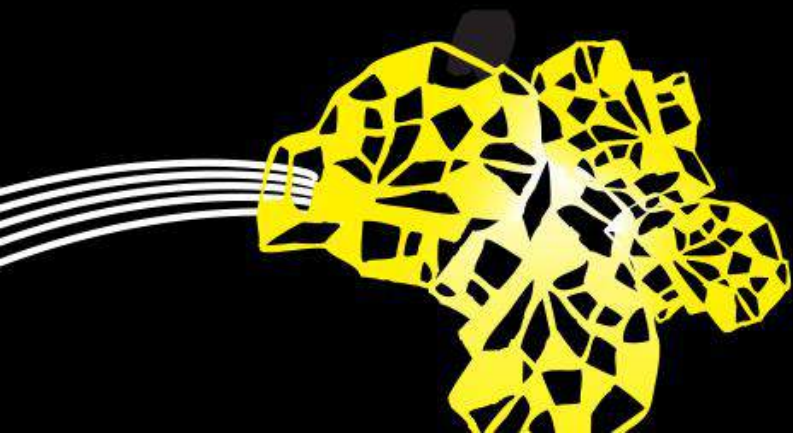
UNIVERSITY OF TWENTE.



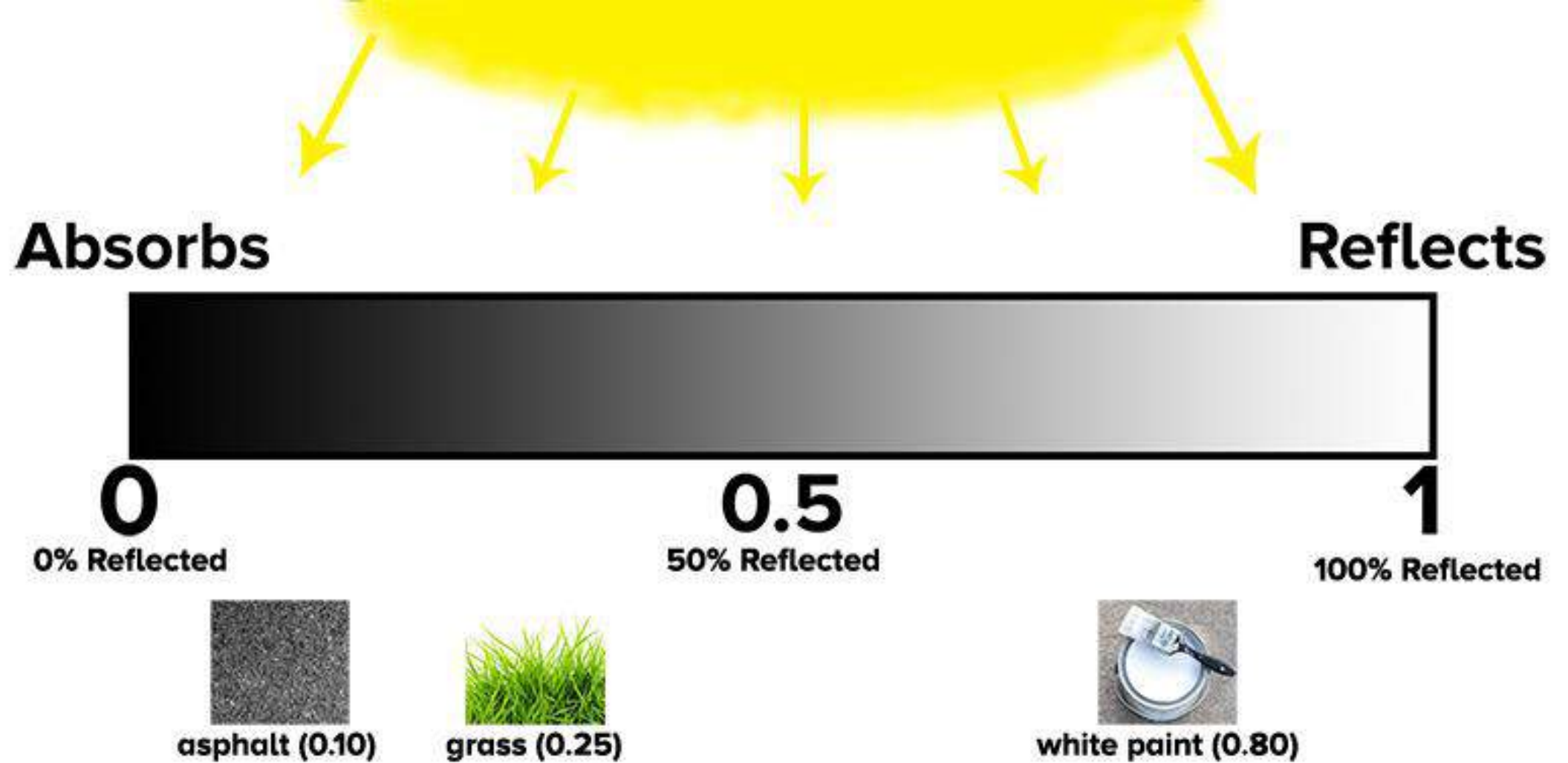
Reflectivity, roads, and urban climates.

M. Pena Acosta (Monik)

PhD Researcher

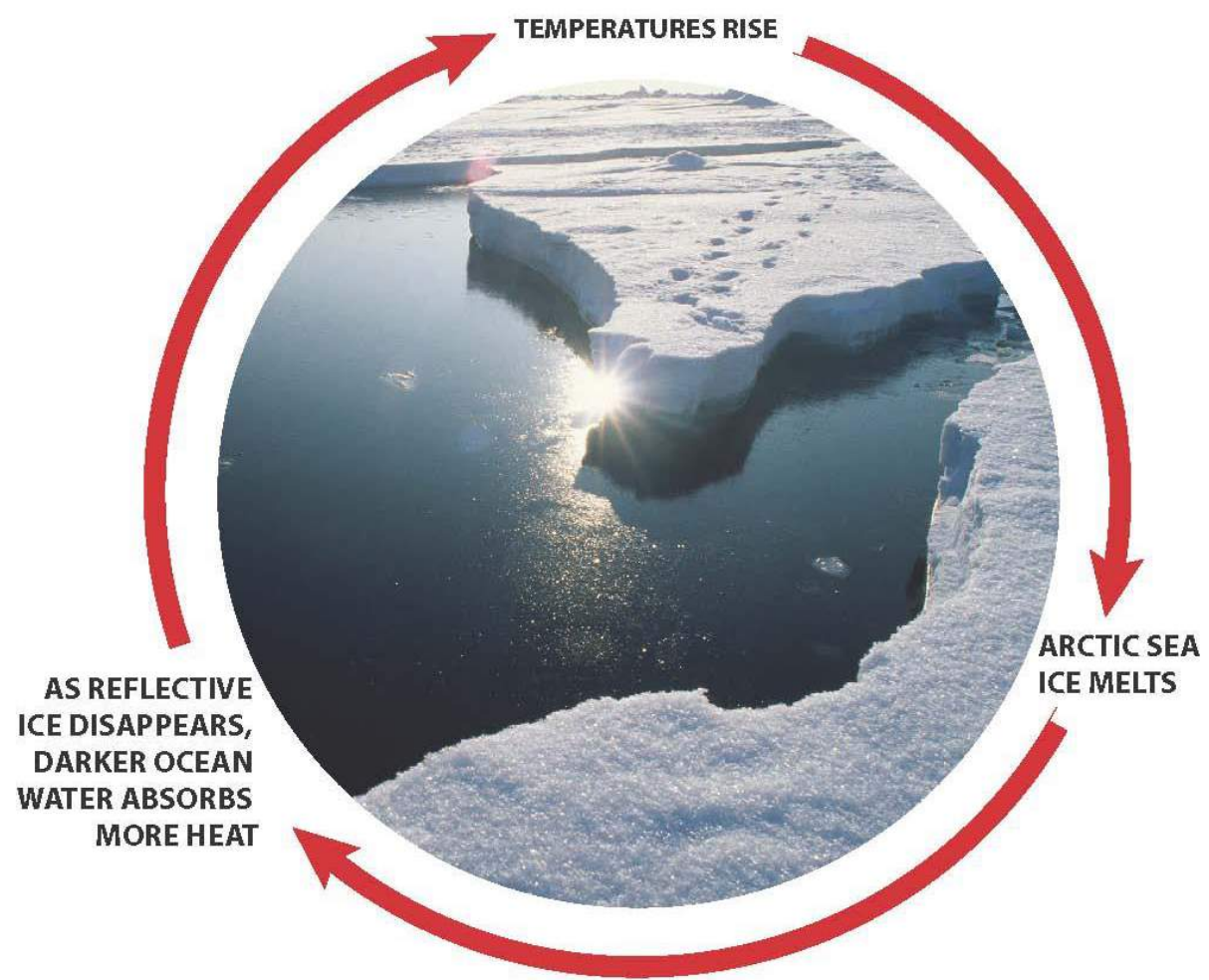


4th of December 2019



Albedo

<http://www.nc-climate.ncsu.edu/edu/Albedo>

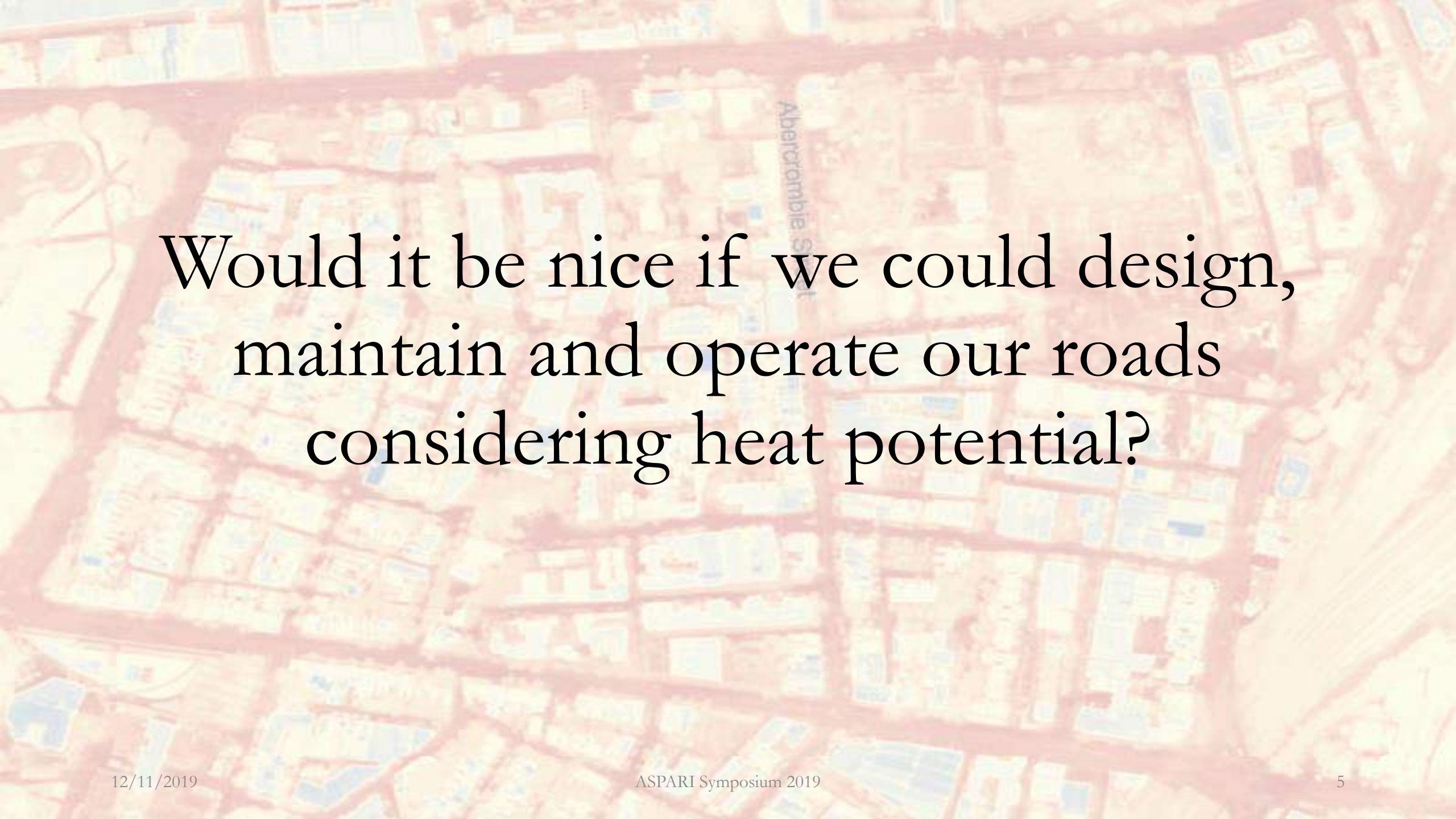


Surface albedo feedbacks

Ice is very reflective, some of the solar energy is reflected back to space



Urban climates

An aerial photograph of a city street grid, overlaid with a semi-transparent red filter. The streets are clearly visible, and the text is centered over the grid. A vertical street name, "Albercrombie St", is visible in the background.

Would it be nice if we could design,
maintain and operate our roads
considering heat potential?





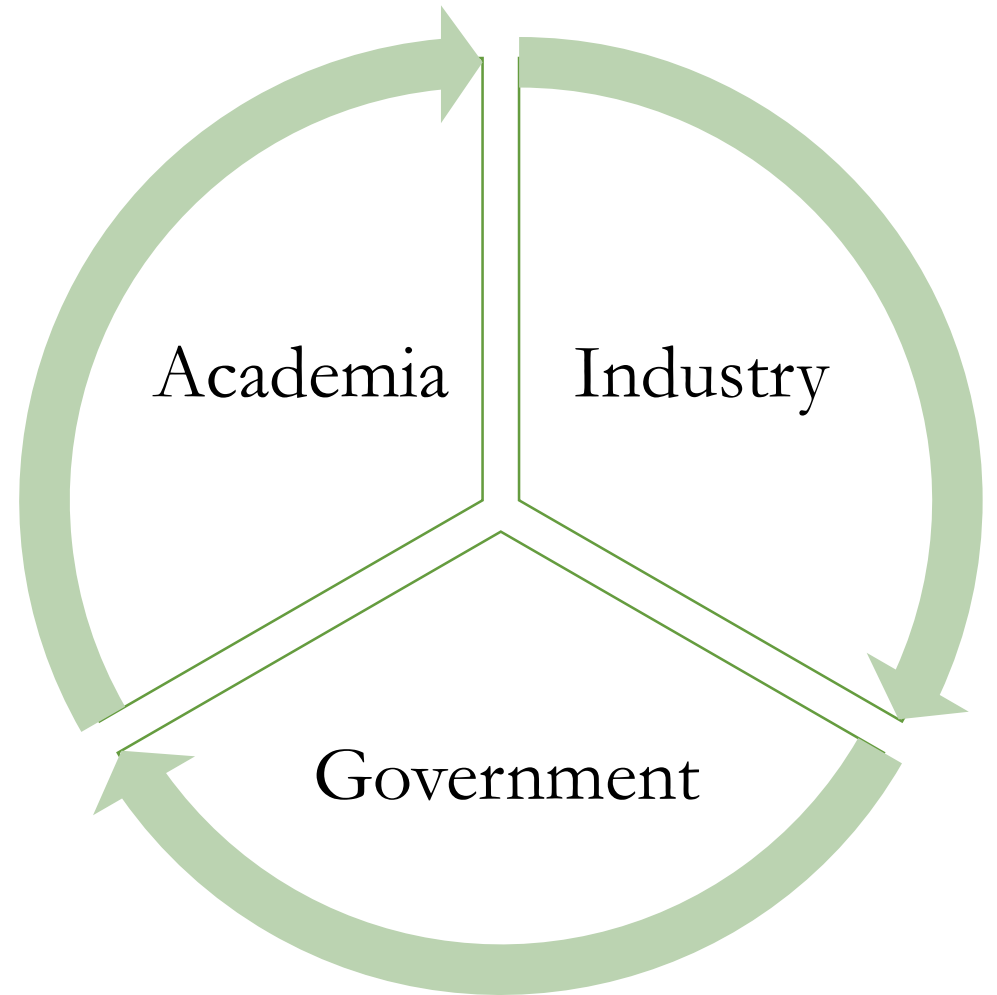
Challenges

- Local climate
- Climate change
- Urban geometry
- Materials
- Policies

Evaluating the impacts of pavement albedo is complicated.

Data-driven techniques are a potential solution





Experimental set-up



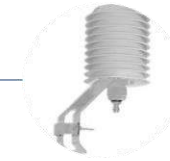
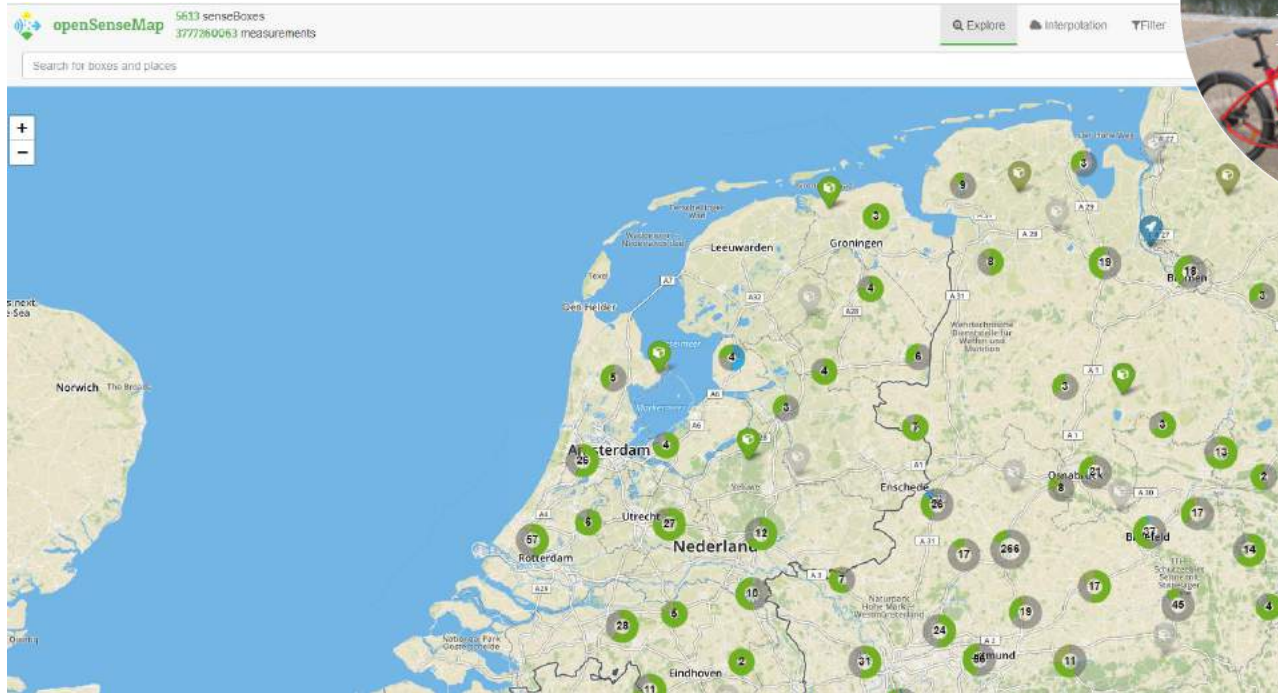
Air temperature

	A	B	C
1	Create a street profile		
2	Location	Latitude	Altitude
3	Width of street	cm	
4	Sky view factor	0-1	
5	Average height of building	cm	
6	Vegetation	0-1	
7	Materials of façade		
8	Others		
9			



Road surface temp

Experimental set-up

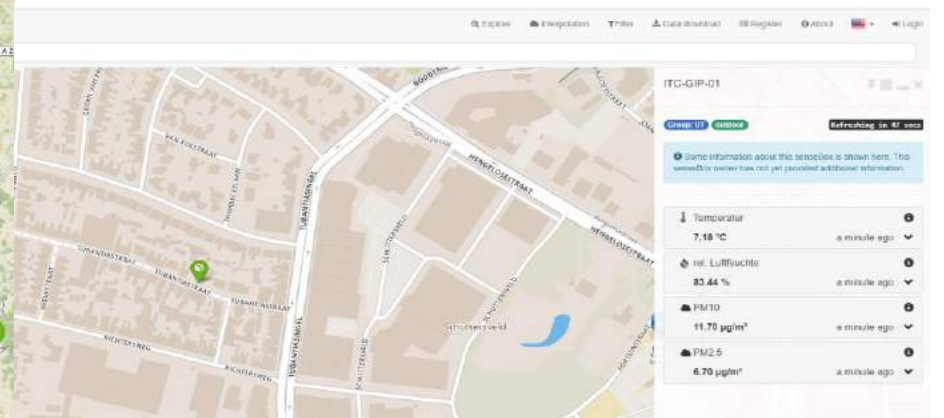


Air temperature

	A	B	C
1	Create a street profile		
2	Location	Latitude	Altitude
3	Width of street	cm	
4	Sky view factor	0-1	
5	Average height of building	cm	
6	Vegetation	0-1	
7	Materials of façade		
8	Others		
9			



Road surface temp

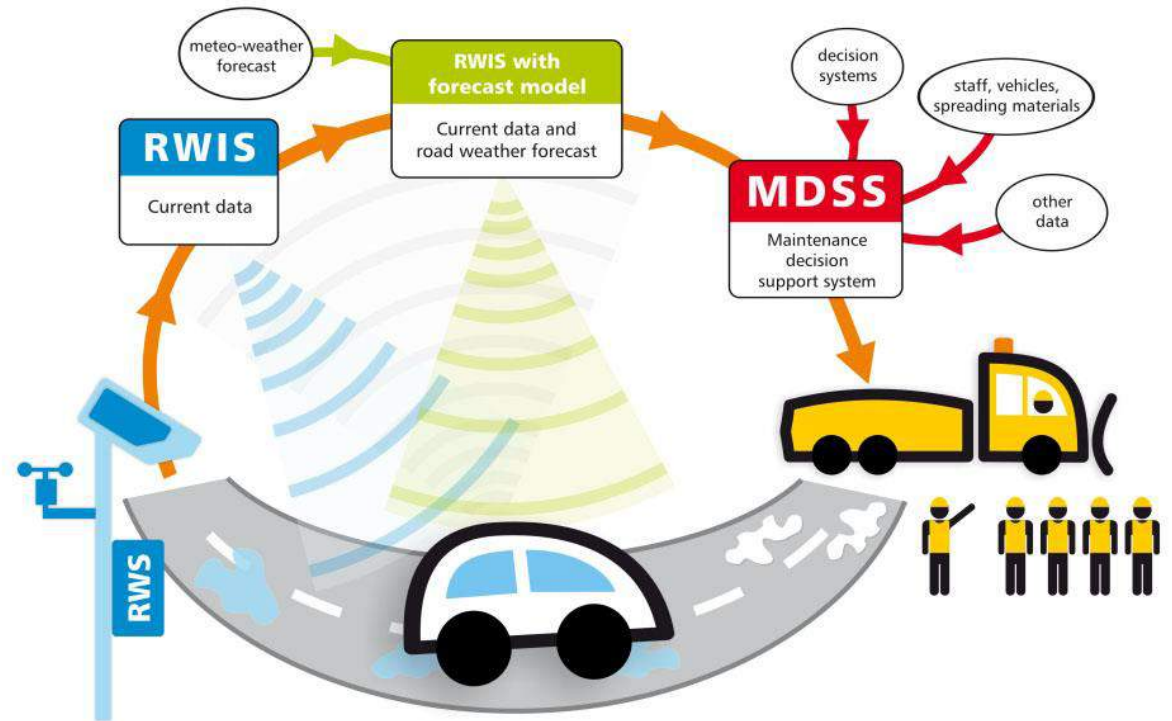


Not enough

Road safety and weather information system

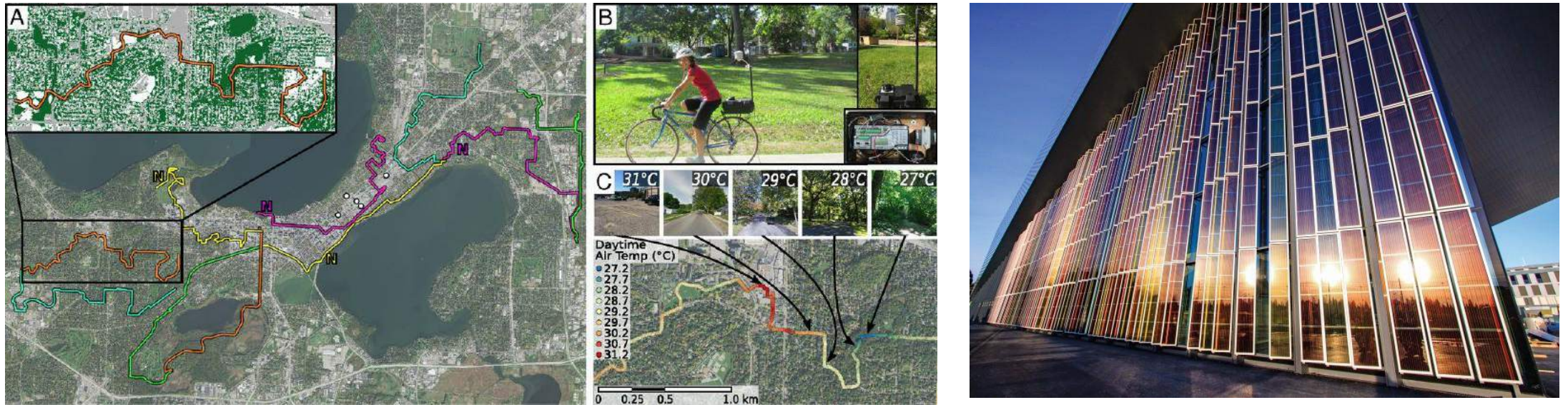


From the SWOV Institute for Road Safety Research



Road weather stations (RWSs) collect current weather data

Inter-academic collaboration



Share knowledge and expertise with researchers from Canada
Could we lower the solar panels?

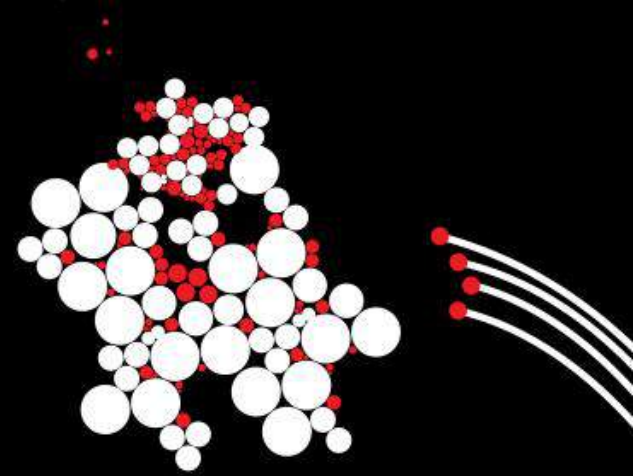
We can design, maintain and operate our roads in terms of heat potential



Take-home message

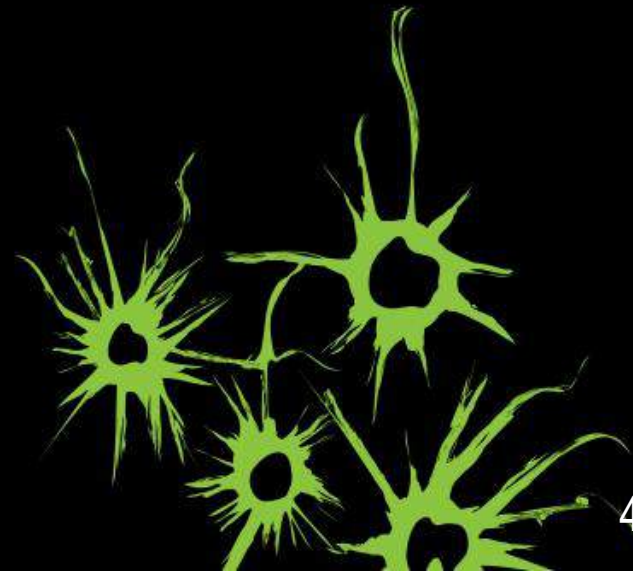
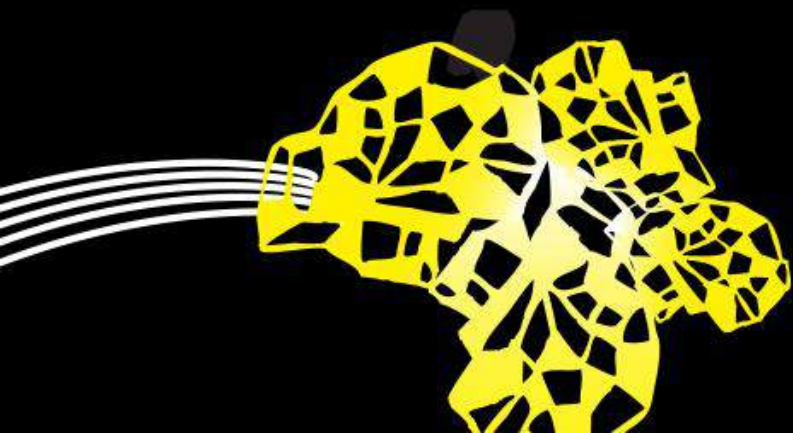
**From your expertise, what do we have already
that we can implement to cool our roads?**

UNIVERSITY OF TWENTE.



THANK YOU!

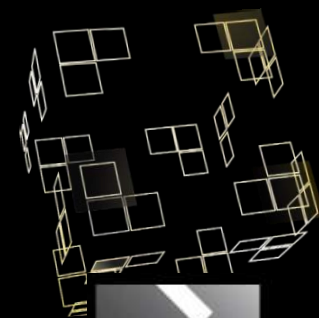
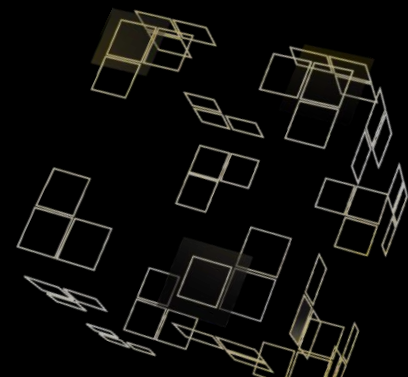
m.penaacosta@utwente.nl



4th of December 2019



DE ONTWIKKELING VAN INNOVATIEVE LESMATERIALEN VOOR HBO-WEGENBOUW

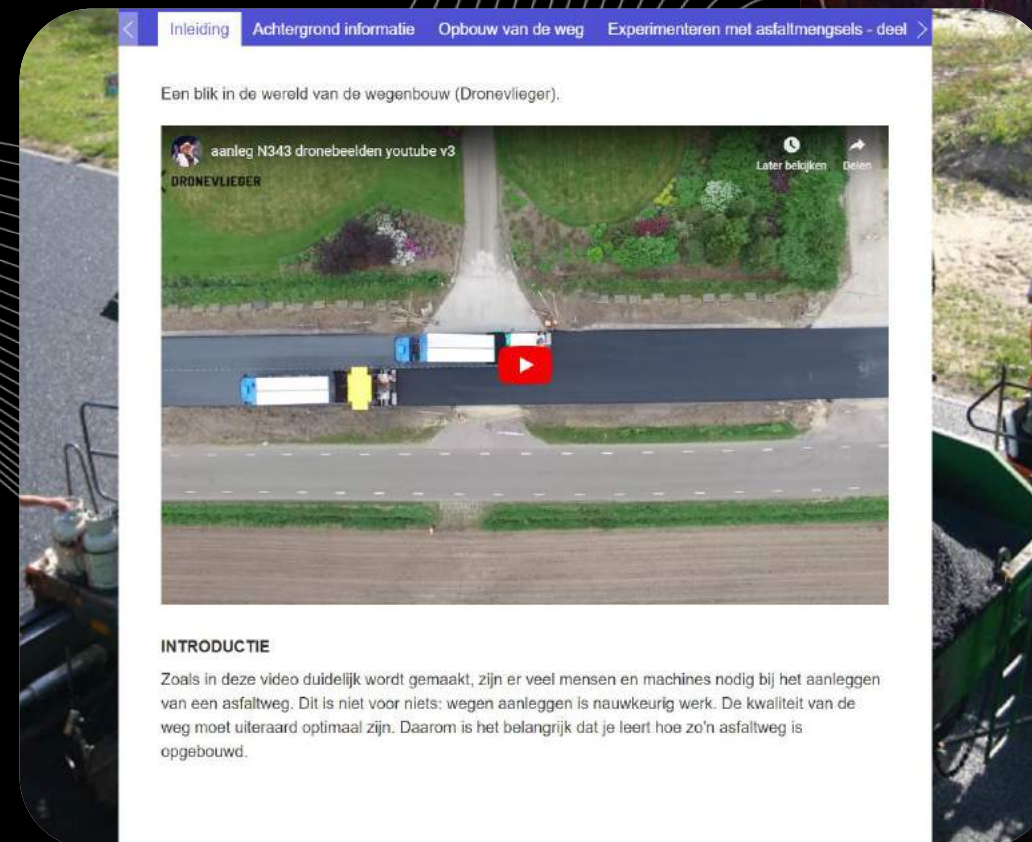


ASPARi
Paving the way forward

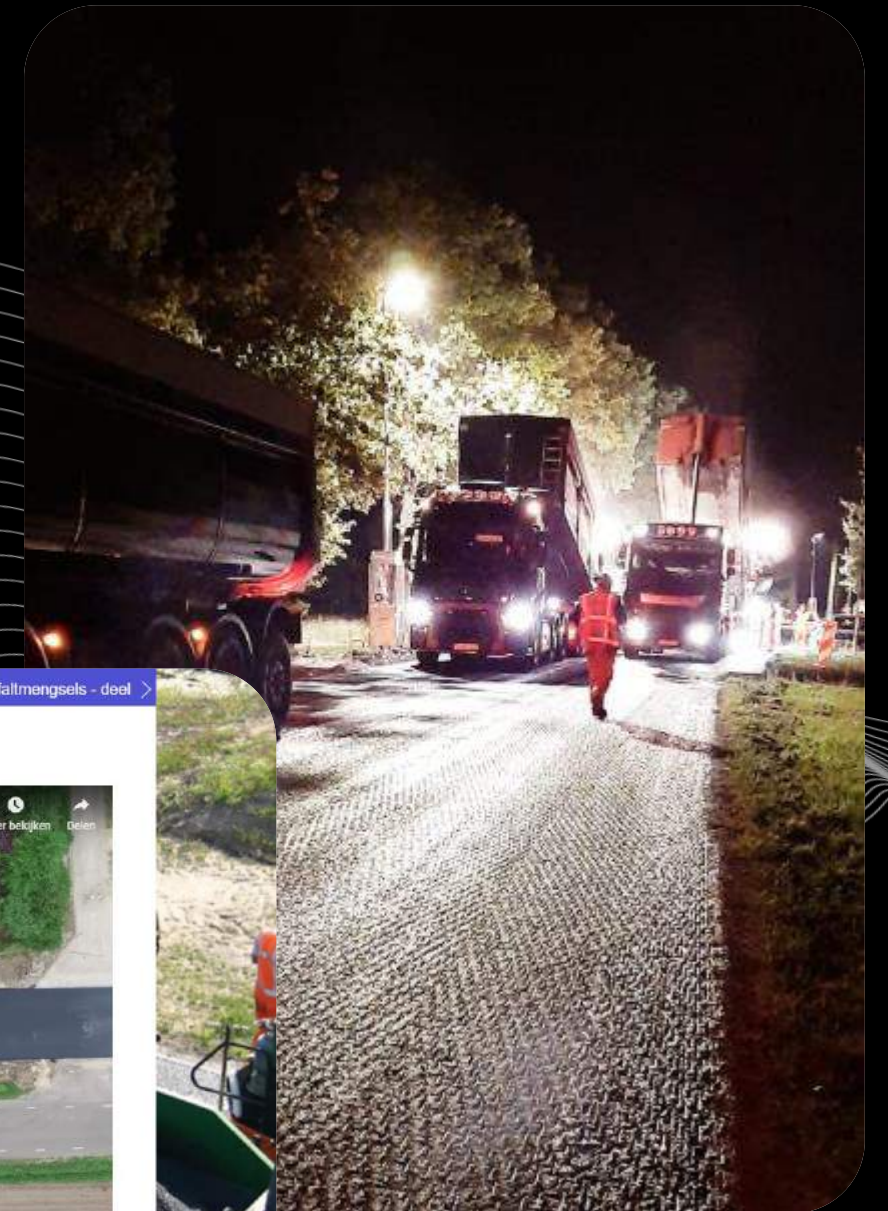
**UNIVERSITY
OF TWENTE.**

DE ACHTERGROND

- Veel ontwikkelingen vanuit ASPARi
- Onderbelicht in het onderwijs
- De slag is al gemaakt in het mbo
- Nu nog in het hbo...



The screenshot shows a presentation slide with a blue header containing navigation tabs: 'Inleiding', 'Achtergrond informatie', 'Opbouw van de weg', and 'Experimenteren met asfaltmengsels - deel >'. The main content area features a video player with a red play button. Above the video, the text reads 'Een blik in de wereld van de wegenbouw (Dronevlieger)'. The video title is 'aanleg N343 dronebeelden youtube v3' and the channel is 'DRONEVLEGER'. Below the video player, the section is titled 'INTRODUCTIE' and contains the following text: 'Zoals in deze video duidelijk wordt gemaakt, zijn er veel mensen en machines nodig bij het aanleggen van een asfaltweg. Dit is niet voor niets: wegen aanleggen is nauwkeurig werk. De kwaliteit van de weg moet uiteraard optimaal zijn. Daarom is het belangrijk dat je leert hoe zo'n asfaltweg is opgebouwd.'



VOORTGANG

EÉN JAAR IN DE WEGENBOUW

- Heel veel literatuur
 - Asfalt
 - Hoe werkt de wegenbouw
 - Literatuurstudie
 - Kennis vanuit ASPARi
- Veel plekken bezocht
- Interviews uitgevoerd
- Stakeholdersmeetings

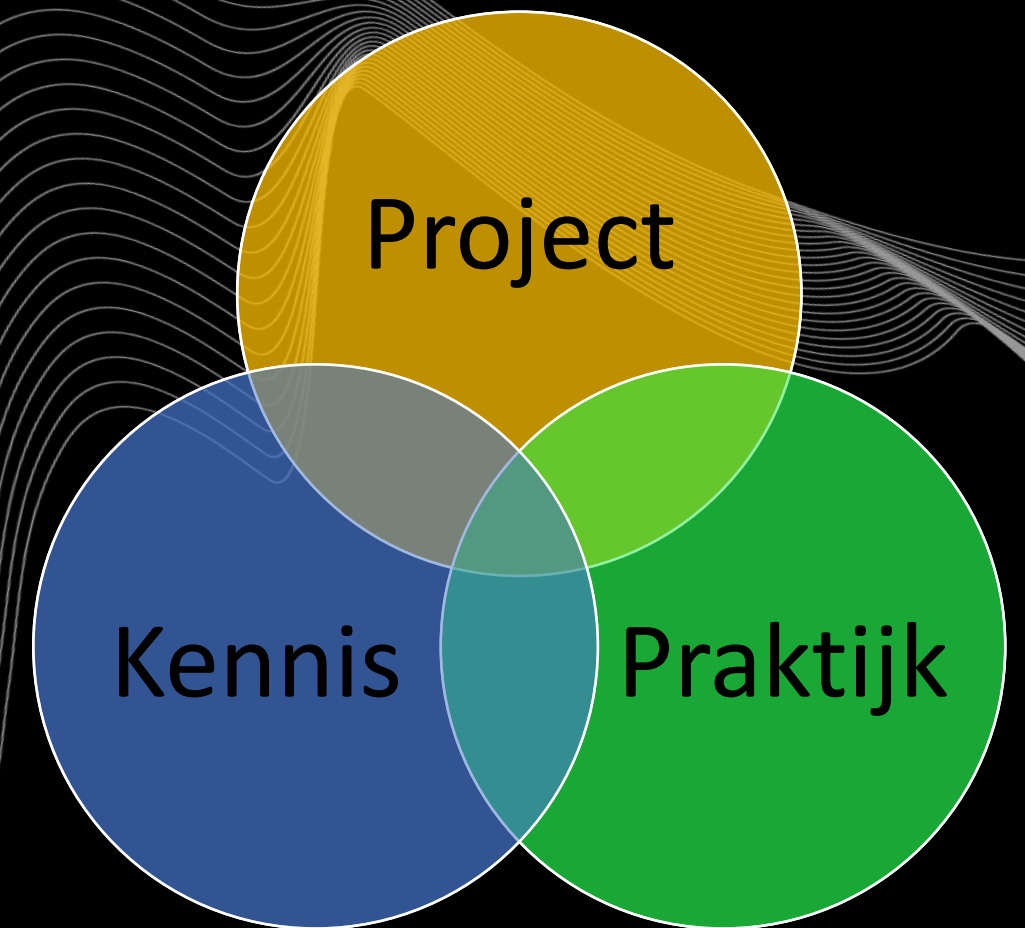


HET DESIGN

- Minor voor het HBO
 - Volledige minor gegeven bij Avans Hogeschool
 - Toevoeging aan een bestaande minor Hogeschool Arnhem en Nijmegen
- In het kader van lifelong learning zijn de lesmaterialen ook beschikbaar voor werknemers

HET DESIGN

- Modulaire minor
 - Aanpasbaar naar de wensen van de docenten/studenten en voorkennis
 - Modules kunnen ingezet worden om onderwijs te verbeteren naast de minor
 - Modulaire vorm staat toe de materialen eenvoudiger te onderhouden
- De minor zal uit twee blokken bestaan



BLOK 1 (KORT)

OVERZICHT

- De asfaltcyclus
- Samenhang tussen de verschillende stappen
- Interpreteren van wensen van opdrachtgevers

BLOK 2 (LANG)

OPLOSSEN

- Variabiliteit in het wegenbouwproces
 - Meerdere casussen
- Toepassen van nieuwe technologieën
- Data interpreteren, evalueren en rapporteren vanuit metingen
- Verbanden kunnen leggen tussen data, werkmethodes en schades
- Rapportage creëren

LEERDOELEN

- De leerling is in staat uit te leggen waarom het wegebouwproces variabel is.
- De leerling is in staat uit te leggen hoe nieuwe technologieën toegepast kunnen worden om deze variabiliteit te meten en terug te dringen.
- De leerling is in staat om data afkomstig vanuit ASPARi metingen te interpreteren en evalueren

WAAR WILLEN WE HEEN?

WAT WORDT ER OPGELEVERD

Technische kennis wordt omgezet naar concrete lesmaterialen.

- Lesmaterialen asfalt op modulebasis
 - Video's, plaatjes, grafieken
 - Simulaties
 - Teksten
- Lesplan voor de minor
- Digitale Leeromgeving voor de minor
- Assessment (Opdrachten, presentatie, verslagen, calculaties, ...)

WAAR WILLEN WE HEEN?

- Alle stakeholders zijn akkoord met modulaire opbouw en onderwerpen
- Modules opbouwen
- Lesplan en minor in elkaar zetten en voorzichtig testen
- Mbo-lesmaterialen worden als ondersteunende materialen gebruikt

WAAR WILLEN WE HEEN?

- Kleine pilottests met hbo-studenten, hbo-docenten en ASPARi.
- September 2020 implementatie op het hbo (definitieve pilottest)
 - Valideren
 - Evalueren

WAAR WILLEN WE HEEN?

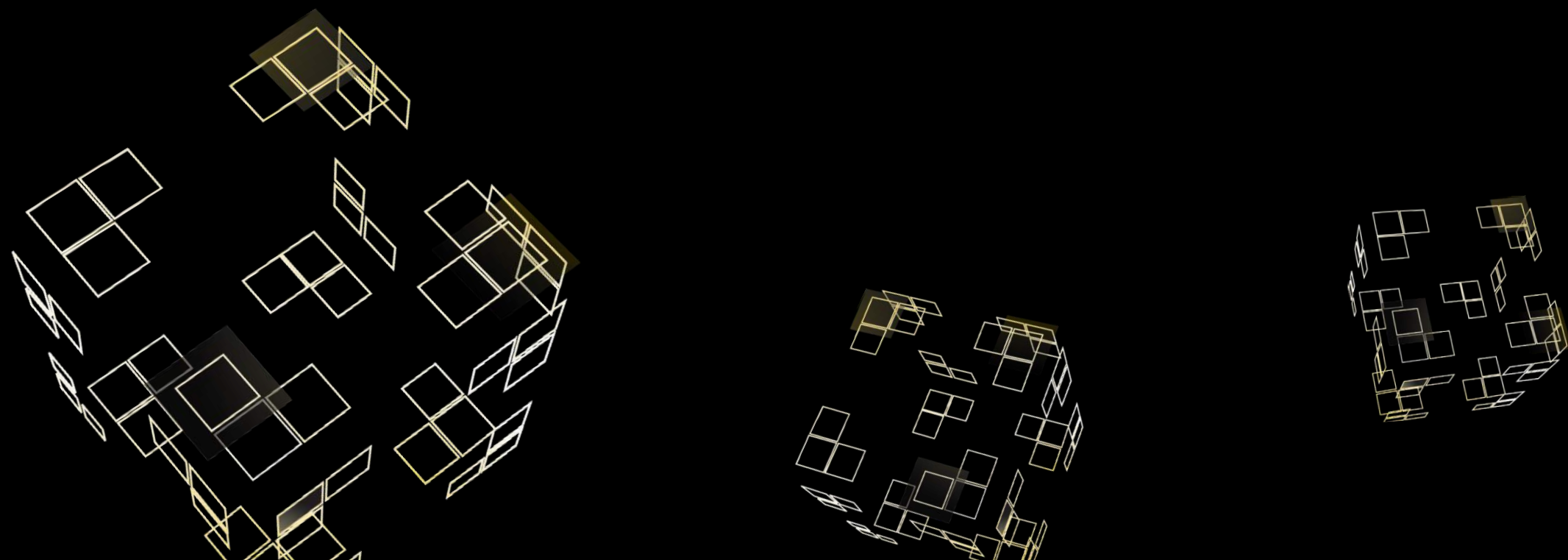
- Als onderwijskundige heb ik niet alle asfaltwijsheid in pacht...
- Aantal bedrijven hebben al toegezegd te ondersteunen

b.t.m.ernst@utwente.nl

06-53906450

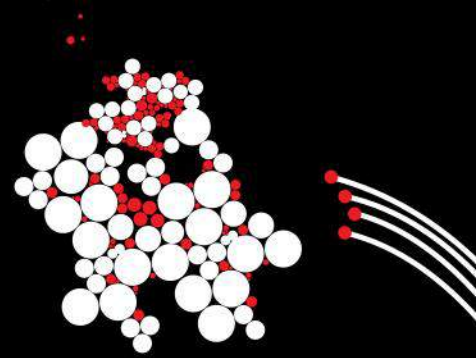


**UNIVERSITY
OF TWENTE.**



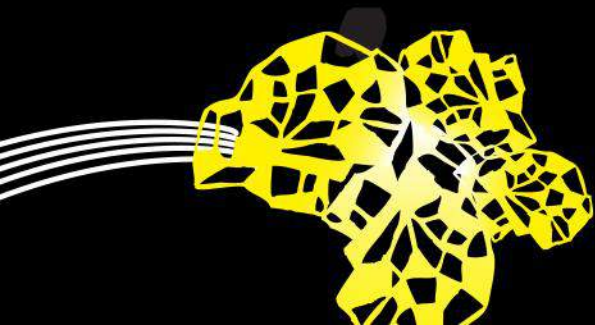
**UNIVERSITY
OF TWENTE.**

UNIVERSITY OF TWENTE.

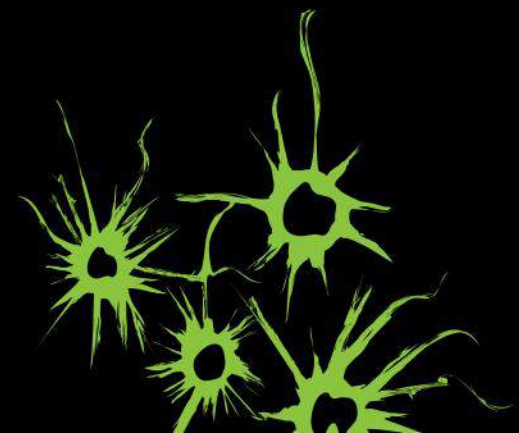


MODERNIZING THE PQI METHOD

DENIS MAKAROV - AFSHIN JAMSHIDI



December 2019

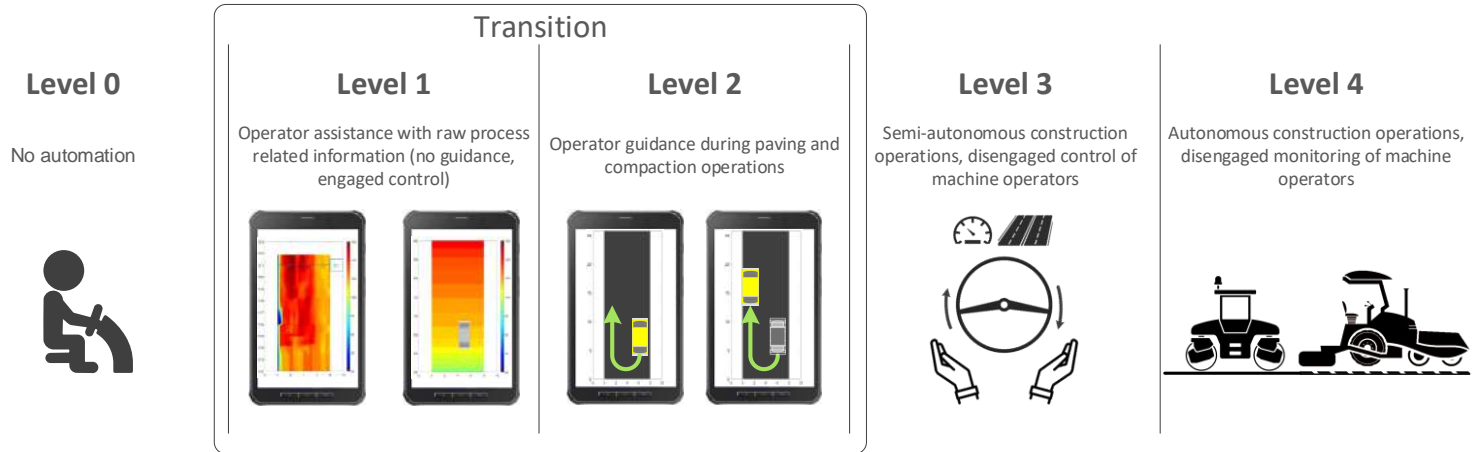


OUTLINE

- Introduction (background)
- Current situation
- Alternatives
- Current results

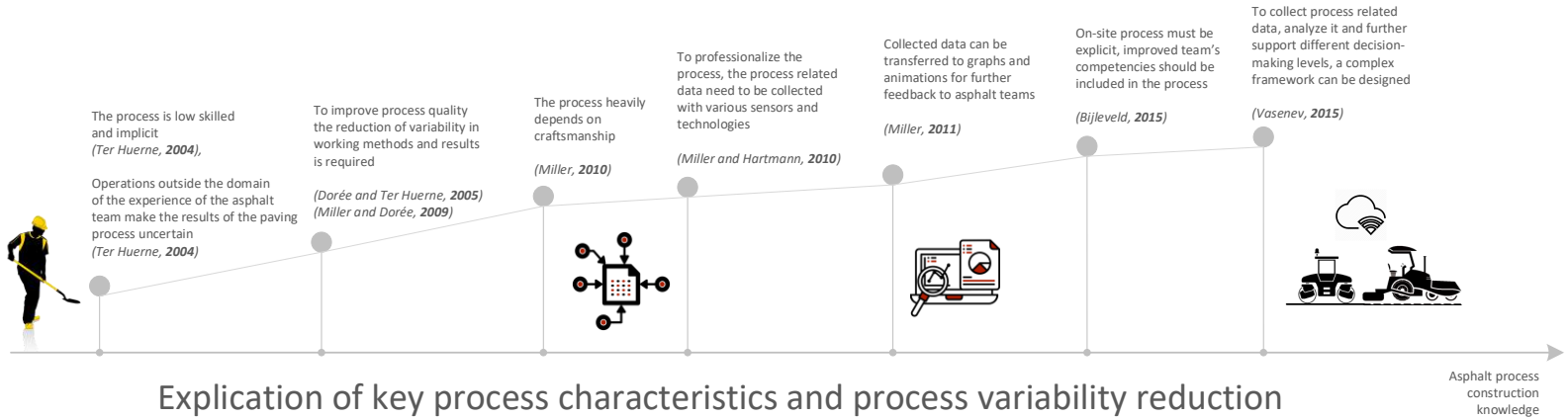


INTRODUCTION



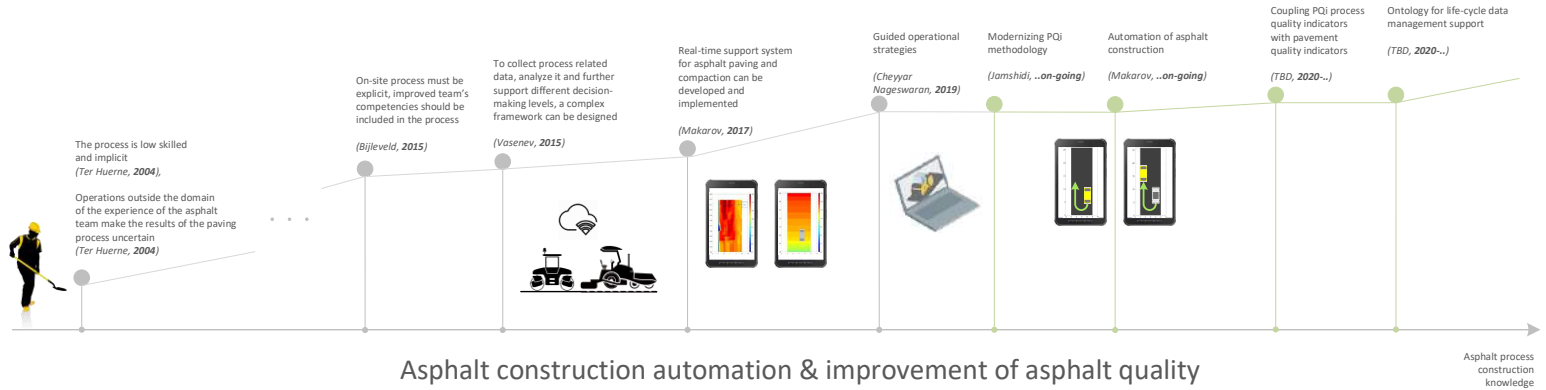
INTRODUCTION

ASPARI HISTORY



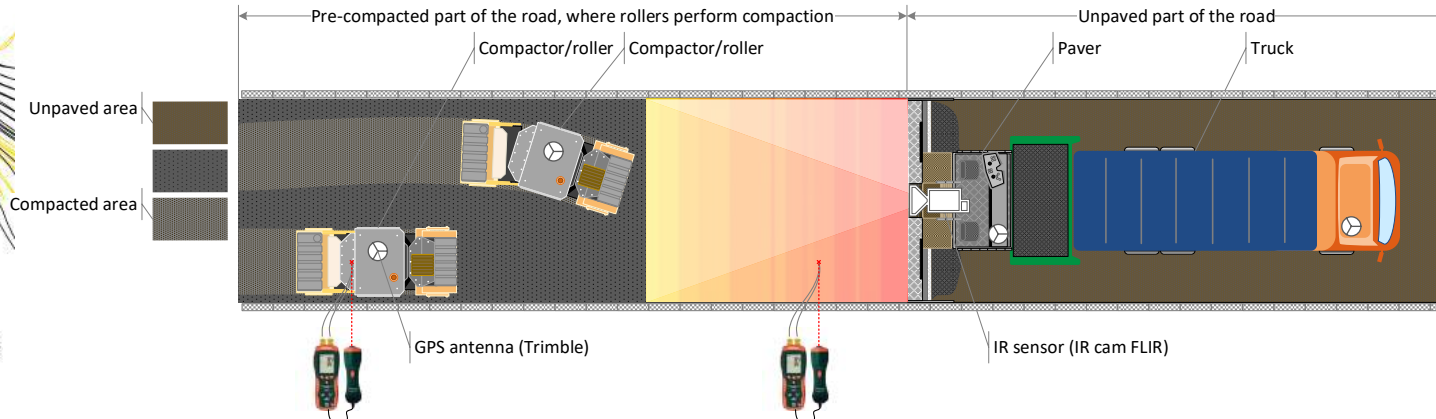
INTRODUCTION

ASPARI VISION



INTRODUCTION

CURRENT PQI SYSTEM



Reference Station #1

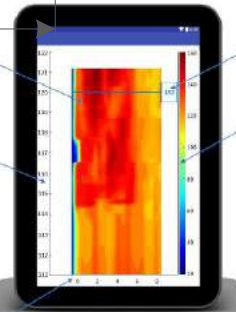
Reference Station #2

~100 meters

Surface temperature of the asphalt mat behind the paver

Length of the paved section (meters)

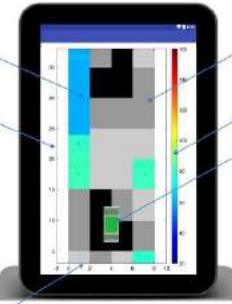
Width of the paved section (meters)



Average temperature across the paved section behind the paver (degrees celsius)

Temperature bar

Width of the paved section (meters)



Temperature of the asphalt mat

Length of the paved section (meters)

Width of the paved section (meters)

Compaction plot

Temperature bar

Roller position on a construction site

CURRENT PROBLEMS

- Offline → no stable assistance to operators in real time
- Interoperability issue → interoperability issue and sensor dependency
- Expensive → low technology penetration
- Cumbersome installation → low technology penetration

POSSIBLE SOLUTION

Modernizing Process Control system in pavement operations by:

- Develop real-time support structure of PQi measurement
- Develop data structure to achieve sensor independence, extensibility and scalability
- Explore and develop alternative solutions (i.e., sensors and methods) to enhance PQi methodology (cheaper, more accurate, more usable and less intrusive)

PROPOSED SYSTEM

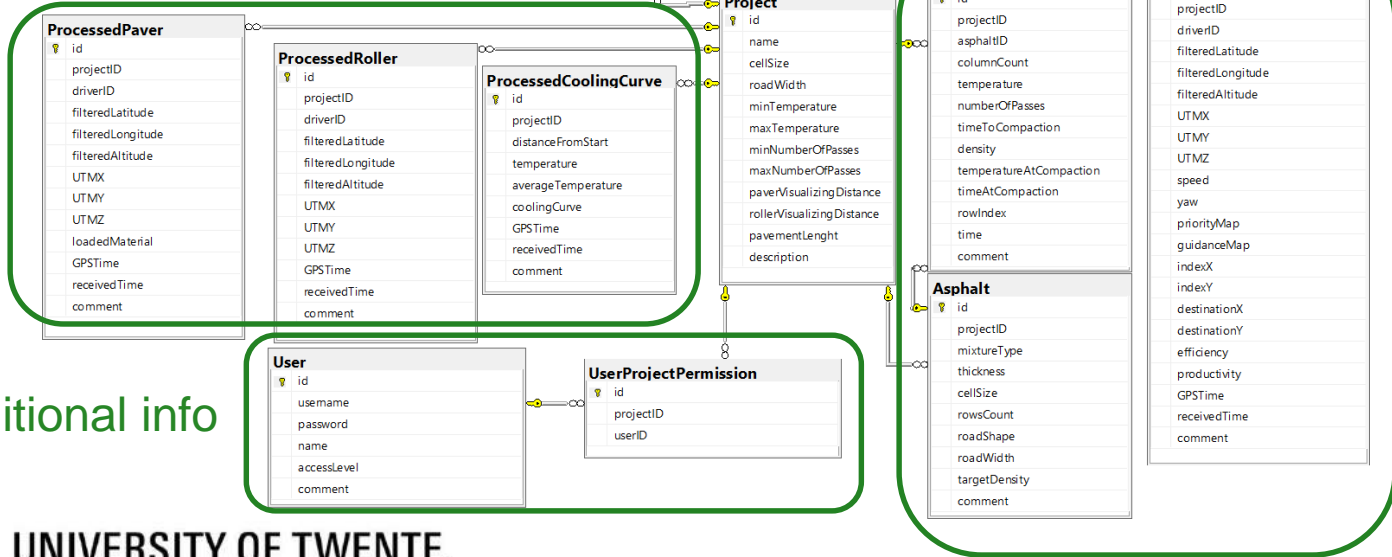
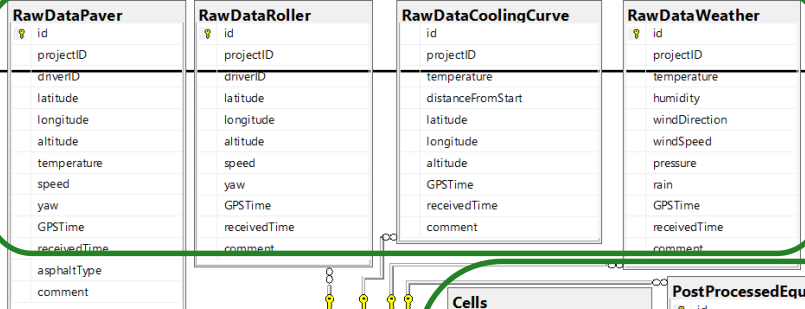
ONTOLOGY/DATABASE

Raw data

Filtered data

Final output

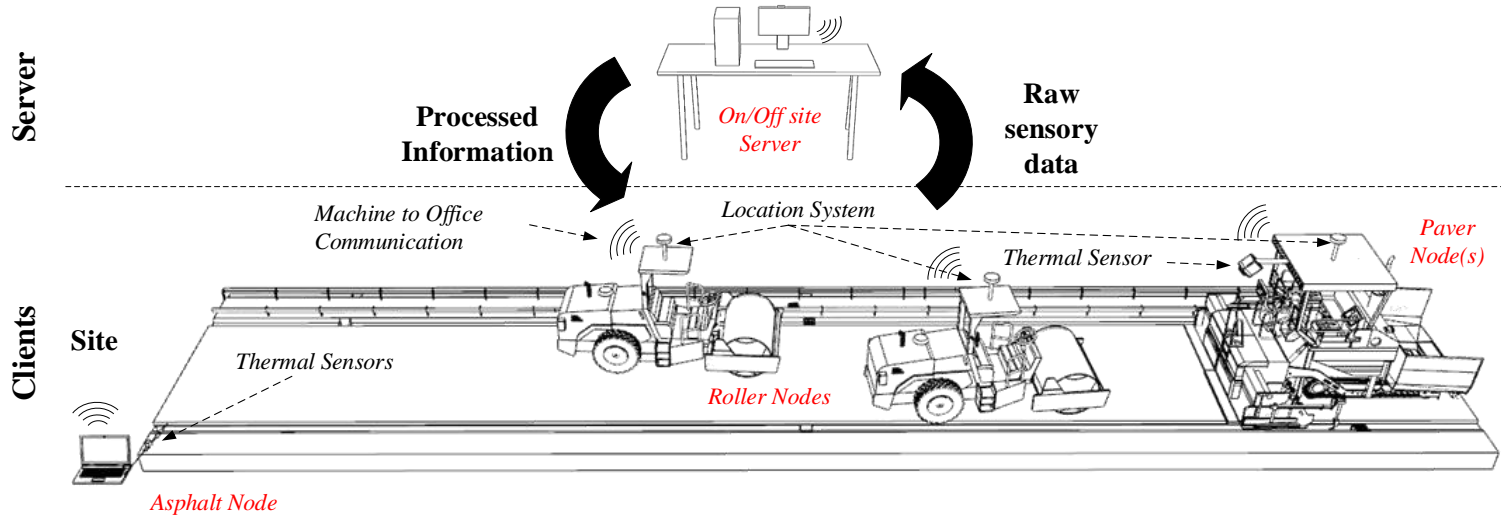
Additional info



PROPOSED SYSTEM

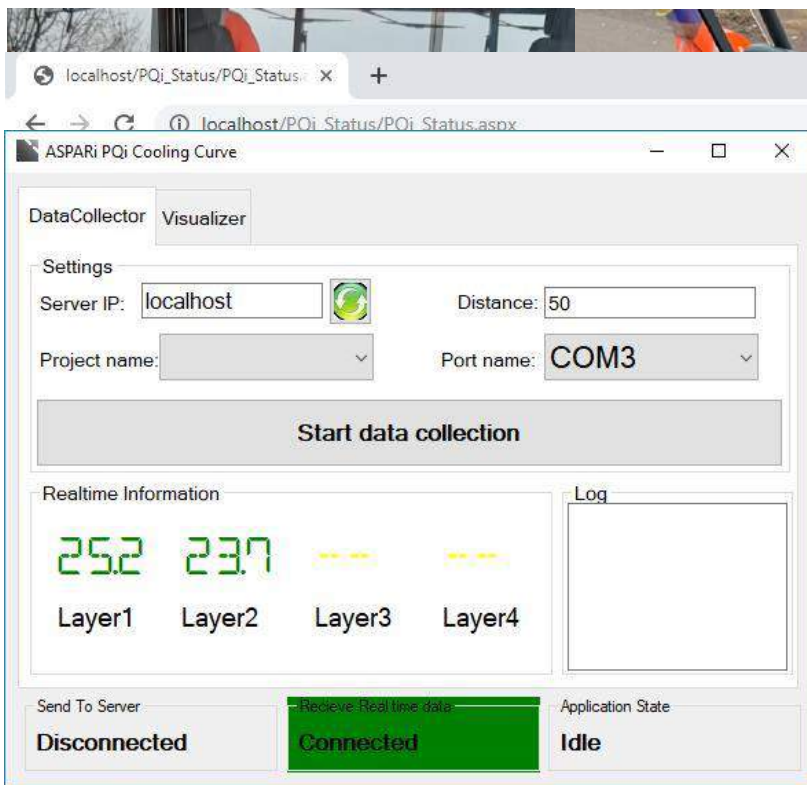
CONCEPTUAL DESIGN

- Soft real time thin client server



PROPOSED SYSTEM

VISUALIZATION RESULTS



localhost/PQI_Status/PQI_Status.aspx

ASPARI PQi Cooling Curve

DataCollector Visualizer

Settings

Server IP: localhost Distance: 50

Project name: Port name: COM3

Start data collection

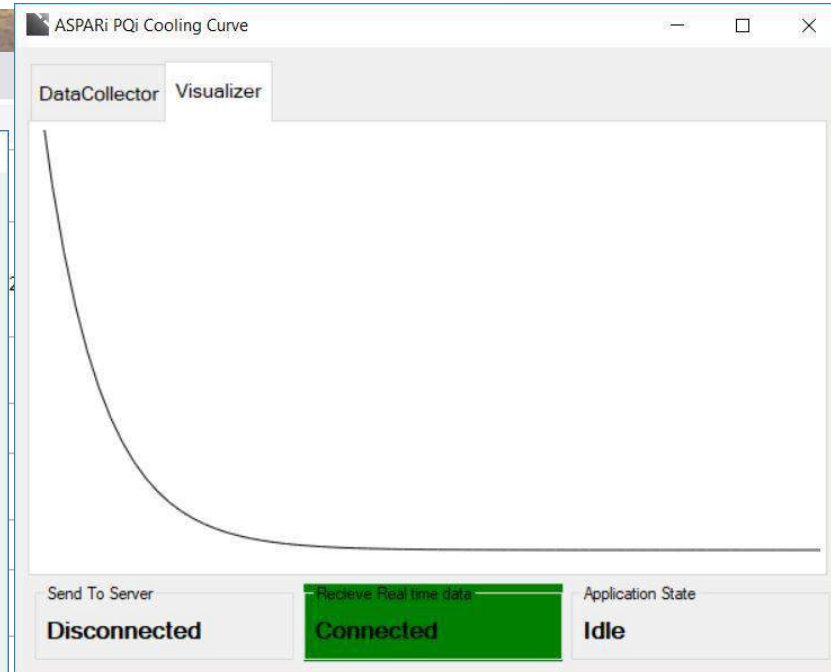
Realtime Information

252 237

Layer1 Layer2 Layer3 Layer4

Log

Send To Server Disconnected Receive Real time data Connected Application State Idle



PROPOSED SYSTEM

LOCATION SENSOR ALTERNATIVES

Sensor/device application	Option	Advantages	Disadvantages	Roughly estimated price (€)
Gathering equipment positioning on site (locations)	Drone with image processing solution	<ul style="list-style-type: none"> ❖ Cheap to scale ❖ Can cover a big area 	<ul style="list-style-type: none"> ❖ Capacity of drone's battery ❖ Necessity in operator ❖ Site's preparation before drone's usage during construction activities 	5.000
	Ublox	<ul style="list-style-type: none"> ❖ Cheap 	<ul style="list-style-type: none"> ❖ Low accuracy 	100
	BLE	<ul style="list-style-type: none"> ❖ Cheap ❖ Possible usage in tunnels and dense areas 	<ul style="list-style-type: none"> ❖ Low accuracy in distances more than 5 meters ❖ Site's preparation before usage during construction activities 	5
	Ultra-wide band	<ul style="list-style-type: none"> ❖ Possible usage in tunnels and dense areas 	<ul style="list-style-type: none"> ❖ Low accuracy ❖ Complex synchronization between sensors 	
	Lidar	<ul style="list-style-type: none"> ❖ High accuracy 	<ul style="list-style-type: none"> ❖ Expansive 	10.000
	DGPS	<ul style="list-style-type: none"> ❖ High accuracy ❖ Ready for application 	<ul style="list-style-type: none"> ❖ Expansive ❖ Low accuracy in dense areas 	5.000
	RTK	<ul style="list-style-type: none"> ❖ High accuracy ❖ Ready for application 	<ul style="list-style-type: none"> ❖ Expansive ❖ Necessity of RTK server ❖ Low accuracy in dense areas 	7.000

PROPOSED SYSTEM

TEMPERATURE SENSOR ALTERNATIVES

Sensor/device application	Option	Advantages	Disadvantages	Roughly estimated price (€)
Obtaining asphalt surface temperatures	Temperature line scanner (paver)	❖ High accuracy	❖ Expansive ❖ Complex installation procedure	50.000
	IR thermal camera (paver)	❖ Cheap	❖ Can only measure initial temperatures due to restricted field of view (by the predefined mounting place on a paver)	7.000
	IR thermal camera (drone)	❖ Cheap ❖ Can measure wider area of asphalt layer with changes of surface layer temperatures in real-time	❖ Capacity of drone's battery ❖ Necessity in operator	2.000
Obtaining asphalt core temperatures	Thermocouple	❖ Cheap	❖ Laborious setup and re-setup during construction activities	50
	Fiber optic	❖ Can capture data after pavement finished	❖ Hard to install ❖ Expansive	10.000
Machine 2 machine communication	WIFI	❖ No extra payments for usage	❖ Small coverage area	200
	GSM	❖ Large coverage	❖ Monthly fees according to the data usage	500

PROPOSED SYSTEM

DRONE RESULTS

- Demo



DISCUSSION





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Paving the way forward

UNIVERSITY OF TWENTE.

PROMOTEN CIVIELE TECHNIEK IN HET MBO

JANINE PROFIJT – ONDERWIJSKUNDIGE

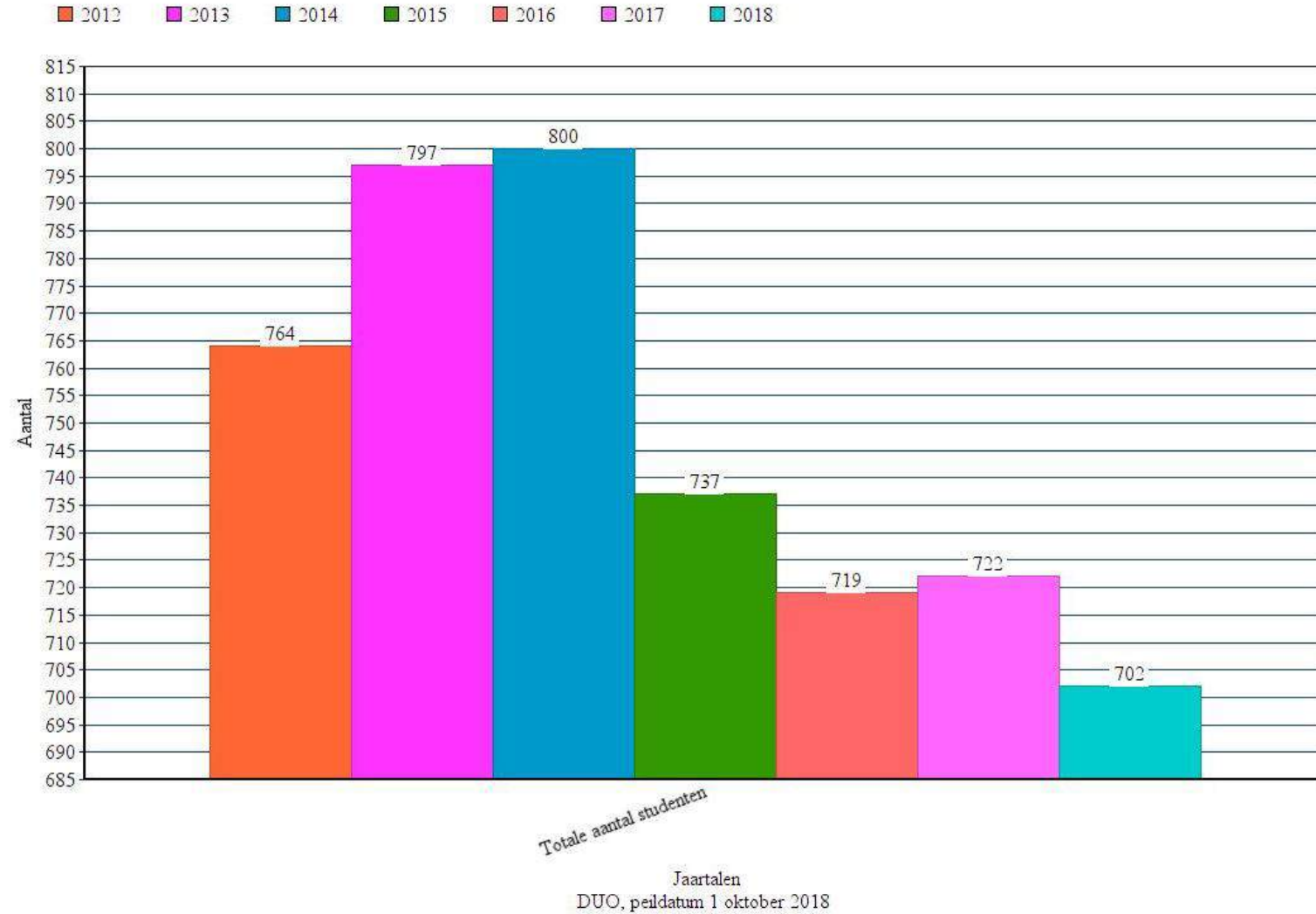
INLEIDING

- Aanleiding
- Hoofd- en deelvragen
- Aspecten die een rol spelen
- Initiatieven promotie
- Acties die bijdragen
- Conclusie
- Keuzedeel

AANLEIDING

- Nieuw onderwijs ontwikkeld
- Studenten aantallen versus Werkgelegenheid
- Verantwoordelijkheid

Studenten aantallen per opleidingsinstituut Opleiding MKF infra BOLA



HOOFD- EN DEELVRAGEN

Hoe zorgen de infrasector en het onderwijs ervoor dat de mbo opleidingen op het gebied van civiele techniek een hogere aanmeldingspercentage krijgen?

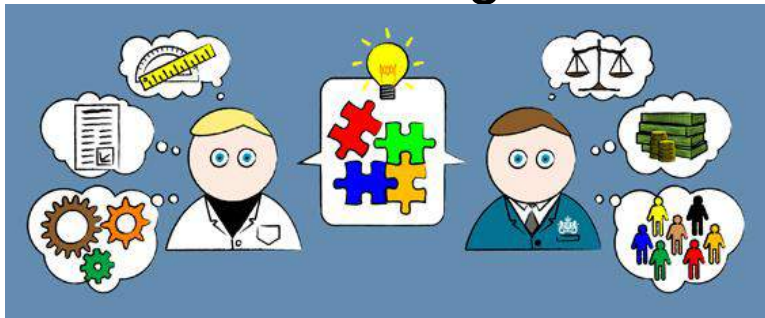
1. Welke aspecten spelen een rol bij het kiezen van een studie voor jongeren tussen de 14-16 jaar?
2. Welke initiatieven op het gebied van promotie van het vak en de opleidingen zijn er geweest of spelen nu?
3. Welke acties kunnen in de toekomst bijdragen aan het verhogen van het aantal studenten die kiezen voor de opleidingen in civiele techniek

ASPECTEN DIE EEN ROL SPELEN

1. Economische modellen



2. Statusverwerkingsmodellen



3. Combinatiemodellen

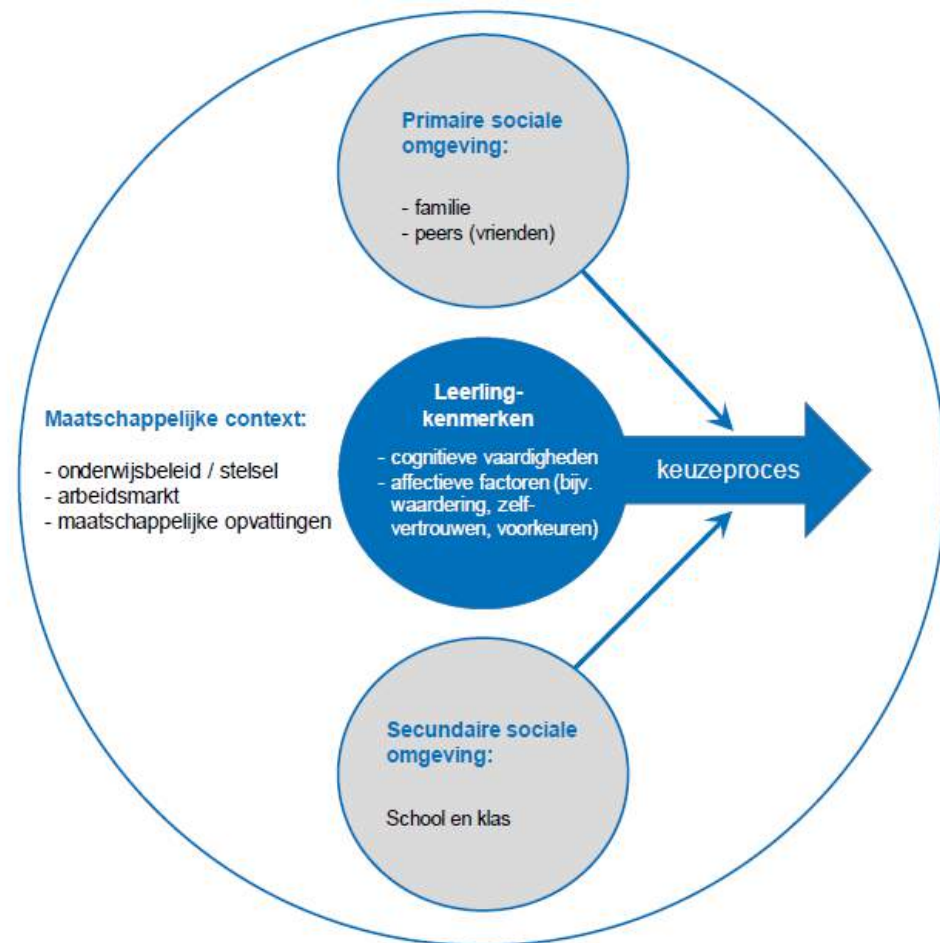
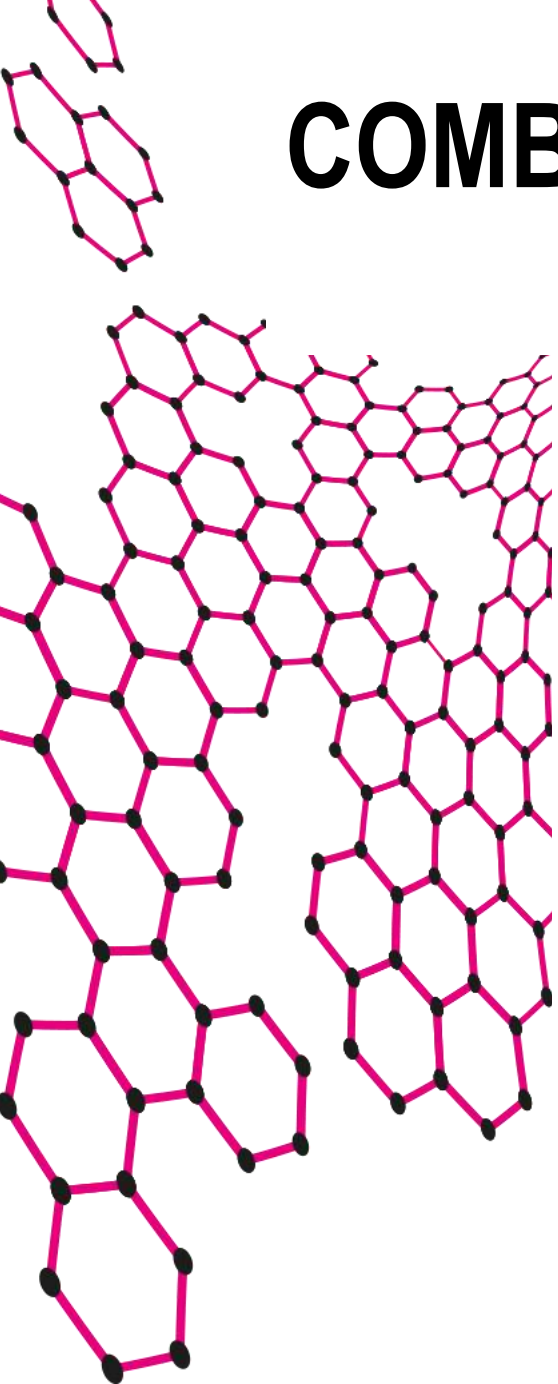
ASPECTEN DIE EEN ROL SPELEN



Combinatie model 1

- Individuele kenmerken
- Contextuele kenmerken
- Kenmerken van de school
- Karakter eigenschappen school

COMBINATIEMODEL 2



ASPECTEN DIE EEN ROL SPELEN

- Interesse in vakgebied
- Carrièreperspectief
- Beïnvloeding door anderen
- School
- Locatie (Van der Ploeg, 2016)
- Open dagen + studie informatie

INITIATIEVEN

- Instellingen en instanties
 - Bv Jegaathetmaken
- Techniekpact
- Opleidingsbedrijven
- Mbo scholen
- RIF
- Aannemers
- Samenwerkingsverbanden
- Samenwerken tussen docenten
- [Promotiefilm](#)
- Conclusie: vaak geen samenwerking tussen scholen, bedrijven en overheid



WELKE ACTIES KUNNEN BIJDRAGEN?

- Teksten standaardiseren op websites
- Decanen informeren
- Open dagen
- Meer samenwerking tussen bedrijven, scholen en de overheid
- Onderwijsontwikkeling

CONCLUSIES

Hoe zorgen de infrasector en het onderwijs ervoor dat de mbo opleidingen op het gebied van civiele techniek een hogere aanmeldingspercentage krijgen?

- Samenwerking bedrijven, scholen en overheid
- Initiatieven delen
- Decanen informeren
- Open dagen
- Informatie op websites

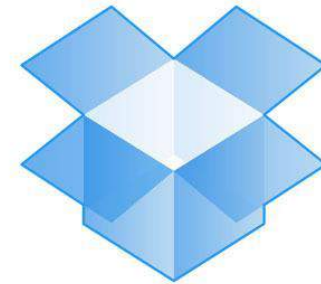


KEUZEDEEL INNOVATIES IN DE ASFALTWEGENBOUW

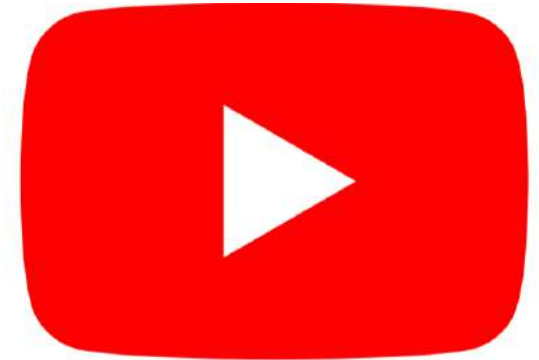
- Producten gereed
 - basis
 - keuzedeel



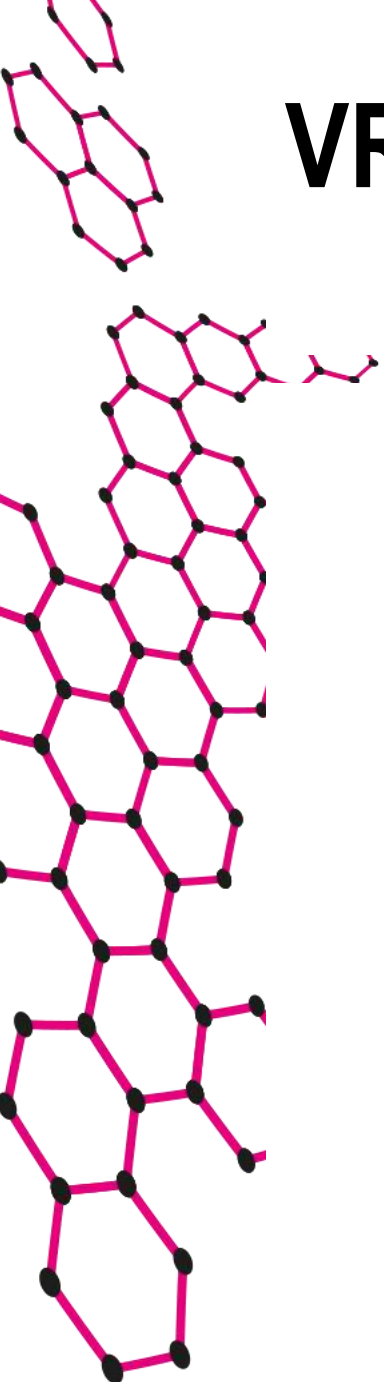
- Examen voor niveau 2/3 en niveau 4
- Toekomstgericht
- Afronden januari-februari



Dropbox



VRAGEN/OPMERKINGEN



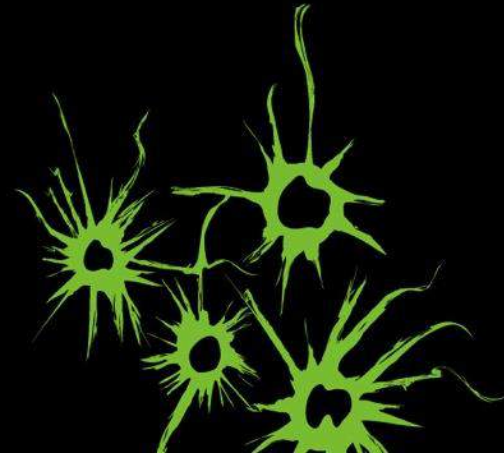
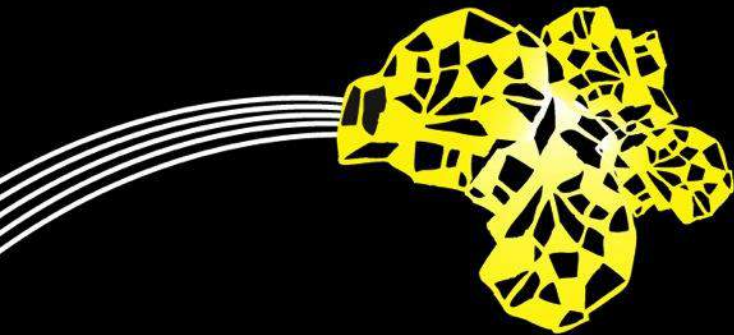
UNIVERSITEIT TWENTE.

OUTREACH ACTIVITEITEN IN 2019



ASPARi

Paving the way forward





Opdrachtgeversdag 2019 & High Tech, Low Cost project



CAPSA 2019 in Zuid Afrika



ISARC 2019, Banff, Canada

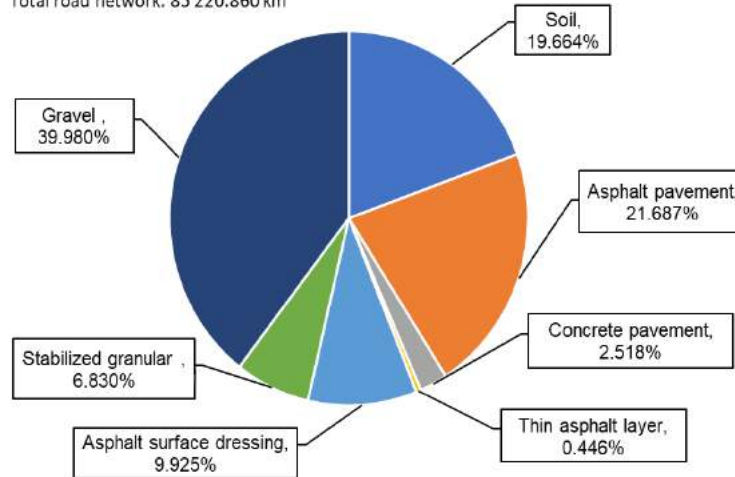
Aachener Straßenbau- und Verkehrstage 2019

Donnerstag 21/11/2019			Verleihung des S
		Moderation:	Dipl. Fon
Eröffnung der Fachausstellung			15:25 Uhr
11:00 Uhr	Eröffnung der begleitenden Fachausstellung		Jon RW
Begrüßung			15:30 Uhr
12:00 Uhr	Dipl.-Ing. Winfried Krux Forschungsvereinigung SETAC e. V.		Ale RW
	Univ.-Prof. Dr.-Ing. habil. Markus Oeser Institut für Straßenwesen, RWTH Aachen University		15:40 Uhr
Zukunftsweisende Bauprozesse			Bauen unter Betr
Moderation:		LRDir Dr.-Ing. Lutz Pinkofsky Bundesanstalt für Straßenwesen (BASt) Bergisch Gladbach	Moderation:
12:15 Uhr	Wie ist die Effizienz? Kommunikation und Data Science für die Baustelle von Morgen Johannes Lipp, M.Sc. Lehrstuhl für Informationsmanagement im Maschinenbau RWTH Aachen University		16:10 Uhr
12:40 Uhr	Prozesssicherheit im Asphaltbau (und CO²- Reduzierung) durch innovative Technik Dipl.-Ing. Martin Fliegl Fliegl Bau- und Kommunaltechnik GmbH Mühdorf an der Inn		16:35 Uhr
13:05 Uhr	Asphalt Process Control - Digitalization and Lessons learnt in the Netherlands Dr. ir. Seirgel Miller University of Twente Enschede (Niederlande)		17:00 Uhr
13:30 Uhr	Diskussion		n.B Bet Dipl nes Aac
13:45 Uhr	Kaffeepause		17:25 Uhr
Neue Bauweisen - von der Innovation in die Praxis			Podiumsdiskussi
Moderation:		Univ.-Prof. Dr.-Ing. habil. Markus Oeser Institut für Straßenwesen RWTH Aachen University	Moderation:
14:20 Uhr	Praktische Umsetzung von PU-Asphalt Dipl.-Ing. Lukas Renken ISAC GmbH Aachen		Dr. . HO Ess
14:45 Uhr	Asphalteinlagen für die Straßensanierung - Regelwerk sowie Möglichkeiten und Grenzen bei Planung und Verwendung Dipl.-Ing. Lars Kodritsch		17:40 Uhr
			Bau mit
			Disi
			AD Gec Pet Jan Jan
			19:30 Uhr
			AB

ASPARi in Chili



Total road network: 85 220.860 km



Chilean Highway Agency, 2017

Importance of improvement the quality of low-volume roads



Experimentation with Drone



Continuous improvement

Trucks logistics

Establishing optimal compaction strategies

Different weather conditions and geometries
(hills & curves)

Active work with the asphalt crew

As a result currently we have:

Enthusiasm of the authority

New phase → incorporating asphalt surface dressings

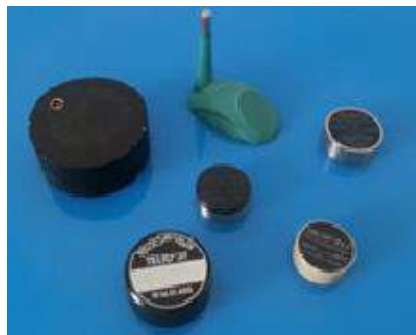




RWS WORKSHOP



ERVARINGEN MET SENSOREN IN ASFALT ... EEN PRAKTISCHE BENADERING



In de toekomst

....

